Twistors,

Self-Duality,

and

Spin<sup>c</sup> Structures

Claude LeBrun Stony Brook University

RP90: Twistors from Geometry to Physics. University of Oxford, July 23, 2021.

Revised version.

For my friend and teacher





In celebration of his 90th birthday



In celebration of his 90th birthday and his 2020 Nobel Prize in Physics.

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 $\{\text{infinitesimal rotations}\} = \{\text{skew matrices}\} = \{2\text{-forms}\}.$ 

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 $\Lambda^+$  self-dual 2-forms  $\Lambda^-$  anti-self-dual 2-forms

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which is almost-complex structure compatible with metric and determining given orientation.

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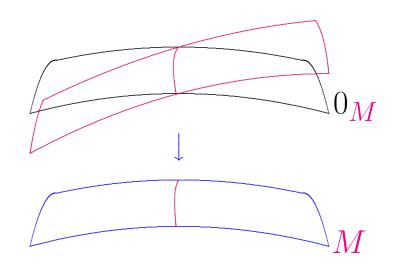
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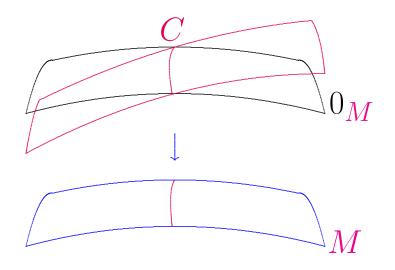
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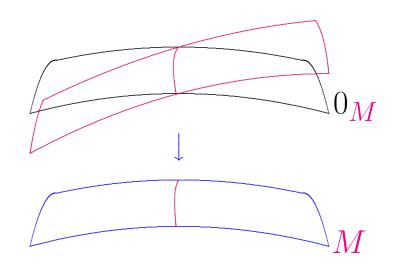
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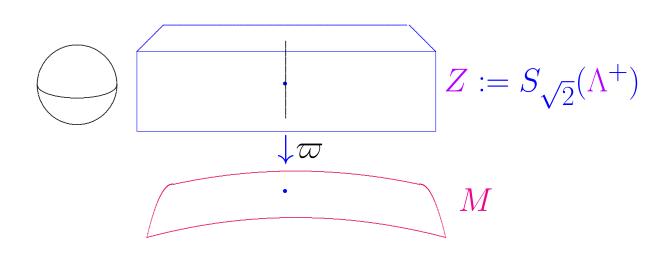
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(in sense of Atiyah-Hitchin-Singer)

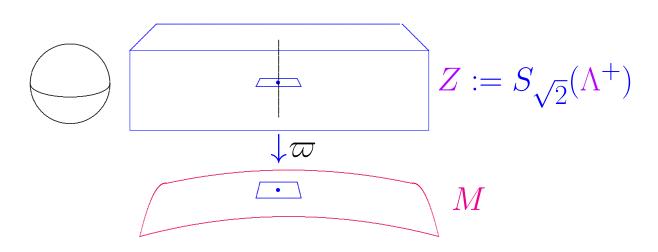
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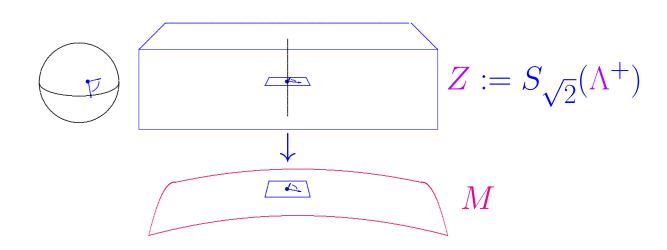
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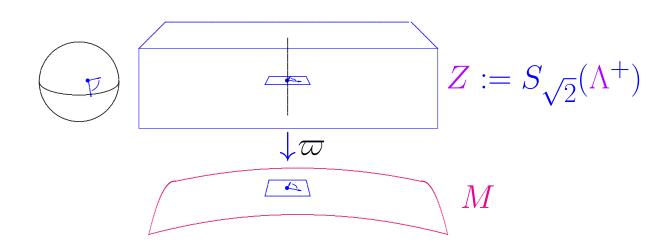


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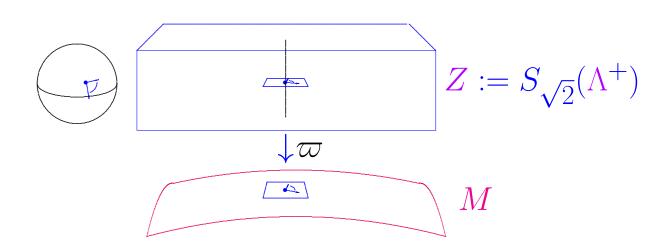
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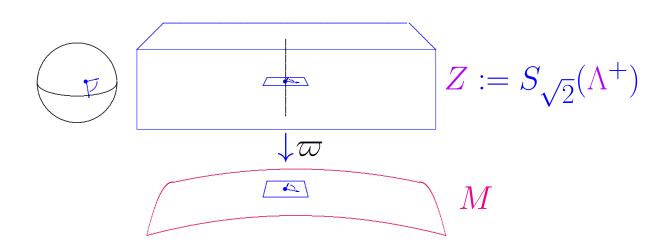
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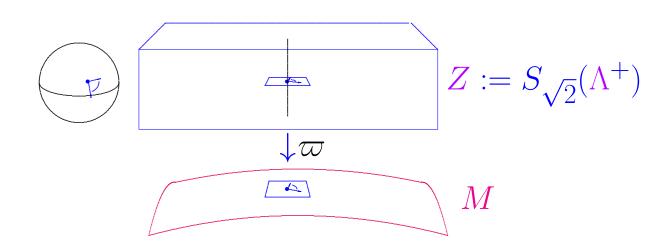


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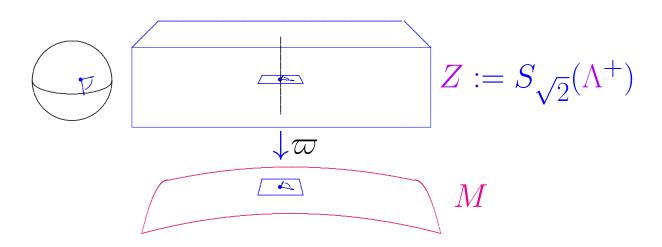
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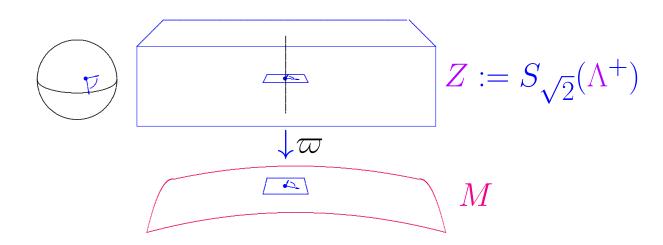
#### Yes!

 $\iff \exists \text{ spin}^c \text{ structures!}$ 

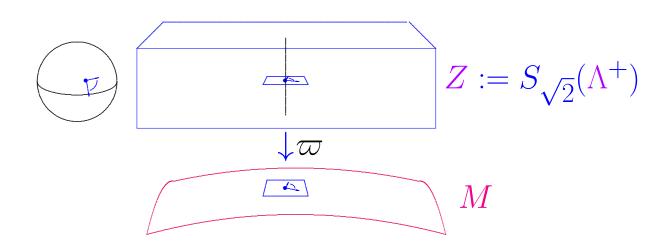
#### Geometric Definition.



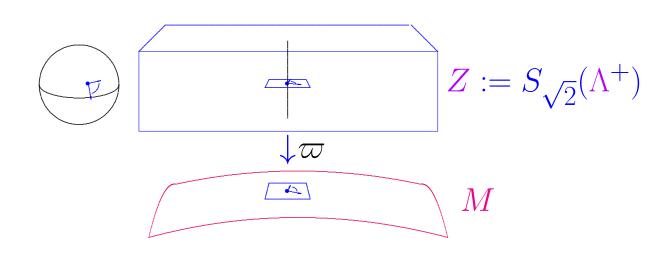
# Geometric Definition. $A \operatorname{spin}^c \operatorname{structure}$



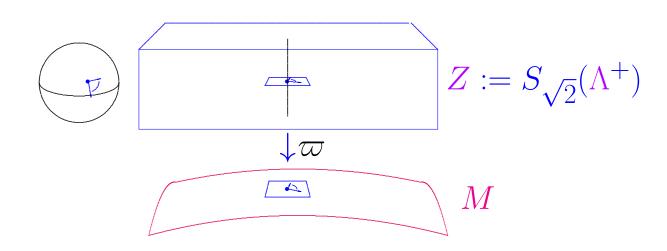
Geometric Definition.  $A \operatorname{spin}^c \operatorname{structure} on a$ smooth oriented 4-manifold M



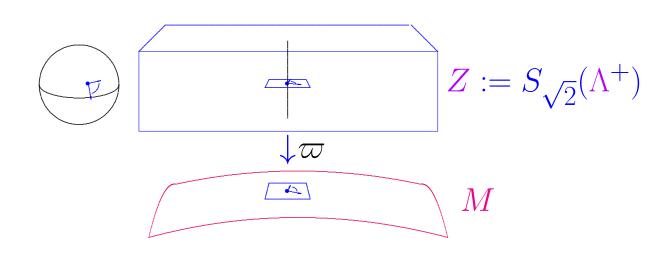
Geometric Definition. A spin<sup>c</sup> structure on a smooth oriented 4-manifold M is a complex line bundle  $\mathcal{L} \to Z$ 



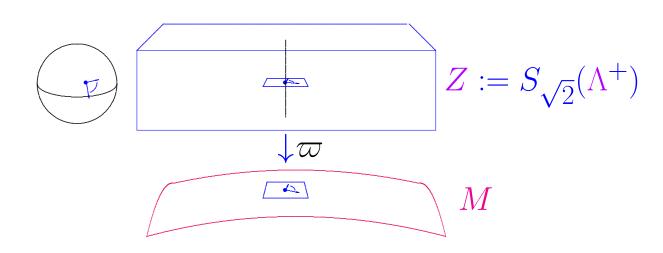
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Geometric Definition. A spin<sup>c</sup> structure on a smooth oriented 4-manifold M is a complex line bundle  $\mathcal{L} \to Z$  on the twistor space that has degree 1



**Geometric Definition.** A spin<sup>c</sup> structure on a smooth oriented 4-manifold M is a complex line bundle  $\mathcal{L} \to Z$  on the twistor space that has degree 1 on any  $S^2$  fiber of  $Z \to M$ .



# Standard Definition.

Standard Definition. A spin<sup>c</sup> structure on an oriented Riemannian 4-manifold (M, g)

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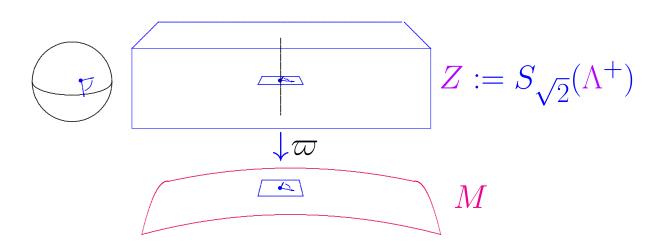
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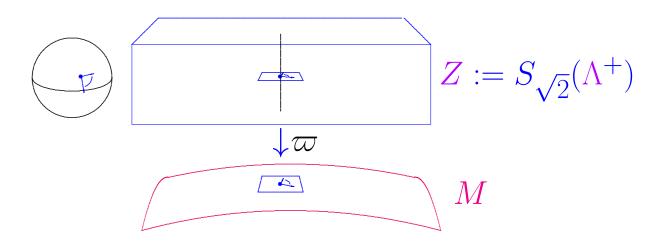
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This can be made into a principal  $\mathbf{Spin}^c(4)$ -bundle  $\widehat{\mathfrak{F}} \to M$  in an essentially unique way.

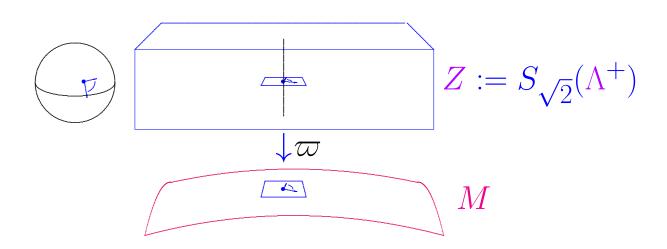
## Geometric Definition.



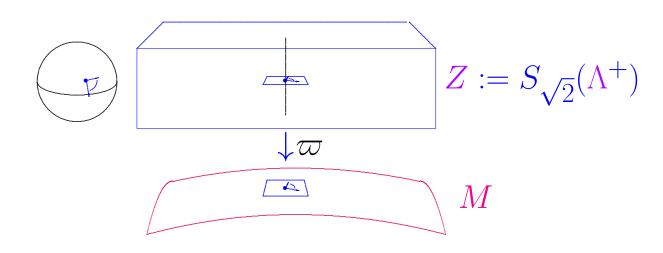
# Geometric Definition. A spin structure

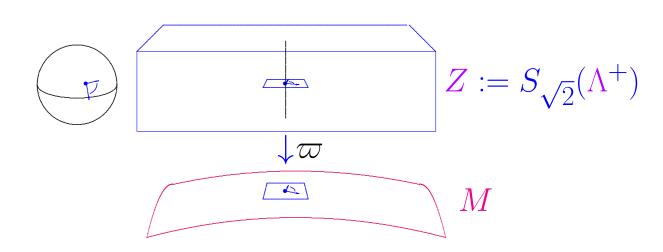


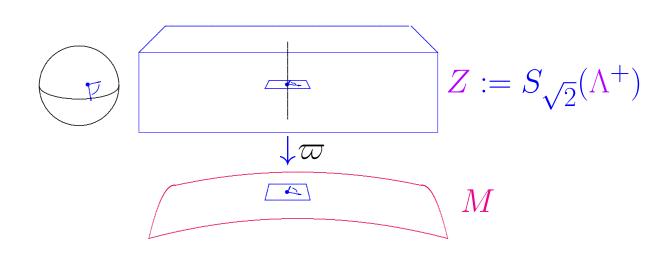
Geometric Definition. A spin structure on an oriented Riemannian 4-manifold (M, g)



Geometric Definition. A spin structure on an oriented Riemannian 4-manifold (M, g) is a square-root  $\mathcal{V}^{1/2}$ 







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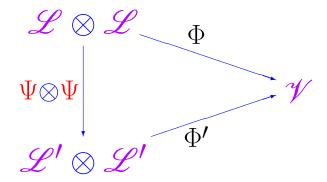
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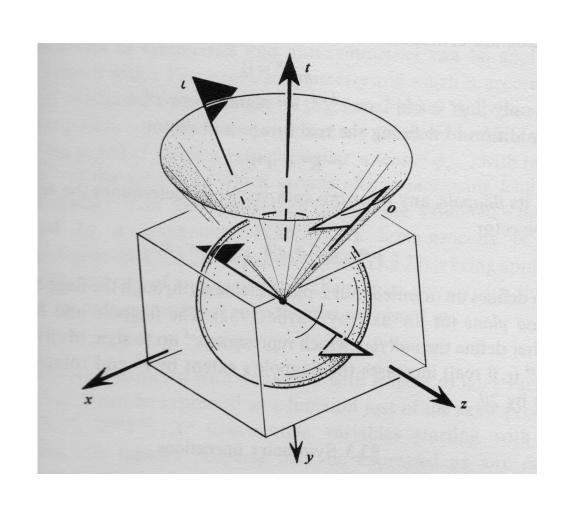
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is the universal cover of SO(4).

**Standard Definition.** A spin structure on an oriented Riemannian 4-manifold (M, g) is a double cover

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$$\rightarrow H^2(\mathsf{E}) \rightarrow H^2(\mathsf{E}-0) \rightarrow \\ H^3(\mathsf{E},\mathsf{E}-0) \rightarrow H^3(\mathsf{E}) \rightarrow H^3(\mathsf{E}-0) \rightarrow \\ H^4(\mathsf{E},\mathsf{E}-0) \rightarrow H^4(\mathsf{E}) \rightarrow H^4(\mathsf{E}-0) \rightarrow \\ H^5(\mathsf{E},\mathsf{E}-0) \rightarrow$$

#### Key tool:

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Thom isomorphism:

$$H^{k-3}(M) \stackrel{\cong}{\longrightarrow} H^k(\mathsf{E},\mathsf{E}-0)$$

**Proposition.** Let M be a smooth oriented connected compact 4-manifold, and let  $E \to M$  be a real oriented rank-3 vector bundle, equipped with positive-definite inner-product. Let  $\varpi : \mathbb{Z} \to M$  be the unit 2-sphere bundle  $\mathbb{Z} = S(E)$ , and let  $F \in H_2(\mathbb{Z}, \mathbb{Z})$  be the homology class of an  $S^2$ -fiber of  $\varpi$ . Then the following are equivalent:

- (i) The Euler class  $\mathbf{e}(\mathbf{E}) \in H^3(M, \mathbb{Z})$  vanishes;
- (ii)  $\exists \mathbf{a} \in H^2(\mathcal{Z}, \mathbb{Z})$  with  $\langle \mathbf{a}, F \rangle = 1$ ;
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More obvious implications:

$$(i) \Longrightarrow (ii)$$
 and  $(iii) \Longrightarrow (iv)$ .

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$$0 \to H^{2}(M) \stackrel{\varpi^{*}}{\to} H^{2}(\mathcal{Z}) \stackrel{\varpi_{*}}{\to} H^{0}(M) \stackrel{\cup e}{\to}$$

$$\to H^{3}(M) \stackrel{\varpi^{*}}{\to} H^{3}(\mathcal{Z}) \stackrel{\varpi_{*}}{\to} H^{1}(M) \stackrel{\cup e}{\to}$$

$$\to H^{4}(M) \stackrel{\varpi^{*}}{\to} H^{4}(\mathcal{Z}) \stackrel{\varpi_{*}}{\to} H^{2}(M) \stackrel{\cup e}{\to} 0$$

- (i) The Euler class  $\mathbf{e}(\mathbf{E}) \in H^3(M, \mathbb{Z})$  vanishes;
- (ii)  $\exists \mathbf{a} \in H^2(\mathcal{Z}, \mathbb{Z})$  with  $\langle \mathbf{a}, F \rangle = 1$ ;
- (iii)  $H_2(\mathbb{Z}, \mathbb{Z}) \cong H_2(M, \mathbb{Z}) \oplus \mathbb{Z}$ ; and
- (iv)  $|\mathfrak{T}_2(\mathbb{Z})| = |\mathfrak{T}_2(M)|$ , where  $\mathfrak{T}_2$  is the torsion subgroup of  $H_2(\underline{\hspace{0.5cm}},\mathbb{Z})$ .

More obvious implications:

$$(i) \Longrightarrow (ii)$$
 and  $(iii) \Longrightarrow (iv)$ .

- (i) The Euler class  $\mathbf{e}(\mathbf{E}) \in H^3(\mathbf{M}, \mathbb{Z})$  vanishes;
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What about

$$(ii) \Longrightarrow (iii)$$
?

- (i) The Euler class  $\mathbf{e}(\mathbf{E}) \in H^3(M, \mathbb{Z})$  vanishes;
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$$0 \to H^{2}(M, \mathbb{Z}) \xrightarrow{\varpi^{*}} H^{2}(\mathcal{Z}, \mathbb{Z}) \xrightarrow{\varpi_{*}} H^{0}(M, \mathbb{Z}) \xrightarrow{\cup e}$$

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$$\to H^{4}(M, \mathbb{Z}) \xrightarrow{\varpi^{*}} H^{4}(\mathcal{Z}, \mathbb{Z}) \xrightarrow{\varpi_{*}} H^{2}(M, \mathbb{Z}) \xrightarrow{\cup e} 0$$

$$0 \to H^{2}(M, \mathbb{Z}) \xrightarrow{\varpi^{*}} H^{2}(\mathcal{Z}, \mathbb{Z}) \xrightarrow{\varpi_{*}} H^{0}(M, \mathbb{Z}) \xrightarrow{\cup \mathbf{e}}$$

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$$H^{4}(M, \mathbb{Z}) = \mathbb{Z} \text{ is free,}$$

$$0 \to H^{2}(M, \mathbb{Z}) \xrightarrow{\varpi^{*}} H^{2}(\mathcal{Z}, \mathbb{Z}) \xrightarrow{\varpi_{*}} H^{0}(M, \mathbb{Z}) \xrightarrow{\bigcup e}$$

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$$0 \to H^4(M, \mathbb{Z}) \stackrel{\varpi^*}{\to} H^4(\mathcal{Z}, \mathbb{Z}) \stackrel{\varpi_*}{\to} H^2(M, \mathbb{Z}) \to 0$$
 Poincaré duality:

$$0 \to H^{2}(M, \mathbb{Z}) \xrightarrow{\varpi^{*}} H^{2}(\mathcal{Z}, \mathbb{Z}) \xrightarrow{\varpi^{*}} H^{0}(M, \mathbb{Z}) \xrightarrow{\bigcup e}$$

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Poincaré duality:

$$0 \to \mathbb{Z} \stackrel{\cdot F}{\to} H_2(\mathbb{Z}, \mathbb{Z}) \to H_2(M, \mathbb{Z}) \to 0$$

$$0 \to H^{2}(M, \mathbb{Z}) \xrightarrow{\varpi^{*}} H^{2}(\mathcal{Z}, \mathbb{Z}) \xrightarrow{\varpi^{*}} H^{0}(M, \mathbb{Z}) \xrightarrow{\bigcup e}$$

$$\to H^{3}(M, \mathbb{Z}) \xrightarrow{\varpi^{*}} H^{3}(\mathcal{Z}, \mathbb{Z}) \xrightarrow{\varpi^{*}} H^{1}(M, \mathbb{Z}) \xrightarrow{\bigcup e}$$

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$$H^{4}(M, \mathbb{Z}) = \mathbb{Z} \text{ is free,}$$

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$$0 \to \mathbb{Z} \stackrel{\cdot F}{\to} H_2(\mathcal{Z}, \mathbb{Z}) \to H_2(M, \mathbb{Z}) \to 0$$
If  $\exists \mathbf{a} \in H^2(\mathcal{Z}, \mathbb{Z})$  with  $\langle \mathbf{a}, F \rangle = 1$ , gives splitting
$$0 \to \mathbb{Z} \stackrel{\cdot}{\to} H_2(\mathcal{Z}, \mathbb{Z}) \to H_2(M, \mathbb{Z}) \to 0$$

$$0 \to H^{2}(M, \mathbb{Z}) \xrightarrow{\varpi^{*}} H^{2}(\mathcal{Z}, \mathbb{Z}) \xrightarrow{\varpi^{*}} H^{0}(M, \mathbb{Z}) \xrightarrow{\bigcup e}$$

$$\to H^{3}(M, \mathbb{Z}) \xrightarrow{\varpi^{*}} H^{3}(\mathcal{Z}, \mathbb{Z}) \xrightarrow{\varpi^{*}} H^{1}(M, \mathbb{Z}) \xrightarrow{\bigcup e}$$

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If  $\exists \mathbf{a} \in H^2(\mathbb{Z}, \mathbb{Z})$  with  $\langle \mathbf{a}, F \rangle = 1$ , gives splitting 
$$H_2(\mathbb{Z}, \mathbb{Z}) \cong \mathbb{Z} \oplus H_2(M, \mathbb{Z}).$$

So we now have

$$(i) \Longrightarrow (ii) \Longrightarrow (iii) \Longrightarrow (iv).$$

- (i) The Euler class  $\mathbf{e}(\mathbf{E}) \in H^3(M, \mathbb{Z})$  vanishes;
- (ii)  $\exists \mathbf{a} \in H^2(\mathcal{Z}, \mathbb{Z})$  with  $\langle \mathbf{a}, F \rangle = 1$ ;
- (iii)  $H_2(\mathbb{Z}, \mathbb{Z}) \cong H_2(M, \mathbb{Z}) \oplus \mathbb{Z}$ ; and
- (iv)  $|\mathfrak{T}_2(\mathbb{Z})| = |\mathfrak{T}_2(M)|$ , where  $\mathfrak{T}_2$  is the torsion subgroup of  $H_2(\underline{\hspace{0.5cm}},\mathbb{Z})$ .

Finally, we'll show

$$(iv) \Longrightarrow (i)$$

- (i) The Euler class  $\mathbf{e}(\mathbf{E}) \in H^3(M, \mathbb{Z})$  vanishes;
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$$0 \to H^{2}(M, \mathbb{Z}) \xrightarrow{\varpi^{*}} H^{2}(\mathcal{Z}, \mathbb{Z}) \xrightarrow{\varpi_{*}} H^{0}(M, \mathbb{Z}) \xrightarrow{\cup e}$$

$$\to H^{3}(M, \mathbb{Z}) \xrightarrow{\varpi^{*}} H^{3}(\mathcal{Z}, \mathbb{Z}) \xrightarrow{\varpi_{*}} H^{1}(M, \mathbb{Z}) \xrightarrow{\cup e}$$

$$\to H^{4}(M, \mathbb{Z}) \xrightarrow{\varpi^{*}} H^{4}(\mathcal{Z}, \mathbb{Z}) \xrightarrow{\varpi_{*}} H^{2}(M, \mathbb{Z}) \xrightarrow{\cup e} 0$$

$$\mathfrak{T}_2(M) \cong \mathfrak{T}^3(M), \qquad \mathfrak{T}_2(\mathcal{Z}) \cong \mathfrak{T}^3(\mathcal{Z})$$

$$0 \to H^{2}(M, \mathbb{Z}) \xrightarrow{\varpi^{*}} H^{2}(\mathcal{Z}, \mathbb{Z}) \xrightarrow{\varpi_{*}} H^{0}(M, \mathbb{Z}) \xrightarrow{\cup e}$$

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$$|\mathfrak{T}_2(\mathcal{Z})| = |\mathfrak{T}_2(M)| \implies |\mathfrak{T}^3(\mathcal{Z})| = |\mathfrak{T}^3(M)|$$

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$$|\mathfrak{T}_2(\mathcal{Z})| = |\mathfrak{T}_2(M)| \implies |\mathfrak{T}^3(\mathcal{Z})| = |\mathfrak{T}^3(M)|$$
  
But

$$H^0(M, \mathbb{Z}) \stackrel{\cup \mathbf{e}}{\to} H^3(M, \mathbb{Z}) \stackrel{\varpi^*}{\to} H^3(\mathcal{Z}, \mathbb{Z}) \stackrel{\varpi_*}{\to} H^1(M, \mathbb{Z})$$

$$0 \to H^{2}(M, \mathbb{Z}) \xrightarrow{\varpi^{*}} H^{2}(\mathcal{Z}, \mathbb{Z}) \xrightarrow{\varpi_{*}} H^{0}(M, \mathbb{Z}) \xrightarrow{\cup e}$$

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$$|\mathfrak{T}_2(\mathcal{Z})| = |\mathfrak{T}_2(M)| \implies |\mathfrak{T}^3(\mathcal{Z})| = |\mathfrak{T}^3(M)|$$
  
But

$$\mathbb{Z} \xrightarrow{\mathbf{e} \cdot} \mathfrak{T}^3(\mathbf{M}) \rightarrow \mathfrak{T}^3(\mathbf{Z}) \rightarrow 0$$

$$0 \to H^{2}(M, \mathbb{Z}) \xrightarrow{\varpi^{*}} H^{2}(\mathcal{Z}, \mathbb{Z}) \xrightarrow{\varpi_{*}} H^{0}(M, \mathbb{Z}) \xrightarrow{\cup e}$$

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But

$$\mathfrak{T}^3(\mathcal{Z}) = \mathfrak{T}^3(M)/\langle e(\mathsf{E}) \rangle$$

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angle$$

Hence

$$|\mathfrak{T}_2(\mathcal{Z})| = |\mathfrak{T}_2(M)| \implies \mathsf{e}(\mathsf{E}) = 0.$$

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In other words,

$$(iv) \Longrightarrow (i)$$
.

$$(iv) \Longrightarrow (i)!$$

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So we've shown

$$(i) \Longrightarrow (ii) \Longrightarrow (iv) \Longrightarrow (i)$$

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We'll prove that 
$$Z = S(\Lambda^+)$$
 satisfies  $|\mathfrak{T}_2(Z)| = |\mathfrak{T}_2(M)|.$ 

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We'll do this by showing the geometric projection

$$\varpi_*:\mathfrak{T}_2(Z)\to\mathfrak{T}_2(M)$$

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**Observation 1.** Every homology class  $\in H_2(M, \mathbb{Z})$  can be represented by a smoothly embedded compact oriented surface

$$\Sigma^2 \subset M^4$$
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Why? By Poincaré duality, every such class is dual to an element of  $H^2(M^4, \mathbb{Z})$ , which is then  $c_1(\mathsf{L})$  for some complex line bundle  $\mathsf{L} \to M$ .

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Why? By Poincaré duality, every such class is dual to an element of  $H^2(M^4, \mathbb{Z})$ , which is then  $c_1(\mathsf{L})$  for some complex line bundle  $\mathsf{L} \to M$ . Zero set of a generic section of  $\mathsf{L}$  is an embedded compact oriented surface  $\Sigma$  in the given homology class.

We'll prove that 
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 satisfies  $\varpi_* : \mathfrak{T}_2(Z) \twoheadrightarrow \mathfrak{T}_2(M).$ 

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 $j: TM|_{\Sigma} \to TM|_{\Sigma}$  rotates by  $+90^{\circ}$  in  $T\Sigma$ ,  $T\Sigma^{\perp}$ .

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**Observation 1.** Every homology class  $\in H_2(M, \mathbb{Z})$  can be represented by a smoothly embedded compact oriented surface

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Observation 2. Every smoothly embedded oriented surface  $\Sigma \subset M$  has a canonical lift  $\widehat{\Sigma} \hookrightarrow Z$ :

$$J_H: H_{\widehat{\Sigma}} \to H_{\widehat{\Sigma}} \text{ rotates by } +90^{\circ} \text{ in } T\Sigma, T\Sigma^{\perp}.$$

We'll prove that 
$$Z = S(\Lambda^+)$$
 satisfies  $\varpi_* : \mathfrak{T}_2(Z) \twoheadrightarrow \mathfrak{T}_2(M).$ 

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So if  $[\Sigma] \in H_2(M, \mathbb{Z})$  is a torsion class, then

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Why torsion?

$$H^2(Z,\mathbb{R}) = \mathbb{R}c_1(H^{1,0}) \oplus \varpi^*H^2(M,\mathbb{R})$$

and

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- (i) The Euler class  $\mathbf{e}(\mathbf{E}) \in H^3(M, \mathbb{Z})$  vanishes;
- (ii)  $\exists \mathbf{a} \in H^2(\mathcal{Z}, \mathbb{Z})$  with  $\langle \mathbf{a}, F \rangle = 1$ ;
- (iii)  $H_2(\mathbb{Z}, \mathbb{Z}) \cong H_2(M, \mathbb{Z}) \oplus \mathbb{Z}$ ; and
- (iv)  $|\mathfrak{T}_2(\mathbb{Z})| = |\mathfrak{T}_2(M)|$ , where  $\mathfrak{T}_2$  is the torsion subgroup of  $H_2(\underline{\hspace{1em}},\mathbb{Z})$ .

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(This defines fiber-wise  $\mathcal{O}$  structure of  $\mathcal{L}$ .)

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which e.g. appears in Seiberg-Witten equations

$$\mathcal{D}_{\theta} \Phi = 0$$

$$F_{\theta}^{+} = i \sigma(\Phi).$$

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But since  $\operatorname{rank}_{\mathbb{R}}(\mathbb{V}_+) = 4 = \dim M$ , always have sections of  $\mathbb{V}_+$  that only vanish at one point!

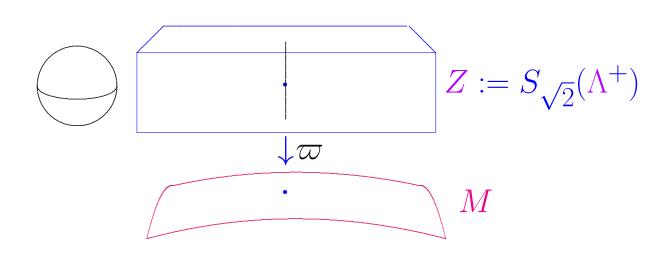
**Theorem.** Let (M, g) be a compact connected oriented Riemannian 4-manifold.

•  $M - \{p\}$  admits almost-complex structures J compatible with the given metric, orientation.

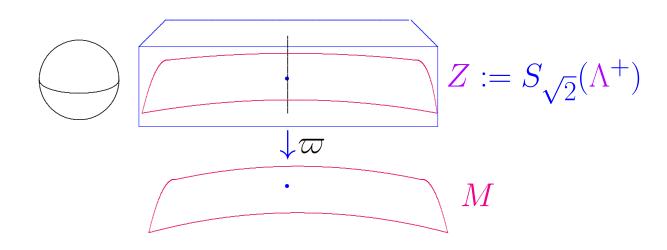
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## Happy Birthday, Roger!



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And Many Happy Returns!