

Continue: Systems of 2 autonomous, 1st-order differential equations

and two-species interactions
 1 species population \leftrightarrow 1 autonomous eqn
 2 species population \leftrightarrow 2 interacted

Main Example: $R(t)$ = # rabbits at time t
 $W(t)$ = # wolves at time t

$$\begin{cases} \frac{dR}{dt} = \frac{1}{20}R - \frac{1}{500}RW \\ \frac{dW}{dt} = -\frac{1}{10}W + \frac{1}{1000}RW \end{cases} \quad (R, W) = (R(t), W(t))$$

$W=0$: $\frac{dR}{dt} = \frac{1}{20}R$ exponential growth eqn.
 \Rightarrow # of rabbits grows exponentially if no wolves

$$\frac{dR}{dt} = \frac{1}{20}R - \frac{1}{500}RW$$

wolves have negative effect on rabbits

$R=0$: $\frac{dW}{dt} = -\frac{1}{10}W$ exponential decay eqn.
 \Rightarrow # wolves decays to 0 if no rabbits

$$\frac{dW}{dt} = -\frac{1}{10}W + \frac{1}{1000}RW$$

rabbits have positive effect on wolves
 \therefore reasonable model for rabbits-wolves interaction

About solutions $(R, W) = (R(t), W(t))$ of the system

(1) What are the constant/equilibrium solutions?
 $(R, W) = (\text{const}, \text{const}) \Rightarrow \begin{cases} \frac{dR}{dt} = 0 \\ \frac{dW}{dt} = 0 \end{cases}$
 $\Rightarrow \begin{cases} \frac{1}{20}R(1 - \frac{1}{25}W) = 0 \\ -\frac{1}{10}W(1 - \frac{1}{100}R) = 0 \end{cases} \Rightarrow \begin{cases} R=0 \text{ or } W=25 \\ W=0 \text{ or } R=100 \end{cases}$



Constant solutions: $(R(t), W(t)) = (0, 0)$ for all t
 $(R(t), W(t)) = (100, 25)$

CAUTION: must choose 1 condition from each line of

$$\begin{cases} R=0 \text{ or } W=25 \\ W=0 \text{ or } R=100 \end{cases}$$

E.g. 1st line $R=0$ \nearrow $W=0$ 2nd line \searrow $R=100$
 $(W, R) = (25, 0)$ not a constant solution
 \leftarrow must pick something from 2nd line

Significance of constant solutions:

$(R, W) = (0, 0)$ no rabbits, no wolves
 $(R, W) = (100, 25)$ 100 rabbits precisely enough to support 25 wolves and be contained by them

Two ways to "graph solutions" $(R, W) = (R(t), W(t))$

(1) curve traced by $(R(t), W(t))$ as $t \rightarrow \infty$ in RW -plane
 \hookrightarrow phase trajectory

(2) graphs of $R=R(t)$ and $W=W(t)$ as functions of t
 with same t , but different R -axis, W -axis

Goal: sketch one from the other

Tip: ded. this for $(x(t), y(t)) = (2\cos t, 2\sin t)$

do not erase

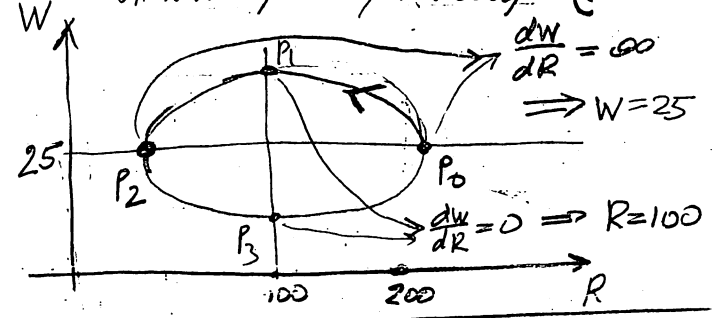
$(R, W) = (R(t), W(t))$ solution of the system
 traces some curve in RW -plane

Slope of curve at (R, W) :

$$\frac{dW}{dR} = \frac{dW/dt}{dR/dt} = \frac{-\frac{1}{10}W + \frac{1}{1000}RW}{\frac{1}{20}R - \frac{1}{500}RW} = -\frac{W(100-R)}{2R(25-W)}$$

separable equation \Rightarrow can solve (Problem F-(a))

get simple closed curves in 1st-quadrant
 of RW -plane, not ellipse (F-(b))



external left/right points on phase trajectory

$$\Leftrightarrow \frac{dW}{dR} = \infty \Leftrightarrow \frac{dR}{dt} = 0 \Leftrightarrow W = 25 \text{ in this case}$$

external up/down points

$$\Leftrightarrow \frac{dW}{dR} = 0 \Leftrightarrow \frac{dW}{dt} = 0 \Leftrightarrow R = 100 \text{ in this case}$$

Sketch graphs of $R=R(t)$ and $W=W(t)$

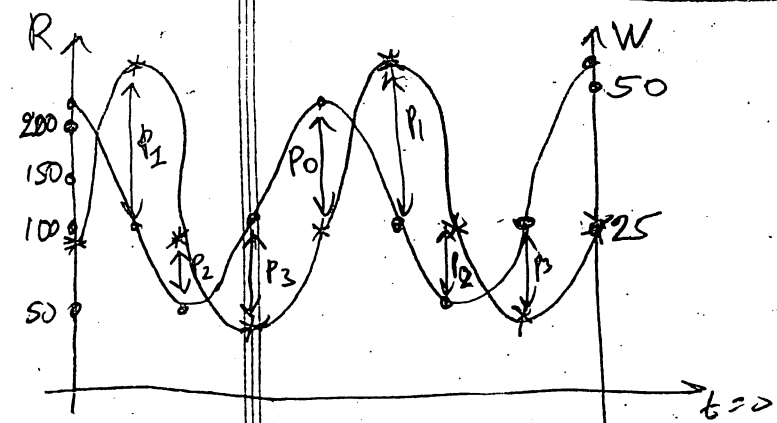
a) functions of time from phase trajectory

Key points on trajectory = turns in direction

$$P_0 = (220, 25) \quad P_1 = (100, 52)$$

$$P_2 = (50, 25) \quad P_3 = (100, 12)$$

then repeat; W -range = 50-220; R -range = 12-52



R : min/max $\Leftrightarrow W=25$; W : min/max $\Leftrightarrow R=100$

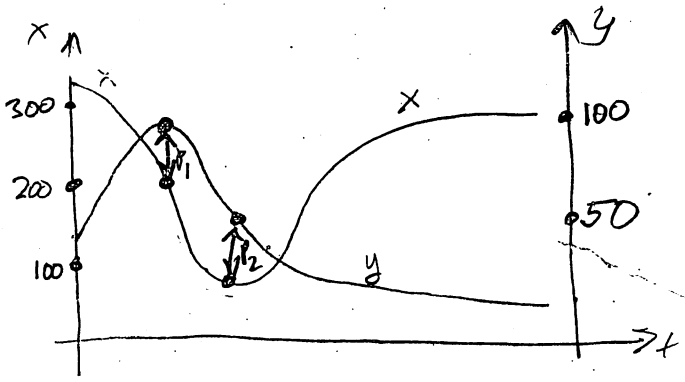
(1) Mark "external points"

(2) Connect R -points by smoothing
 going up or down only between nearby points
 Same for W -points

Caution: (1) Keep R and W points separate

(2) R -axis (and W -axis) may have different scales
(color check helps) \Rightarrow over

From graphs to phase trajectory



Important Points

Starting: $x=320, y=48 \rightarrow P_0 = (320, 48)$

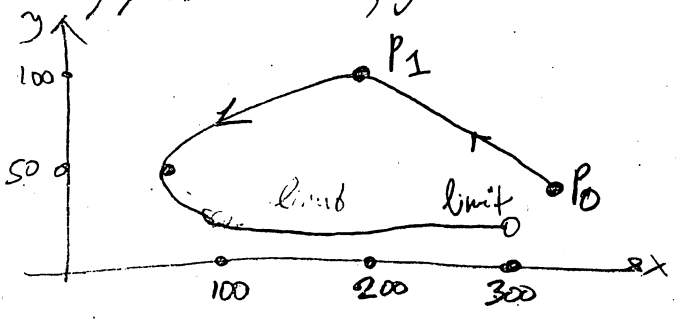
1st y-max: $x=200, y=100 \rightarrow P_1 = (200, 100)$

→ extremal top point

1st x-min: $x=80, y=50 \rightarrow P_2 = (80, 50)$

→ extremal left point

horizontal asymptotes: $x \rightarrow 100, y \rightarrow 20$



(1) mark extremal points, by dots but not the limit (just →)

(2) connect all by smooth curve in correct order (increasing t) without changing general direction between extremal points
 general direction = left & up, left & down, ...

101
55