

MAT 569 Differential Geometry II : Exercise Sheet Four

1. A manifold M^n is *Einstein* if $\text{Ric} = \lambda g$ for some function $\lambda : M \rightarrow \mathbb{R}$. Prove that if $n \geq 3$ and M is connected then λ must be a constant. Prove that if $n = 3$ then M^3 has constant sectional curvature.

2. Put the metric

$$g_{ij} = \frac{\delta_{ij}}{F^2}$$

on a neighbourhood in \mathbb{R}^n , $n \geq 3$, where F is a non-zero function on \mathbb{R}^n .

(i) Prove that the metric has constant curvature K iff

$$F = G_1(x_1) + \dots + G_n(x_n)$$

where each term is a quadratic

$$G_i(x_i) = ax_i^2 + b_i x_i + c_i$$

and

$$\sum_{i=1}^n (4ac_i - b_i^2) = K.$$

(ii) Putting $a = K/4$, $b_i = 0$, and $c_i = 1/n$ we obtain the metric

$$g_{ij} = \frac{\delta_{ij}}{\left(1 + \frac{K}{4} \sum x_i^2\right)^2}.$$

Show that for $K > 0$ this gives a metric on all of \mathbb{R}^n which is *not* complete.

3. Let p and q be relatively prime integers, $q > 2$. Consider the sphere

$$S^3 = \{(z_1, z_2) \in \mathbb{C}^2 : |z_1|^2 + |z_2|^2 = 1\} \subset \mathbb{C}^2 = \mathbb{R}^4$$

and define $h : S^3 \rightarrow S^3$ by

$$h(z_1, z_2) = \left(e^{\frac{2\pi i}{q}} z_1, e^{\frac{2\pi i p}{q}} z_2\right).$$

(i) Show that h generates a group (isomorphic to \mathbb{Z}_q) of isometries of S^3 which acts in a totally discontinuous manner. The quotient S^3/\mathbb{Z}_q is called a *Lens space*.

(ii) Show that every geodesic of S^3/\mathbb{Z}_q is closed, but they can be of different lengths. What is the diameter of S^3/\mathbb{Z}_q ?

4. Let

$$S^{2n+1} = \{(z_0, \dots, z_n) \in \mathbb{C}^{n+1} : |z_0|^2 + \dots + |z_n|^2 = 1\} \subset \mathbb{C}^{n+1} - \{0\} = \mathbb{R}^{2n+2} - \{0\}.$$

(i) Show that the equivalence relation $(z_0, \dots, z_n) \sim (\lambda z_0, \dots, \lambda z_n)$, $\lambda \in \mathbb{C}^*$ on $\mathbb{C}^{n+1} - \{0\}$ induces the equivalence relation $(z_0, \dots, z_n) \sim (e^{i\theta} z_0, \dots, e^{i\theta} z_n)$ on S^{2n+1} . Thus we obtain a smooth fibration

$$f : S^{2n+1} \rightarrow \mathbb{C}\mathbb{P}^n$$

with S^1 fibres, known as the *Hopf fibration*.

(ii) Show that if $\mathbb{C}\mathbb{P}^n$ has the Fubini-Study metric than f is a *Riemannian submersion*, i.e. f is a submersion in the differential topological sense (its differential df has maximal rank at all points), and df preserves the lengths of vector orthogonal to the fibres.

5. Let X and Y be orthonormal tangent vectors to $\mathbb{C}\mathbb{P}^n$. Using the Riemannian submersion from the previous question, lift them *horizontally* to \bar{X} and \bar{Y} , tangent vectors to S^{2n+1} (the metric on S^{2n+1} splits each tangent space into a vertical part, tangent to the fibre, and a horizontal part). Multiplication by i preserves the horizontal part of the tangent bundle to the sphere, thought of as a subbundle of $T\mathbb{C}^{n+1}|_{S^{2n+1}}$. So let ϕ be the angle between \bar{X} and $i\bar{Y}$, i.e.

$$\cos\phi = g_{S^{2n+1}}(\bar{X}, i\bar{Y}).$$

Show that the sectional curvature of $\mathbb{C}\mathbb{P}^n$ for the plane σ generated by X and Y is

$$K(\sigma) = 1 + 3\cos^2\phi.$$

In particular, projective space is quarter-pinched $1 \leq K \leq 4$.

6. Let M be a complete simply connected Riemannian manifold with non-positive sectional curvature. Let $\gamma : \mathbb{R} \rightarrow M$ be a geodesic parametrized by arc length, and let $p \in M \setminus \gamma(\mathbb{R})$. Define $d(s) := d(p, \gamma(s))$ and let $\sigma_s : [0, d(s)] \rightarrow M$ be the minimizing geodesic from p to $\gamma(s)$.
- (i) For the variation $h(s, t) = \sigma_s(t)$ show that

$$\frac{1}{2}E'(s) = \langle \gamma'(s), \sigma'_s(d(s)) \rangle$$

and

$$\frac{1}{2}E''(s) > 0.$$

Hence d must have a unique critical point s_0 which is a minimum. Moreover

$$\langle \gamma'(s_0), \sigma'_s(d(s_0)) \rangle = 0$$

which means that the shortest curve joining p to γ is perpendicular to γ .

(ii) Show by examples that simple connectivity and non-positive curvature are necessary hypotheses.

7. Let M be a complete Riemannian manifold with $K \leq K_0$, where K_0 is a positive constant. Suppose that p and q can be joined by two distinct geodesics γ_0 and γ_1 , with γ_0 shorter than γ_1 . Assume we have a homotopy (continuous family of curves) γ_t , $t \in [0, 1]$, between these two geodesics. Prove that some curve γ_{t_0} must be “long”, i.e.

$$\ell(\gamma_0) + \ell(\gamma_{t_0}) \geq \frac{2\pi}{K_0}.$$

[This is known as Klingenberg’s Lemma. See page 236 of do Carmo’s book for a hint.]

8. Use Klingenberg's Lemma to prove Hadamard's Theorem. [Hint: You need to show that any two points are joined by a *unique* geodesic, for then the exponential map must be injective.]
9. A weaker version of Bonnet-Myers' Theorem assumes that M is complete and has *sectional* curvature (instead of Ricci curvature) bounded below, $K \geq 1/r^2 > 0$, to conclude that M is compact and $\text{diam} \leq \pi r$ as before. Prove this result using the Rauch Comparison Theorem and the Jacobi Theorem (the latter is the corollary that immediately followed the Morse Index Theorem).
10. (i) Suppose M has $\text{Ric} \geq k$ and for some point $p \in M$

$$\text{vol}B(p, r) = v(n, k, r)$$

where $v(n, k, r)$ is the volume of a ball of radius r in an n -dimensional space of constant curvature k . Show that M has constant curvature k on $B(p, r)$.

(ii) Show that a complete manifold M with $\text{Ric} \geq 0$ and

$$\lim_{r \rightarrow \infty} \frac{\text{vol}B(p, r)}{v(n, 0, r)} = 1$$

for some $p \in M$, must be isometric to Euclidean space.

11. Prove the converse of Toponogov's Theorem. In other words, if for some k the conclusion of Toponogov's Theorem holds when hinges in M are compared to hinges in a two-dimensional space of constant curvature k , then M has sectional curvature $K \geq k$.
12. Show that for arbitrary vector fields X and Y , the Lie derivative satisfies

$$L_X \circ L_Y - L_Y \circ L_X = L_{[X, Y]}.$$

13. Suppose we have a (local) frame of Killing fields X_1, \dots, X_n on a Riemannian manifold M . Show that the structure constants c_{ij}^k defined by

$$[X_i, X_j] = c_{ij}^k X_k$$

are constant. [Thus a Killing frame is a finite-dimensional Lie algebra.]

14. Let X be a Killing field on a closed manifold M . Assume that α is a harmonic form.
- (i) Show that $L_X \alpha = 0$. [Hint: Show it is harmonic.]
- (ii) Show that $i_X \alpha$ is closed, but not necessarily harmonic.

15. Let M^{2n} be a Kähler manifold with Kähler form ω . Show that $\omega^k = \omega \wedge \dots \wedge \omega$ is closed but not exact, for $k = 1, \dots, n$. Thus none of the even cohomology groups can vanish. [Hint: Show that ω^n is proportional to the volume form.]

16. Show that a compact manifold with irreducible holonomy and $\text{Ric} \geq 0$ must have finite fundamental group.

Presentation Topics

1. Describe the flat compact manifolds in dimension three. These are space forms, so must be quotients of \mathbb{R}^3 . [See pages 231- in “Three-Dimensional Geometry and Topology”, William Thurston. He calls these Euclidean manifolds.]
2. Two other interesting space forms are the Poincaré dodecahedral space and the Seifert-Weber dodecahedral space, in positive and negative curvature respectively. Describe these spaces. [See pages 34 and 36 of Thurston’s book. The picture on the cover, and on the Perelman posters, is the tiling of \mathbb{H}^3 coming from the Seifert-Weber space.]
3. Describe focal points and focal sets of submanifolds. [Page 230 of do Carmo’s book.]
4. Describe the basic idea behind Hamilton’s proof that any compact simply connected three-manifold with positive Ricci curvature is homeomorphic to S^3 . There’s lots of analysis, but you can ignore that. [R. Hamilton, “Three-manifolds with positive Ricci curvature”, Jour. Diff. Geom, **17** (1982), 255-306.]
5. Describe some of the Cheeger-Gromov compactness results. Here compactness refers to the ‘space’ of all Riemannian manifolds, which can be topologized in various ways. [See chapter 10 of “Riemannian Geometry”, Peter Petersen.]
6. Describe spinor bundles and the Dirac operator. It would suffice to work in dimension four. If possible, describe Weitzenböck’s formula. [See chapter 7 and appendix C of Petersen’s book.]
7. Describe the generalized Gauss-Bonnet Theorem in dimension greater than two. [See chapter 4 of Petersen’s book.]
8. Describe characteristic numbers (Chern or Pontrjagin numbers) and their relation to curvature. [See exercise 23 on page 205 of Petersen’s book.]
9. Prove that $\mathbb{C}P^2$ is not even locally a hypersurface in \mathbb{R}^5 . [See section 4.2 of Petersen’s book. You will need to understand the curvature *operator* and why it is *not* strictly positive for $\mathbb{C}P^2$.]
10. Generalize Preissmann’s Theorem to show that any *solvable* subgroup must be cyclic.
11. Find out what Yau’s Theorem (the Calabi Conjecture) states and what it has to do with the existence of Ricci-flat metric on, for example, hyperkähler or Calabi-Yau manifolds (holonomy group $Sp(m)$ or $SU(m)$ respectively). [For example, see page 98 of “Compact manifolds with special holonomy”, Dominic Joyce.]
12. Describe the proof of Hodge’s Theorem. You needn’t cover all the analysis. [See “Principles of algebraic geometry”, Griffiths and Harris.]