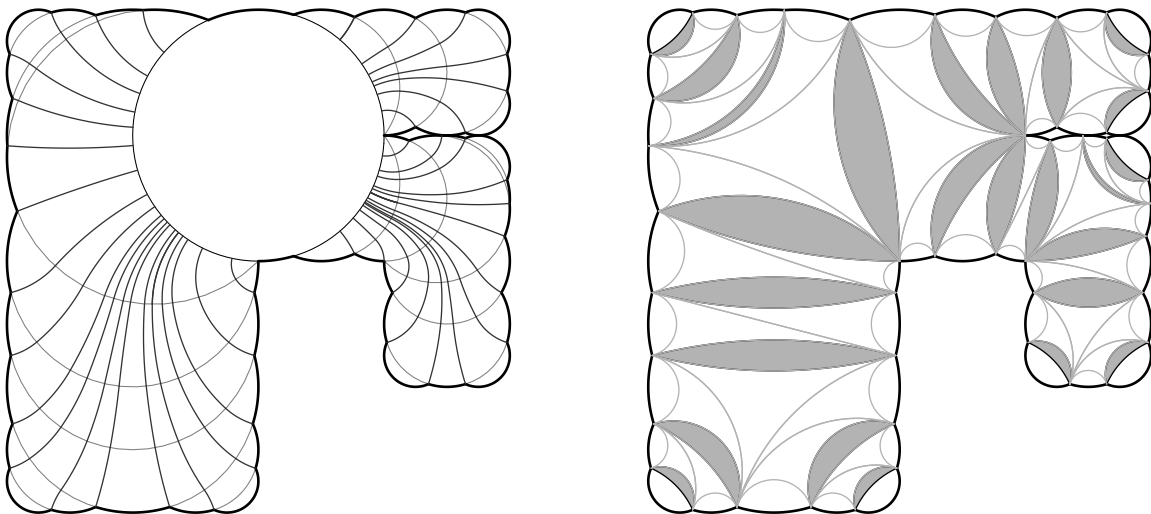
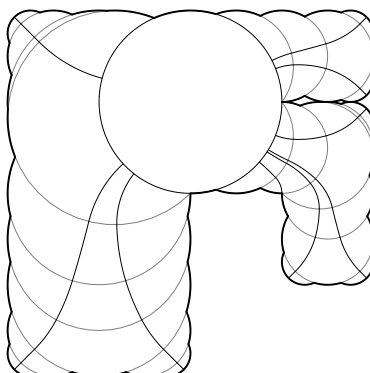
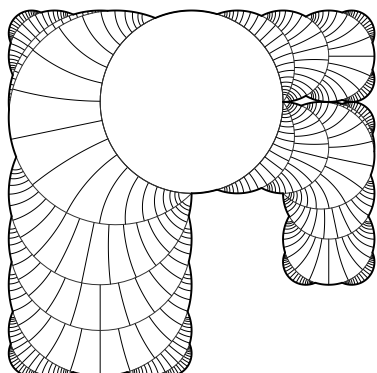
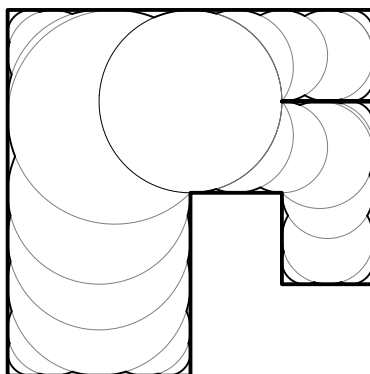
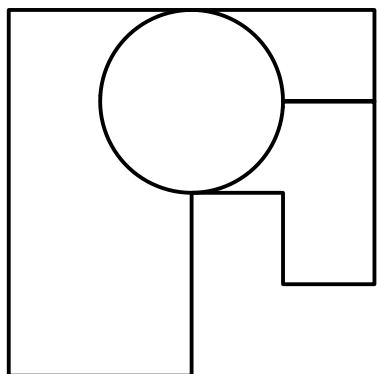


# Conformal Mapping in Linear Time

Christopher J. Bishop  
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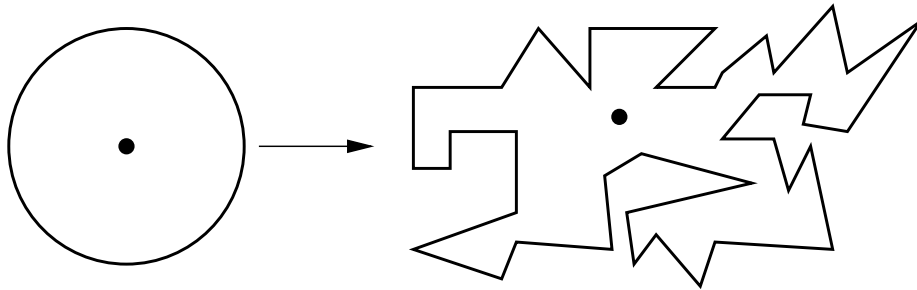


copies of lecture slides available at  
[www.math.sunysb.edu/~bishop/lectures](http://www.math.sunysb.edu/~bishop/lectures)



- Fast to compute using medial axis.
- Close to Riemann map.
- Motivated by hyperbolic 3-manifolds.

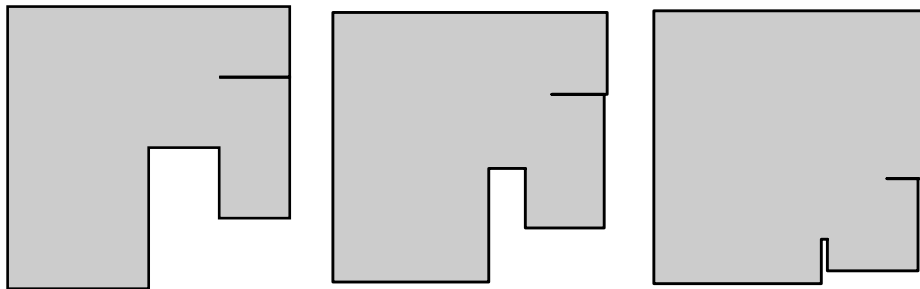
**Riemann Mapping:** If  $\Omega$  is simply connected, then there is a conformal  $f : \mathbb{D} \rightarrow \Omega$ .



**Schwarz-Christoffel** formula for polygons

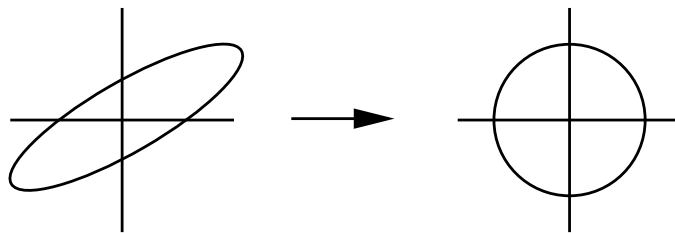
$$f(z) = A + C \int^z \prod_{k=1}^n \left(1 - \frac{w}{z_k}\right)^{\alpha_k - 1} dw.$$

$\alpha$ 's are interior angles,  $z$ 's are pre-vertices.



A mapping  $f$  is  $K$ -quasiconformal if either:

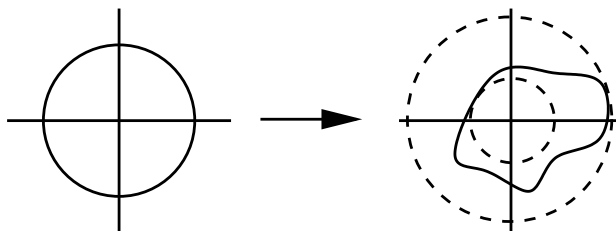
**Analytic definition:**  $|f_{\bar{z}}| \leq \frac{K-1}{K+1}|f_z|$



$$f_z = \frac{1}{2}(f_x - if_y), \quad f_{\bar{z}} = \frac{1}{2}(f_x + if_y).$$

**Metric definition:** For every  $x \in \Omega$ ,  $\epsilon > 0$  and small enough  $r > 0$ , there is  $s > 0$  so that

$$D(f(x), s) \subset f(D(x, r)) \subset D(f(x), s(K + \epsilon)).$$



Notation for today:  $\epsilon$ -conformal =  $e^\epsilon$ -quasiconformal.

- $f$  determined  $\mu_f = f_{\bar{z}}/f_z$ . Conformal iff  $\mu \equiv 0$
- If  $\epsilon$ -QC and fixes  $1, -1, i$  then  $|f(z) - z| = O(\epsilon)$ .

**Theorem:** If  $\partial\Omega$  is an  $n$ -gon we can compute a  $\epsilon$ -QC map between  $\Omega$  and  $\mathbb{D}$  in time  $O(n \log^2 \frac{1}{\epsilon} \log \log \frac{1}{\epsilon})$ .

**Theorem:** Suppose  $\partial\Omega$  is an  $n$ -gon. We can construct points  $\mathbf{w} = \{w_1, \dots, w_n\} \subset \mathbb{T}$  so that:

1. requires at most  $O(n \log^2 \frac{1}{\epsilon} \log \log \frac{1}{\epsilon})$  steps.
2.  $d_{QC}(\mathbf{w}, \mathbf{z}) < \epsilon$ .

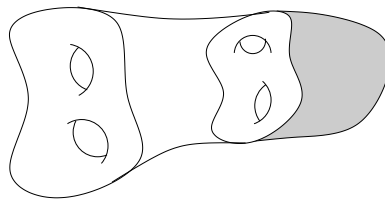
$\mathbf{z}$  = conformal pre-vertices.

$$d_{QC}(\mathbf{w}, \mathbf{z}) = \inf\{\log K : \exists h \in \text{QC}_K, h(\mathbf{w}) = \mathbf{z}\}.$$

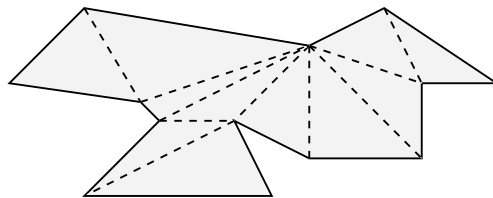
$\text{QC}_K = K$ -quasiconformal maps.

Proof is amusing because it involves (at least) two results which don't seem to involve conformal mappings:

**Theorem (Sullivan, Epstein-Marden):** If  $M$  is a hyperbolic 3-manifold and  $C(M)$  is the convex core of  $M$ , then there is a biLipschitz map between  $\partial_\infty M$  and  $\partial C(M)$ .



**Theorem (Chazelle):** A simple  $n$ -gon can be triangulated in time  $O(n)$ .



## Proof of theorem is in two steps:

**Step 1:** Given  $\epsilon < \epsilon_0$  and  $\epsilon$ -QC  $f_n : \Omega \rightarrow \mathbb{D}$  construct  $C\epsilon^2$ -QC map  $f_{n+1} : \Omega \rightarrow \mathbb{D}$ . Construction takes time  $C(\epsilon) = C + C \log^2 \frac{1}{\epsilon} \log \log \frac{1}{\epsilon}$ .

**Step 2:** Build domains, maps and finite sets

$$(\Omega_0, V_0) \xrightarrow{g_0}, \dots, \xrightarrow{g_{N-1}} (\Omega_N, V_N)$$

so that

- $\Omega_0 = \mathbb{D}$ ,
- $\Omega_N = \Omega$ ,  $V_N = V$ ,
- $\delta$ -QC maps  $g_k : \Omega_k \rightarrow \Omega_{k+1}$ ,  $V_k \rightarrow V_{k+1}$ .

If  $\delta < \epsilon_0/2$  then find conformal maps by induction (use previously found map  $f_k : \mathbb{D} \rightarrow \Omega_k$  composed with  $g_k$  as starting point of iteration in Step 1 to find next map  $f_{k+1} : \mathbb{D} \rightarrow \Omega_{k+1}$  with

accuracy  $\epsilon/2$ ).



**Amazing Fact 1:**  $\epsilon_0$  is independent of  $\Omega, n$ .

**Amazing Fact 2:**  $N$  is independent of  $\Omega, n$ .

**Consequence:** Can build chain of domains and maps and get  $\epsilon_0$  approximation in time  $O(n)$  (independent of  $\Omega$ ). Then just repeat Step 1 until get desired accuracy :

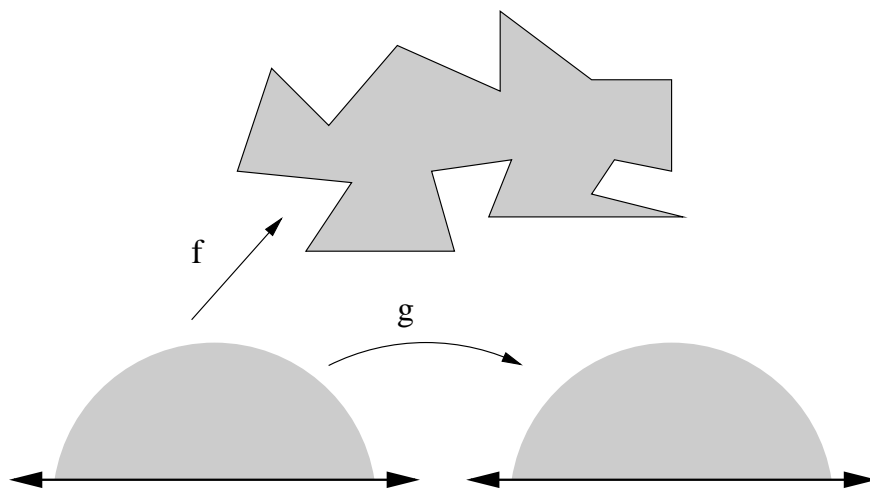
$$\epsilon_0, C\epsilon_0^2, \dots, C^k\epsilon_0^{2^k}.$$

About  $\log \log \epsilon$  iterations suffice and time for  $k$ th iteration is  $O(k2^{2k})$ , so work dominated by final step.

**Idea for Step 1:** Suppose

$$f : \mathbb{H} \rightarrow \Omega, \quad g : \mathbb{H} \rightarrow \mathbb{H}, \quad \mu_f = \mu_g.$$

Then  $f \circ g^{-1} : \mathbb{H} \rightarrow \Omega$  is conformal.

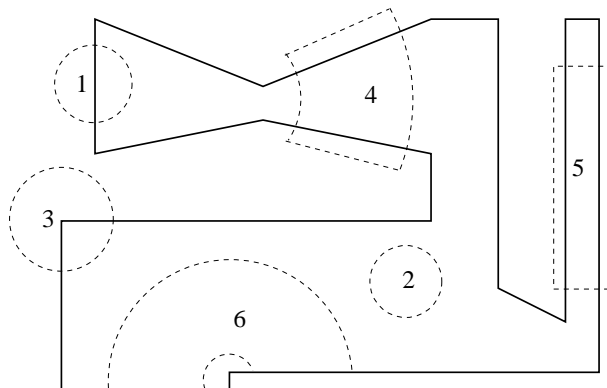
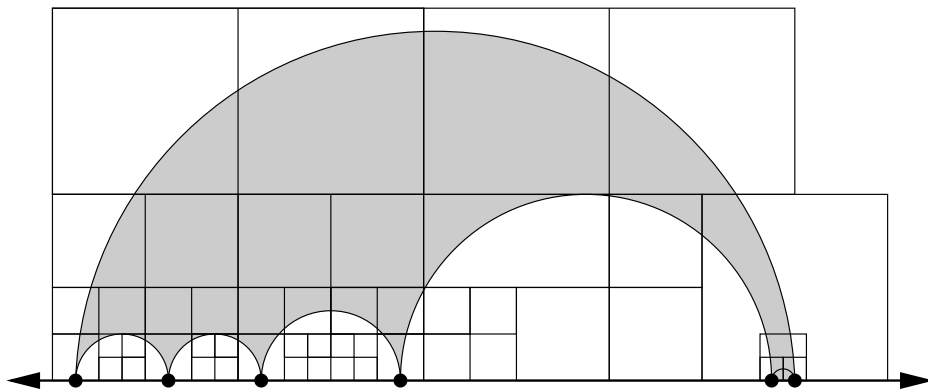


Can't solve Beltrami equation  $g_{\bar{z}} = \mu g_z$  exactly in finite time, but can quickly solve

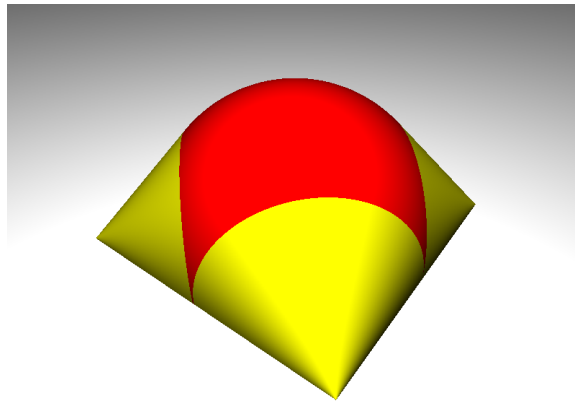
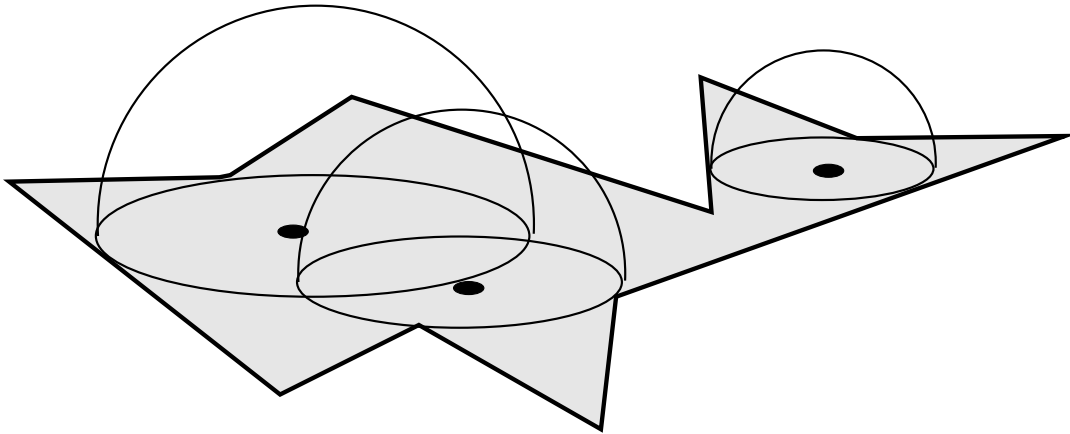
$$g_{\bar{z}} = (\mu + O(\|\mu\|^2))g_z,$$

using fast multipole method of Greengard and Rokhlin. Then  $f \circ g^{-1}$  is  $(1 + C\|\mu\|^2)$ -QC.

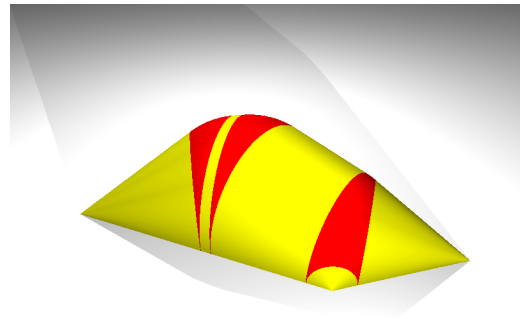
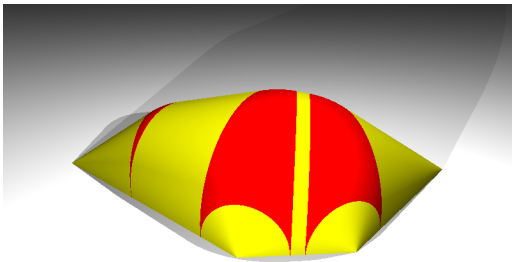
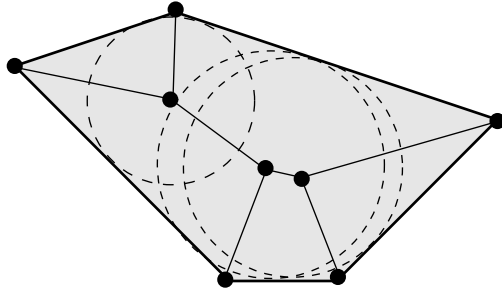
Cut  $\mathbb{H}$  into  $O(n)$  pieces on which  $f$ ,  $f^\alpha$  or  $\log f$  has nice series representation. Need  $p = O(|\log \epsilon|)$  terms on each piece to get  $\epsilon$  accuracy.



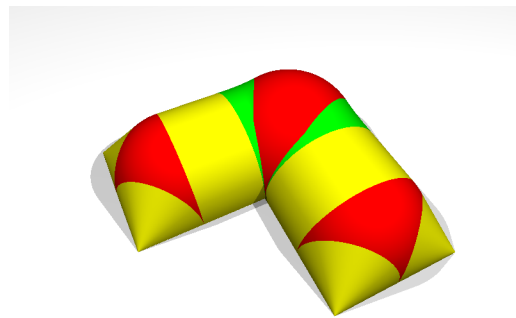
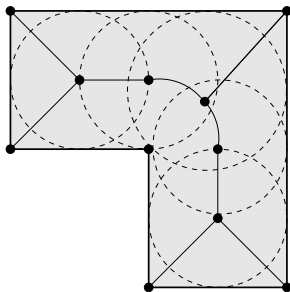
The **dome** of  $\Omega$  is boundary of union of all hemispheres with bases contained in  $\Omega$ .



A convex polygon:



A non-convex polygon:

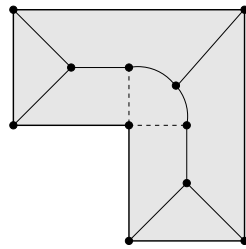


Each point on  $\text{Dome}(\Omega)$  is on dome of a maximal disk  $D$  in  $\Omega$ . Must have  $|\partial D \cap \partial \Omega| \geq 2$ . The centers of these disks form the **medial axis**.

For polygons is a finite tree with 3 types of edges:

- point-point bisectors (straight)
- edge-edge bisectors (straight)
- point-edge bisector (parabolic arc)

MA is boundary of Voronoi cells in polygon.

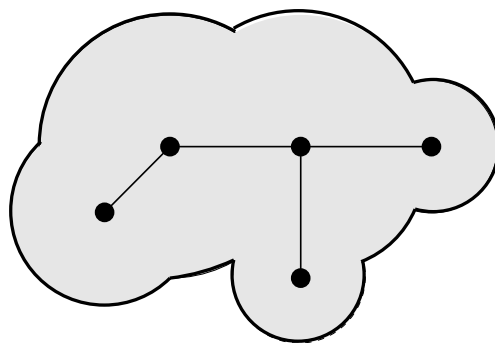
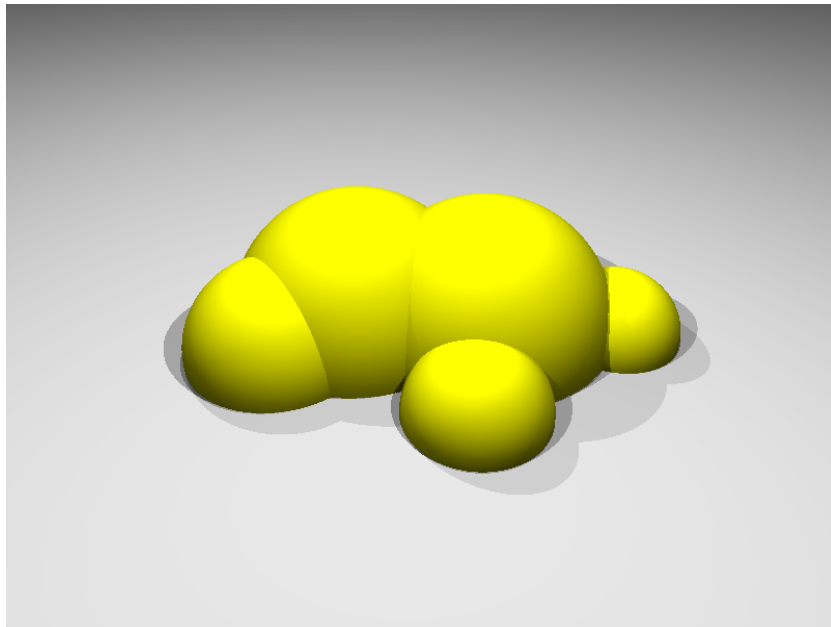


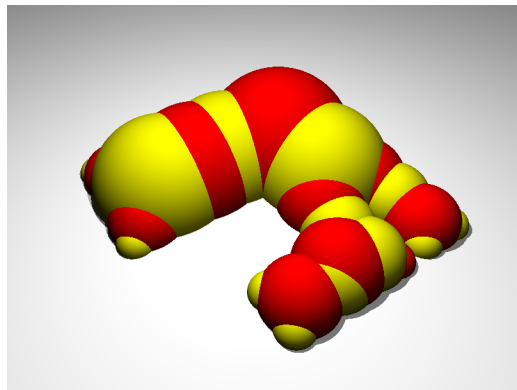
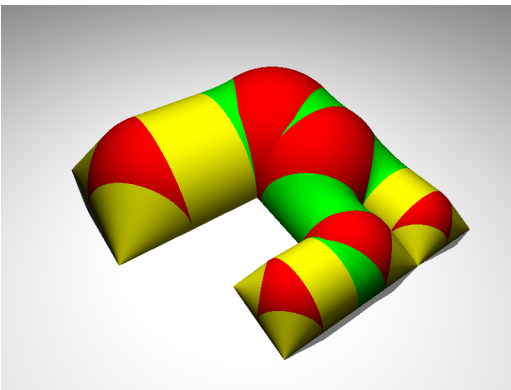
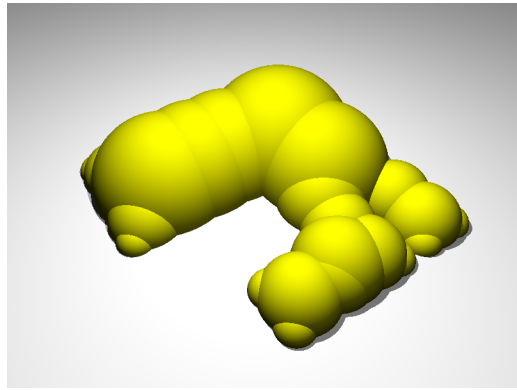
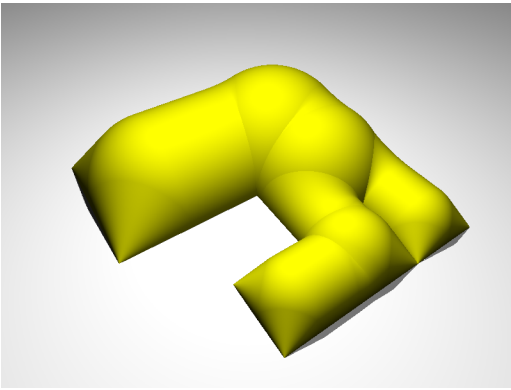
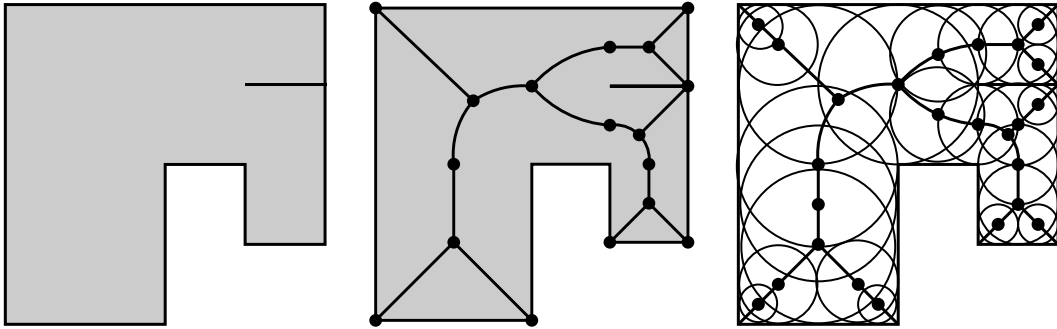
For applications see:

[www.ics.uci.edu/~eppstein/gina/medial.html](http://www.ics.uci.edu/~eppstein/gina/medial.html)

MA can be computed in linear time (Chin, Snoeyink, Wang, 1999): cut polygon into histograms, triangulate using Chazelle's method, compute Voronoi diagrams for each and merge results.

Finitely bent domain (= finite union of disks).



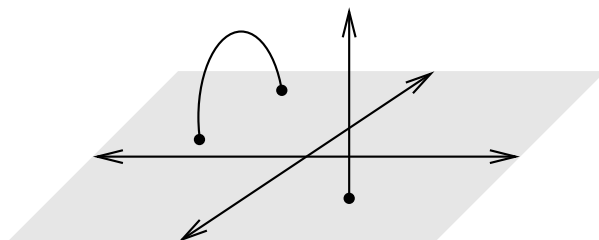




**Hyperbolic space:** Metric on  $\mathbb{R}_+^n$ ,

$$d\rho = |dz|/\text{dist}(z, \mathbb{R}^{n-1}).$$

Geodesics are circles or lines orthogonal to  $\mathbb{R}^{n-1}$ .



Dome of  $\Omega$  bounds hyperbolic convex hull of  $\Omega^c$ .

The hyperbolic metric on a simply connected plane domain  $\Omega$  is defined by transferring the metric on half-plane by conformal map.

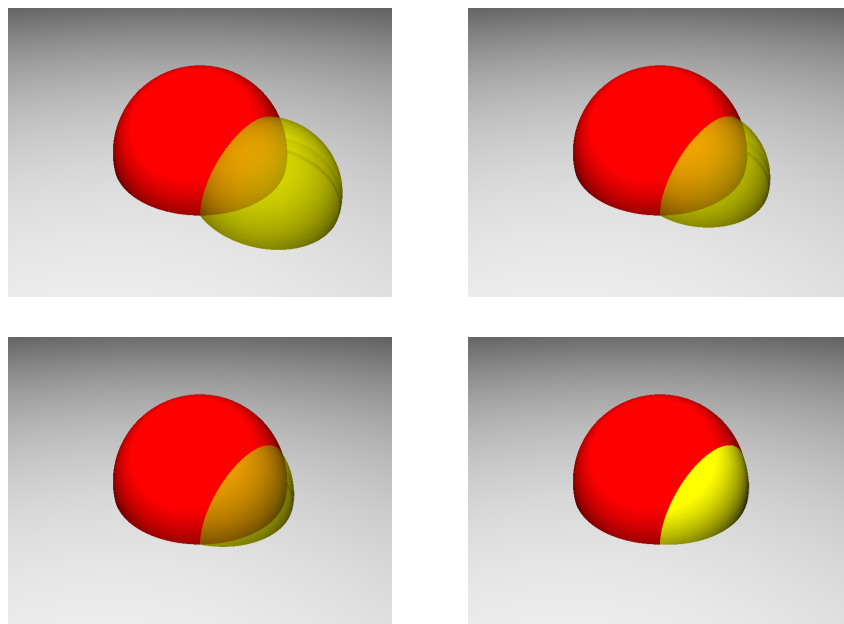
**Fact:**  $\rho \simeq \tilde{\rho}$  (pseudo-hyperbolic metric)

$$d\tilde{\rho} = \frac{|dz|}{\text{dist}(z, \partial\Omega)},$$

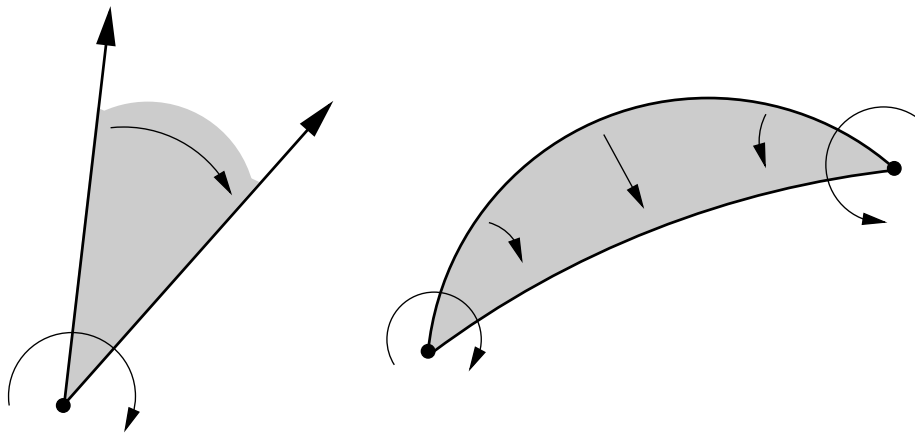
Let  $\rho_S$  be the hyperbolic path metric on  $S$ .

**Theorem (Thurston):** There is an isometry  $\iota$  from  $(S, \rho_S)$  to the hyperbolic disk.

For finitely bent domains rotate around each bending geodesic by an isometry to remove the bending (more obvious if vertices are 0 and  $\infty$ ).

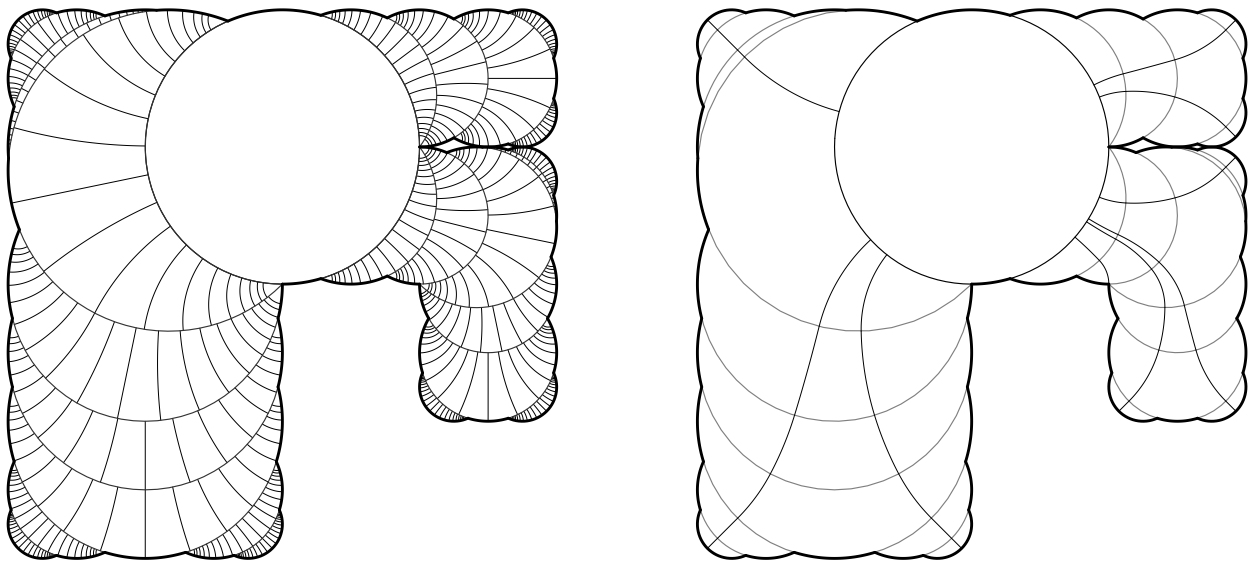


**Elliptic Möbius transformation** is conjugate to a rotation.



Elliptic transformation determined by fixed points and angle of rotation  $\theta$ . It identifies sides of a crescent of angle  $\theta$ : think of flow along circles orthogonal to boundary arcs.

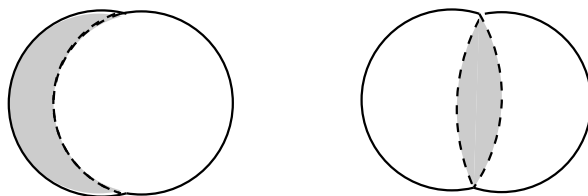
**Visualize  $\iota$  as a flow:** Write finitely bent  $\Omega$  as a disk  $D$  and a union of crescents. Foliate crescents by orthogonal circles. Following leaves of foliation in  $\Omega \setminus D$  gives  $\iota : \partial\Omega \rightarrow \partial D$ .



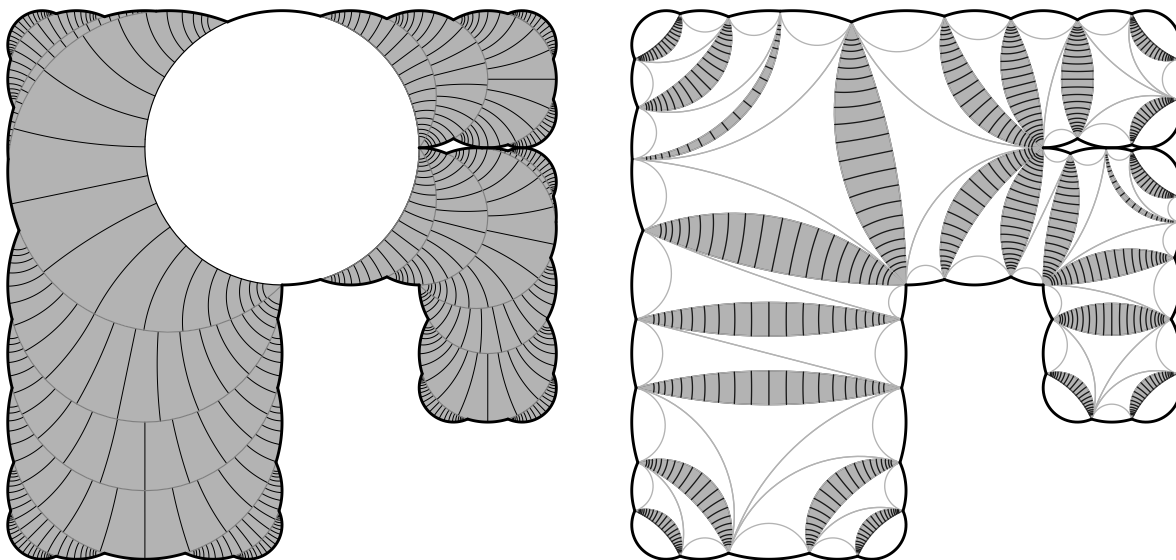
Has continuous extension to interior: identity on disk and collapses orthogonal arcs to points.

- $\iota$  is “Riemann map” from dome to disk.
- $\iota$  has  $K$ -QC extension to interior of base.
- $\iota$  can be evaluated at  $n$  points in time  $O(n)$ .

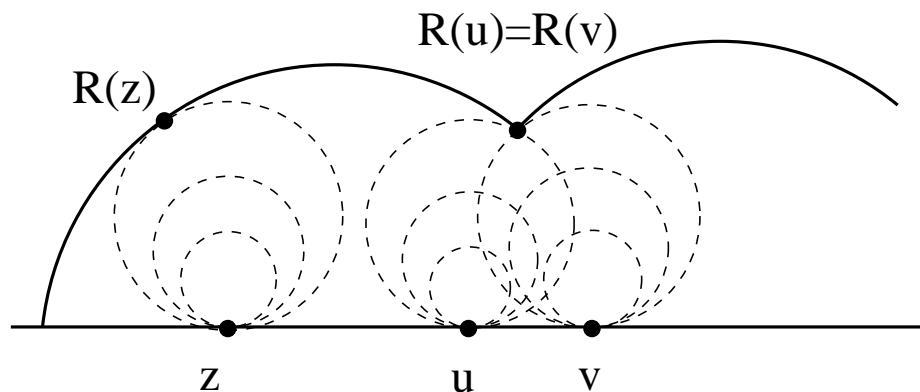
There are at least two ways to decompose a finite union of disks using crescents (with same angles and vertices in both cases).



We call these **tangential** and **normal** crescents. A finitely bent domain can be decomposed with either kind of crescent.



**Nearest point retraction**  $R : \Omega \rightarrow \text{Dome}(\Omega)$ :  
 Expand ball tangent at  $z \in \Omega$  until it hits a point  $R(z)$  of the dome.

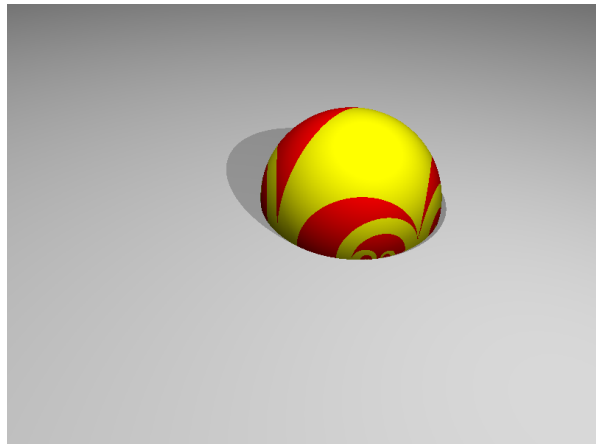
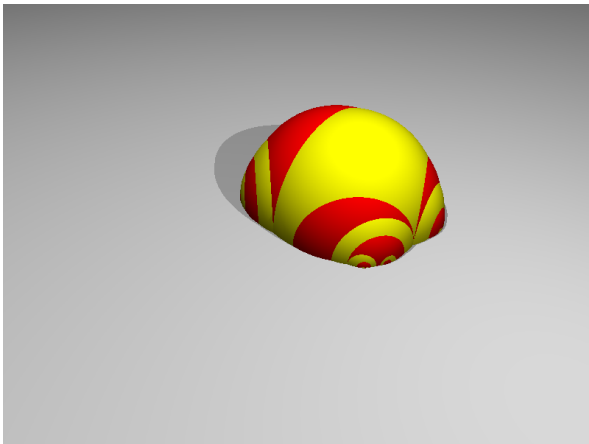
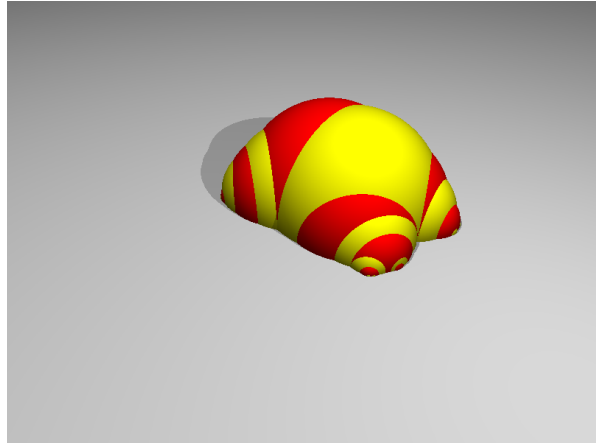
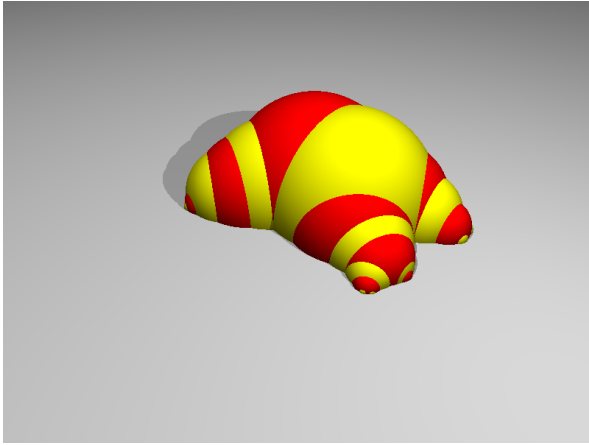
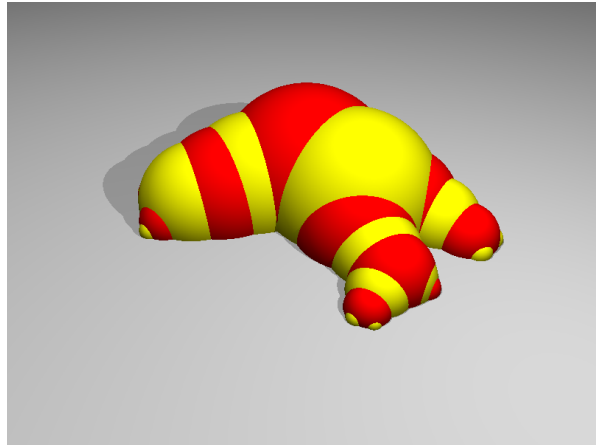
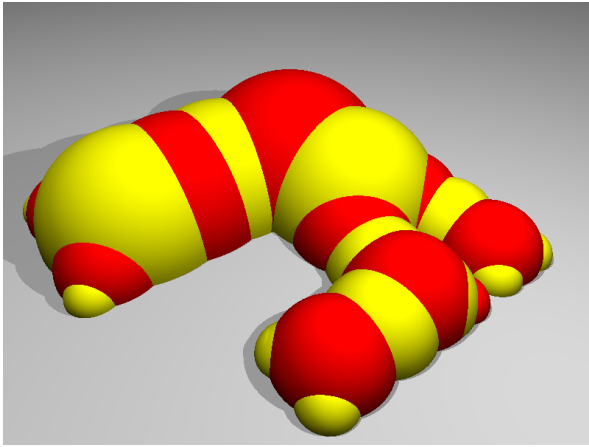


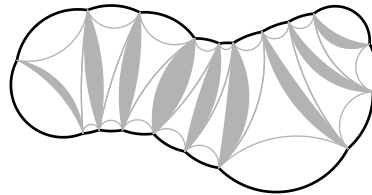
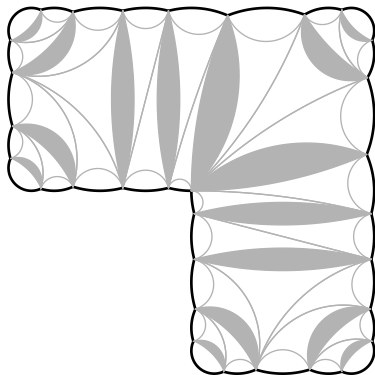
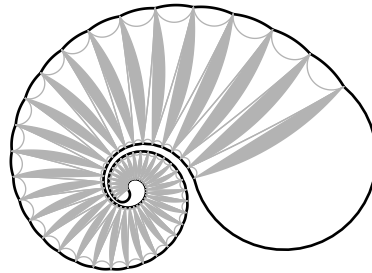
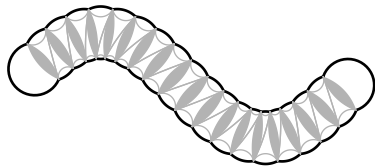
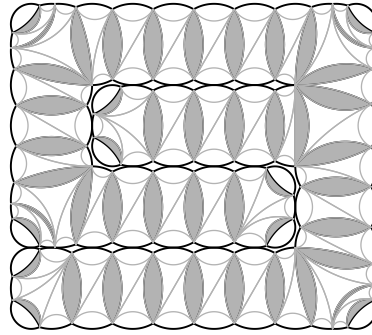
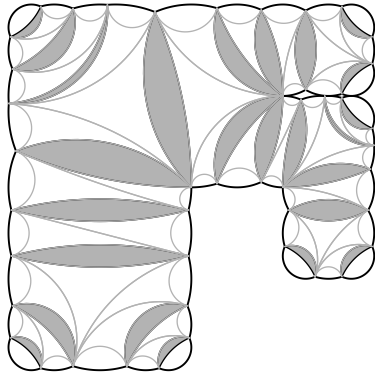
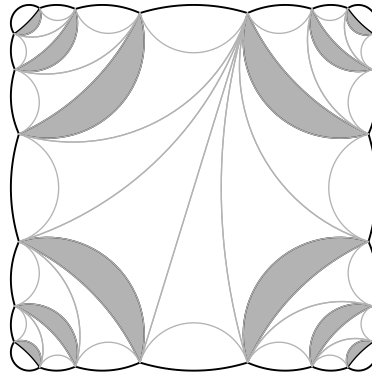
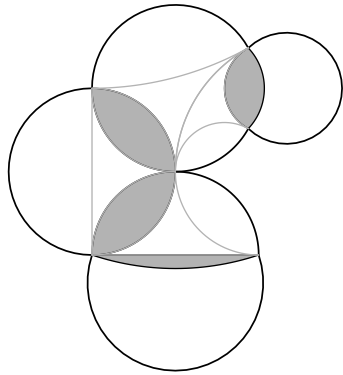
normal crescents =  $R^{-1}$ (bending lines)

gaps =  $R^{-1}$ (faces)

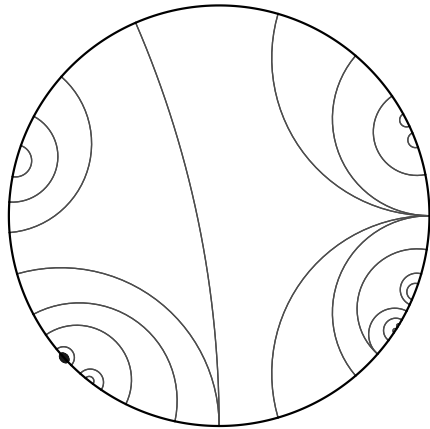
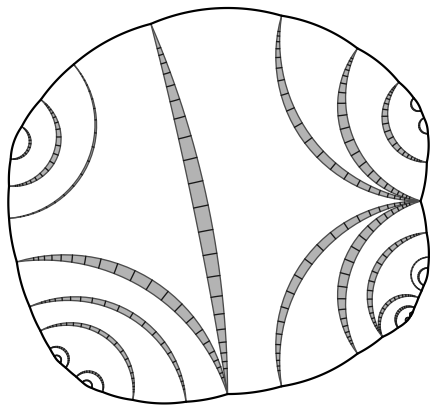
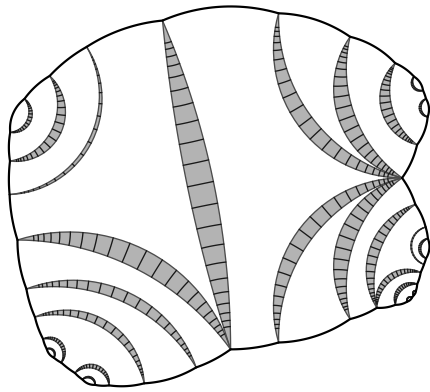
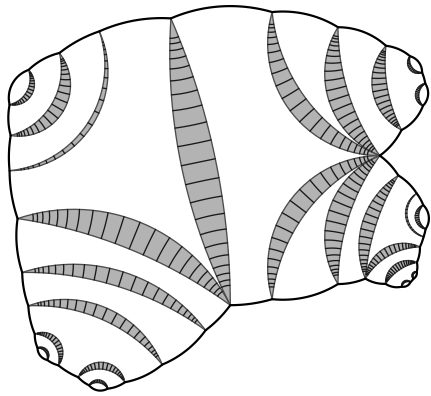
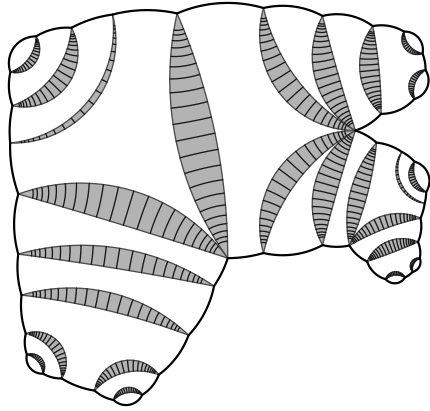
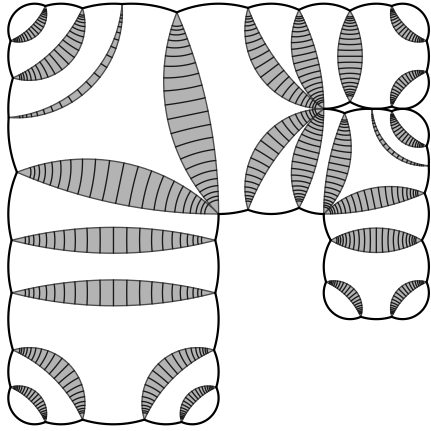
collapsing crescents = nearest point retraction

- Get map from  $\Omega$  to  $\mathbb{D}$  by mapping  $\Omega$  to dome, followed by  $\iota$  map to disk.









- $f$  is a **bi-Lipschitz** if

$$\frac{1}{A}\rho(x, y) \leq \rho(f(x), f(y)) \leq A\rho(x, y).$$

- $f$  is a **quasi-isometry** if

$$\frac{1}{A}\rho(x, y) - B \leq \rho(f(x), f(y)) \leq A\rho(x, y) + B.$$

- QI=BL at “large scales”.

- On hyperbolic disk, BL  $\Rightarrow$  QC  $\Rightarrow$  QI.

**Theorem:**  $f : \mathbb{T} \rightarrow \mathbb{T}$  has a QC-extension to interior iff it has QI-extension (hyperbolic metric) iff it has a BL-extension.

**Theorem:** Nearest point retraction is a quasi-isometry with constants independent of  $\Omega$ .

**Corollary (Sullivan, Epstein-Marden):**

There is a  $K$ -QC map  $\sigma : \Omega \rightarrow \text{Dome}$  so that  $\sigma = \text{Id}$  on  $\partial\Omega$ .

**Corollary:**  $\iota : \partial\Omega \rightarrow \partial\mathbb{D}$  extends  $K$ -QC to  $\Omega$ .

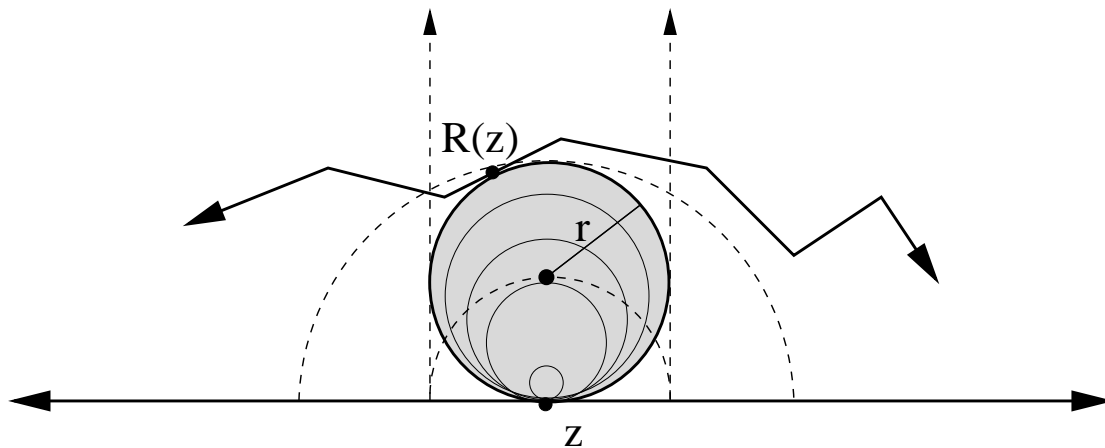
S-E-M theorem comes from hyperbolic 3-manifolds. If  $\Omega$  is invariant under Möbius group  $G$ ,  $M = \mathbb{R}_+^3/G$  is hyperbolic manifold,

$$\partial_\infty M = \Omega/G, \quad \partial C(M) = \text{Dome}(\Omega)/G.$$

Thurston conjectured  $K = 2$  is possible, but shown false by Epstein and Markovic. Best known upper bound is  $K < 7.82$ .

**Fact 1:** If  $z \in \Omega$ ,  $\infty \notin \Omega$ ,

$$r \simeq \text{dist}(z, \partial\Omega) \simeq \text{dist}(R(z), \mathbb{R}^2) \simeq |z - R(z)|.$$



**Fact 2:**  $R$  is Lipschitz.

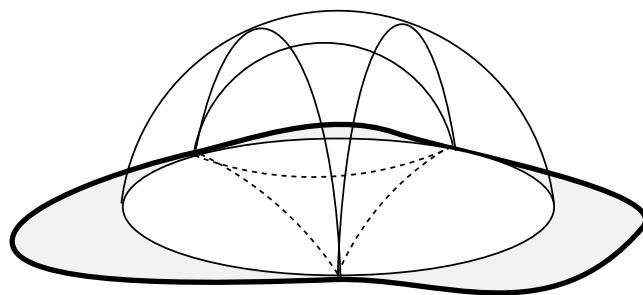
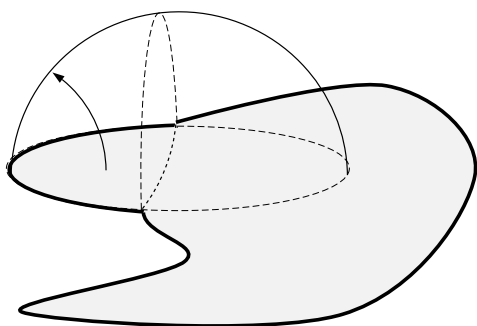
$\Omega$  simply connected  $\Rightarrow$

$$d\rho \simeq \frac{|dz|}{\text{dist}(z, \partial\Omega)}.$$

$z \in D \subset \Omega$  and  $R(z) \in \text{Dome}(D) \Rightarrow$

$$\text{dist}(z, \partial\Omega)/\sqrt{2} \leq \text{dist}(z, \partial D) \leq \text{dist}(z, \partial\Omega)$$

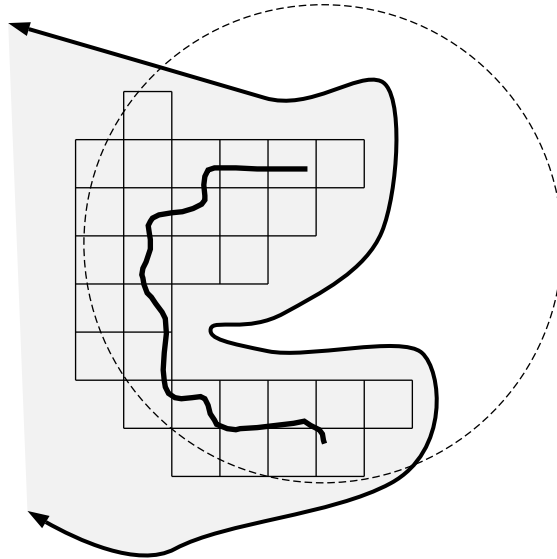
$$\Rightarrow d\rho_{\Omega}(z) \simeq d\rho_D(z) = d\rho_{\text{Dome}}(R(z)).$$



**Fact 3:**  $\rho_S(R(z), R(w)) \leq 1 \Rightarrow \rho_\Omega(z, w) \leq C$ .

Suppose  $\text{dist}(R(z), \mathbb{R}^2) = r$  and  $\gamma$  is geodesic from  $z$  to  $w$ .

$$\begin{aligned} \Rightarrow & \quad \text{dist}(\gamma, \mathbb{R}^2) \simeq r \\ \Rightarrow & \quad \text{dist}(R^{-1}(\gamma), \partial\Omega) \simeq r, \\ & \quad R^{-1}(\gamma) \subset D(z, Cr) \\ \Rightarrow & \quad \rho_\Omega(z, w) \leq C \end{aligned}$$



Moreover,  $g = \iota \circ \sigma : \Omega \rightarrow \mathbb{D}$  is locally Lipschitz. Standard estimates show

$$|g'(z)| \simeq \frac{\text{dist}(g(z), \partial\mathbb{D})}{\text{dist}(z, \partial\Omega)}.$$

Use Fact 1

$$\begin{aligned} \text{dist}(z, \partial\Omega) &\simeq \text{dist}(\sigma(z), \mathbb{R}^2) \\ &\simeq \exp(-\rho_{\mathbb{R}_+^3}(\sigma(z), z_0)) \\ &\gtrsim \exp(-\rho_S(\sigma(z), z_0)) \\ &= \exp(-\rho_D(g(z), 0)) \\ &\simeq \text{dist}(g(z), \partial D) \end{aligned}$$

