

# Phase Transitions of Random Constraint Satisfaction Problems

Allan Sly, Princeton University

Stony Brook November 2019

Introduction:  
random constraint satisfaction problems;



## Combinatorics and Theoretical Computer Science

Constraint satisfaction problem (CSP): is it possible to assign values to a set of *variables* to satisfy a given set of *constraints*?

- Scheduling your appointments for the day
- System of linear equations.
- Colouring a graph or finding a large independent set.
- Satisfying a Boolean formula.

## Combinatorics and Theoretical Computer Science

Constraint satisfaction problem (CSP): is it possible to assign values to a set of *variables* to satisfy a given set of *constraints*?

- Scheduling your appointments for the day
- System of linear equations.
- Colouring a graph or finding a large independent set.
- Satisfying a Boolean formula.

## Random CSPs

Our focus is to investigate properties when the constraints are chosen randomly.

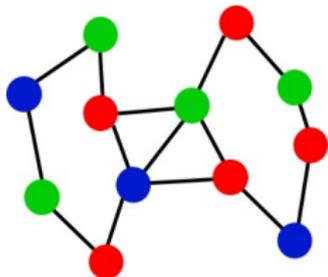
## Combinatorial properties of Random Graphs:

- Erdős-Rényi Random Graph:  $G(n, \alpha/n)$  with  $n$  vertices and edges with probability  $\alpha/n$  (average degree  $\alpha$ ).
- Random  $\alpha$ -regular graph: Uniformly chosen from  $\alpha$ -regular graphs on  $n$  vertices.

## Combinatorial properties of Random Graphs:

- Erdős-Rényi Random Graph:  $G(n, \alpha/n)$  with  $n$  vertices and edges with probability  $\alpha/n$  (average degree  $\alpha$ ).
- Random  $\alpha$ -regular graph: Uniformly chosen from  $\alpha$ -regular graphs on  $n$  vertices.

When is there a proper  $k$ -colouring?



**K-SAT** The random K-SAT problem, a model of a random Boolean formula, is perhaps the canonical random CSP.

**K-SAT** The random K-SAT problem, a model of a random Boolean formula, is perhaps the canonical random CSP.

**Basic Definition:**

Variables:  $x_1, \dots, x_n \in \{\text{TRUE}, \text{FALSE}\} \equiv \{+, -\}$

Constraints:  $m$  clauses taking the **OR** of  $k$  variables uniformly chosen from  $\{+x_1, -x_1, \dots, +x_n, -x_n\}$ .

**K-SAT** The random K-SAT problem, a model of a random Boolean formula, is perhaps the canonical random CSP.

### Basic Definition:

Variables:  $x_1, \dots, x_n \in \{\text{TRUE}, \text{FALSE}\} \equiv \{+, -\}$

Constraints:  $m$  clauses taking the OR of  $k$  variables uniformly chosen from  $\{+x_1, -x_1, \dots, +x_n, -x_n\}$ .

Example: A 3-SAT formula with 4 clauses:

$$\mathcal{G}(\underline{x}) = (+x_1 \text{ OR } +x_2 \text{ OR } -x_3) \text{ AND } \overbrace{(+x_3 \text{ OR } +x_4 \text{ OR } -x_5)}^{\text{clause}} \\ \text{AND } (-x_1 \text{ OR } -x_4 \text{ OR } +x_5) \text{ AND } (+x_2 \text{ OR } -x_3 \text{ OR } +x_4)$$

**K-SAT** The random K-SAT problem, a model of a random Boolean formula, is perhaps the canonical random CSP.

### Basic Definition:

Variables:  $x_1, \dots, x_n \in \{\text{TRUE}, \text{FALSE}\} \equiv \{+, -\}$

Constraints:  $m$  clauses taking the OR of  $k$  variables uniformly chosen from  $\{+x_1, -x_1, \dots, +x_n, -x_n\}$ .

Example: A 3-SAT formula with 4 clauses:

$$\mathcal{G}(x) = (+x_1 \text{ OR } +x_2 \text{ OR } -x_3) \text{ AND } \overbrace{(+x_3 \text{ OR } +x_4 \text{ OR } -x_5)}^{\text{clause}} \\ \text{AND } (-x_1 \text{ OR } -x_4 \text{ OR } +x_5) \text{ AND } (+x_2 \text{ OR } -x_3 \text{ OR } +x_4)$$

**Clause density:** The K-SAT model is parameterized the problem by the density of clauses  $\alpha = m/n$ .

**K-SAT** The random K-SAT problem, a model of a random Boolean formula, is perhaps the canonical random CSP.

### Basic Definition:

Variables:  $x_1, \dots, x_n \in \{\text{TRUE}, \text{FALSE}\} \equiv \{+, -\}$

Constraints:  $m$  clauses taking the OR of  $k$  variables uniformly chosen from  $\{+x_1, -x_1, \dots, +x_n, -x_n\}$ .

Example: A 3-SAT formula with 4 clauses:

$$\mathcal{G}(\underline{x}) = (+x_1 \text{ OR } +x_2 \text{ OR } -x_3) \text{ AND } \overbrace{(+x_3 \text{ OR } +x_4 \text{ OR } -x_5)}^{\text{clause}} \\ \text{AND } (-x_1 \text{ OR } -x_4 \text{ OR } +x_5) \text{ AND } (+x_2 \text{ OR } -x_3 \text{ OR } +x_4)$$

**Clause density:** The K-SAT model is parameterized the problem by the density of clauses  $\alpha = m/n$ .

**Variant NAE-SAT:** An assignment  $\underline{x}$  is a solution if both  $\underline{x}$  and  $-\underline{x}$  are satisfying.

**Graphical description:** We can encode a K-SAT formula as a bipartite hyper-graph:

**Graphical description:** We can encode a K-SAT formula as a bipartite hyper-graph:

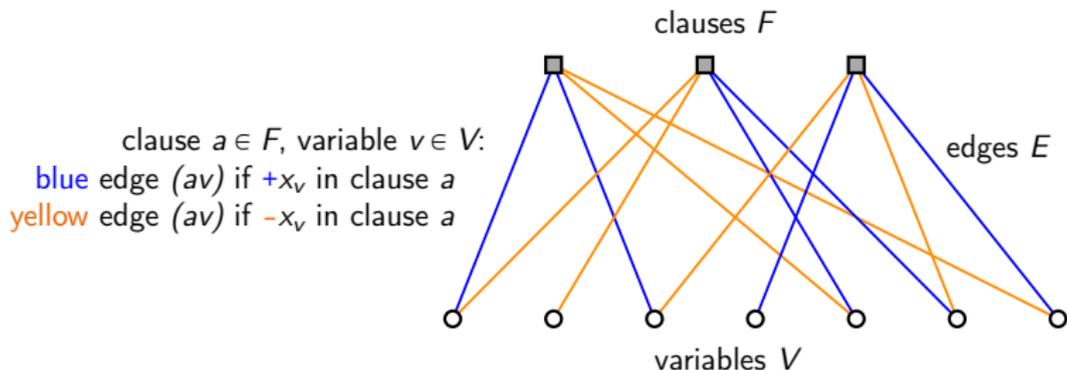
Take a 4-SAT formula with 3 clauses:  $\mathcal{G}(\underline{x}) =$

$$\begin{aligned} & (+x_1 \text{ OR } +x_3 \text{ OR } -x_5 \text{ OR } -x_7) \text{ AND } (-x_1 \text{ OR } -x_2 \text{ OR } +x_5 \text{ OR } +x_6) \\ & \text{AND } (-x_3 \text{ OR } +x_4 \text{ OR } -x_6 \text{ OR } +x_7) \end{aligned}$$

**Graphical description:** We can encode a K-SAT formula as a bipartite hyper-graph:

Take a 4-SAT formula with 3 clauses:  $\mathcal{G}(\underline{x}) =$   
 $(+x_1 \text{ OR } +x_3 \text{ OR } -x_5 \text{ OR } -x_7) \text{ AND } (-x_1 \text{ OR } -x_2 \text{ OR } +x_5 \text{ OR } +x_6)$   
 $\text{AND } (-x_3 \text{ OR } +x_4 \text{ OR } -x_6 \text{ OR } +x_7)$

We can encode the formula as a bipartite graph  $\mathcal{G} \equiv (V, F, E)$ :

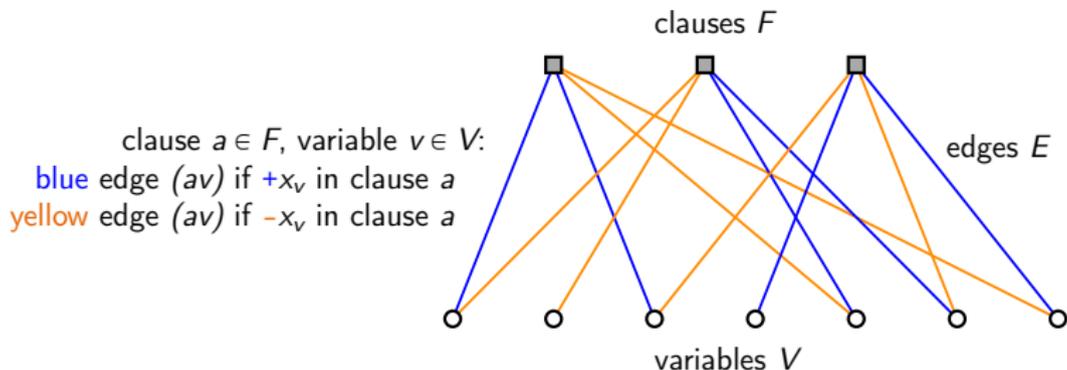


(4-SAT: each clause has degree 4)

**Graphical description:** We can encode a K-SAT formula as a bipartite hyper-graph:

Take a 4-SAT formula with 3 clauses:  $\mathcal{G}(\underline{x}) =$   
 $(+x_1 \text{ OR } +x_3 \text{ OR } -x_5 \text{ OR } -x_7) \text{ AND } (-x_1 \text{ OR } -x_2 \text{ OR } +x_5 \text{ OR } +x_6)$   
 $\text{AND } (-x_3 \text{ OR } +x_4 \text{ OR } -x_6 \text{ OR } +x_7)$

We can encode the formula as a bipartite graph  $\mathcal{G} \equiv (V, F, E)$ :



(4-SAT: each clause has degree 4)

The resulting random graph is locally tree-like, almost no short cycles and it's local distribution can be described completely.



## Main Question:

- *Satisfiability Threshold*: For which  $\alpha$  are there satisfying assignments?

## Main Question:

- *Satisfiability Threshold*: For which  $\alpha$  are there satisfying assignments?

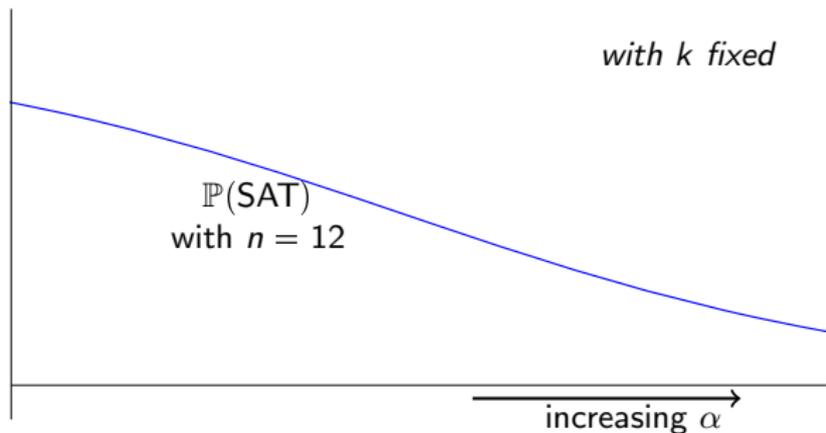
## Other Question:

- *Free Energy*: How many solutions are there?
- *Local Statistics*: Properties of solutions such as how many clauses are satisfied only once?
- *Algorithmic*: Can solutions be found efficiently?

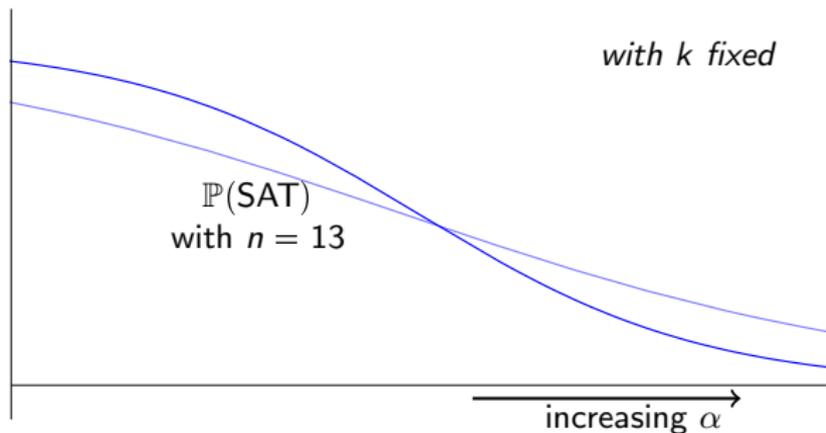


**The Satisfiability Conjecture.** *For each  $k \geq 2$ , random  $k$ -SAT has a sharp satisfiability threshold  $\alpha_{\text{sat}}$ .*

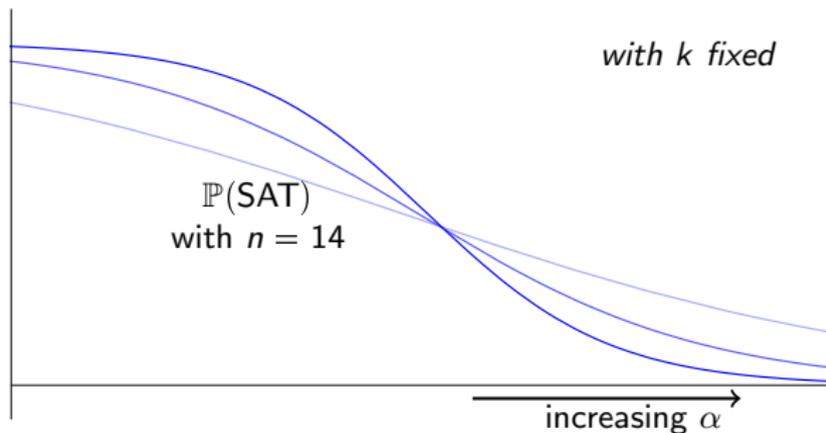
**The Satisfiability Conjecture.** For each  $k \geq 2$ ,  
random  $k$ -SAT has a sharp satisfiability threshold  $\alpha_{\text{sat}}$ .



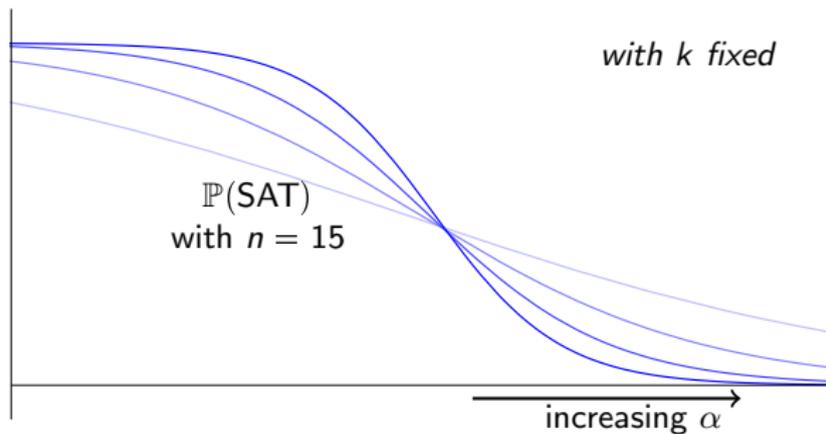
**The Satisfiability Conjecture.** For each  $k \geq 2$ , random  $k$ -SAT has a sharp satisfiability threshold  $\alpha_{\text{sat}}$ .



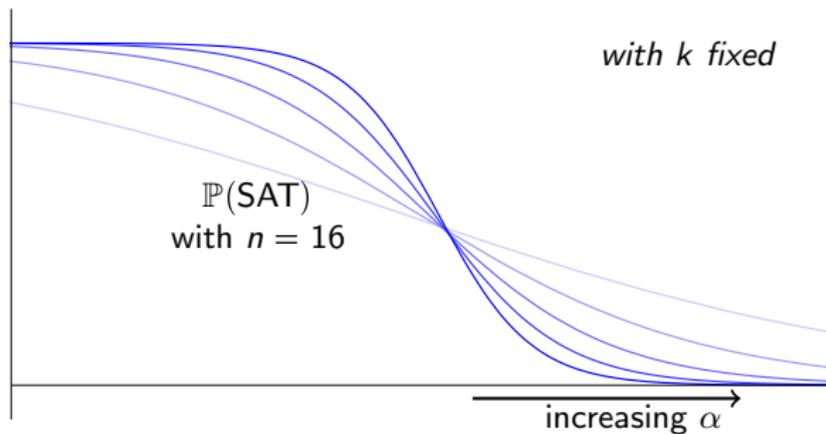
**The Satisfiability Conjecture.** For each  $k \geq 2$ , random  $k$ -SAT has a sharp satisfiability threshold  $\alpha_{\text{sat}}$ .



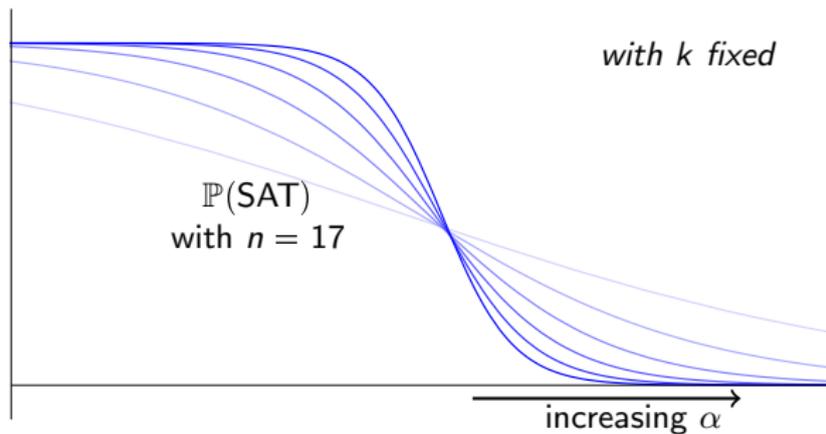
**The Satisfiability Conjecture.** For each  $k \geq 2$ , random  $k$ -SAT has a sharp satisfiability threshold  $\alpha_{\text{sat}}$ .



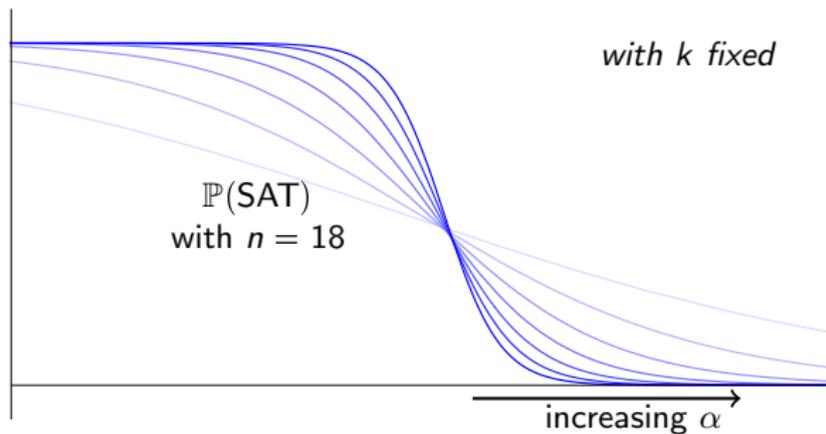
**The Satisfiability Conjecture.** For each  $k \geq 2$ , random  $k$ -SAT has a sharp satisfiability threshold  $\alpha_{\text{sat}}$ .



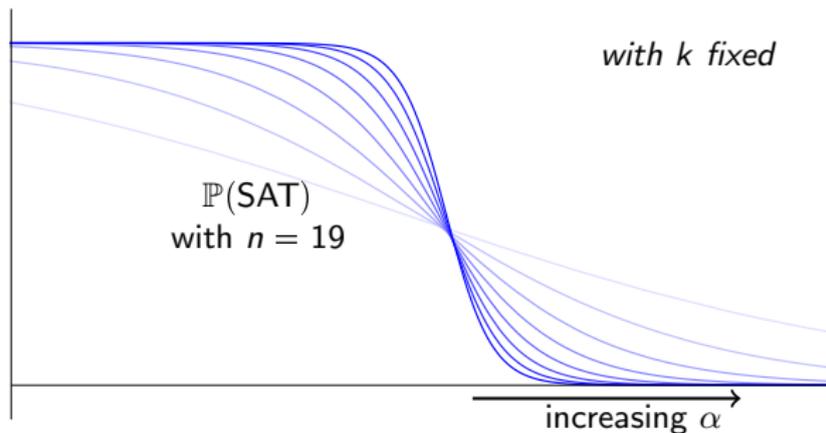
**The Satisfiability Conjecture.** For each  $k \geq 2$ , random  $k$ -SAT has a sharp satisfiability threshold  $\alpha_{\text{sat}}$ .



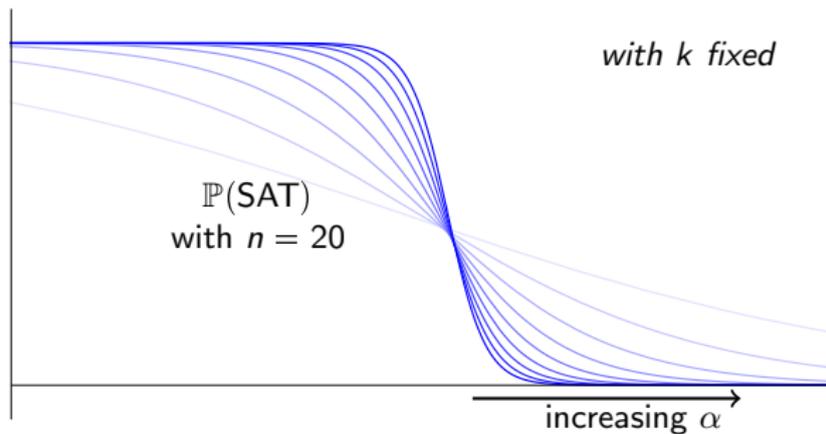
**The Satisfiability Conjecture.** For each  $k \geq 2$ , random  $k$ -SAT has a sharp satisfiability threshold  $\alpha_{\text{sat}}$ .



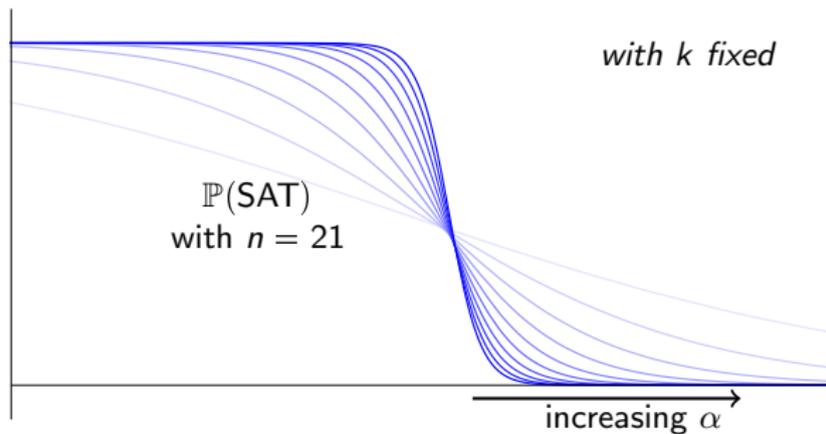
**The Satisfiability Conjecture.** For each  $k \geq 2$ , random  $k$ -SAT has a sharp satisfiability threshold  $\alpha_{\text{sat}}$ .



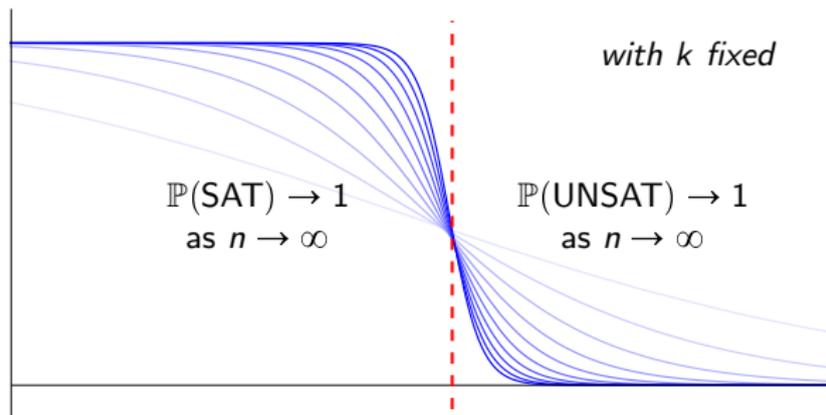
**The Satisfiability Conjecture.** For each  $k \geq 2$ , random  $k$ -SAT has a sharp satisfiability threshold  $\alpha_{\text{sat}}$ .



**The Satisfiability Conjecture.** For each  $k \geq 2$ , random  $k$ -SAT has a sharp satisfiability threshold  $\alpha_{\text{sat}}$ .

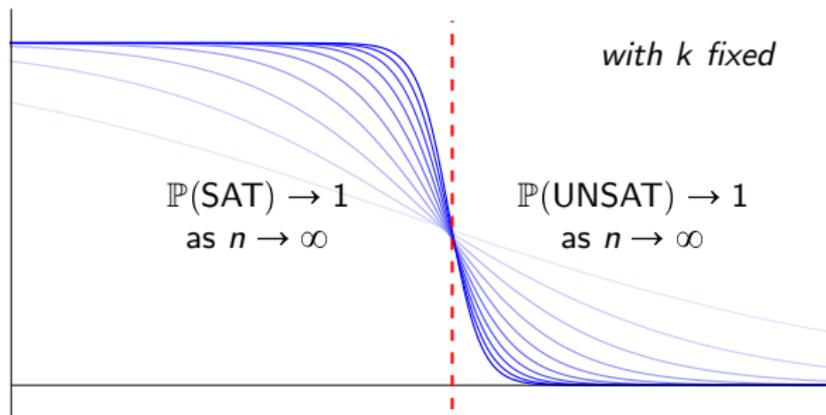


**The Satisfiability Conjecture.** For each  $k \geq 2$ , random  $k$ -SAT has a sharp satisfiability threshold  $\alpha_{\text{sat}}$ .



— that is, a single critical value  $\alpha_{\text{sat}}$  separates SAT|UNSAT  
(with high probability in the limit  $n \rightarrow \infty$ ; fixed  $k$ )

**The Satisfiability Conjecture.** For each  $k \geq 2$ , random  $k$ -SAT has a sharp satisfiability threshold  $\alpha_{\text{sat}}$ .

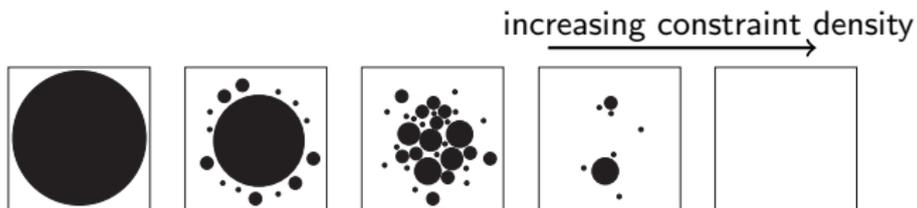


— that is, a single critical value  $\alpha_{\text{sat}}$  separates SAT|UNSAT  
 (with high probability in the limit  $n \rightarrow \infty$ ; fixed  $k$ )

For general  $k$ , Friedgut ('99) proved the transition sharpens around a (possibly non-convergent) *threshold sequence*  $\alpha_{\text{sat}}(n)$   
 (whereas conjecture requires  $\alpha_{\text{sat}}(n) \rightarrow \alpha_{\text{sat}}$  as  $n \rightarrow \infty$ )

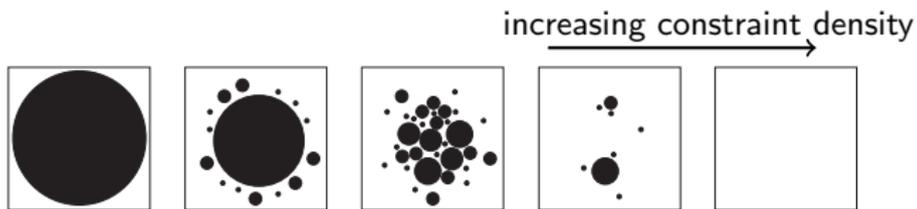
## Theoretical Physics

Disordered systems such as *spin glasses* are models of interacting particles/variables with frustrated interactions. Many random constraint satisfaction problems can be recast as dilute mean-field spin glasses.



## Theoretical Physics

Disordered systems such as *spin glasses* are models of interacting particles/variables with frustrated interactions. Many random constraint satisfaction problems can be recast as dilute mean-field spin glasses.



### One-step Replica Symmetry Breaking Predictions:

Developed to study dense spin-glasses such as the Sherrington-Kirkpatrick model.

- **Replica Symmetry Breaking:** Clustering of assignments.
- **Cavity Method:** Heuristic for analyzing adding one variable.



**First Moment method** on  $Z \equiv |\{\text{satisfying assignments of } \mathcal{G}\}|$ :

**First Moment method** on  $Z \equiv |\{\text{satisfying assignments of } \mathcal{G}\}|$ :

$$\mathbb{E}Z = 2^n(1 - 1/2^k)^m$$

**First Moment method** on  $Z \equiv |\{\text{satisfying assignments of } \mathcal{G}\}|$ :

$$\mathbb{E}Z = 2^n(1 - 1/2^k)^m = \exp\{n[\underbrace{\ln 2 + \alpha \log(1 - 1/2^k)}]\}$$

**First Moment method** on  $Z \equiv |\{\text{satisfying assignments of } \mathcal{G}\}|$ :

$$\mathbb{E}Z = 2^n(1 - 1/2^k)^m = \exp\{n[\underbrace{\ln 2 + \alpha \log(1 - 1/2^k)}]\}$$

exponent decreases in  $\alpha$ , crosses zero at  $\alpha_1 \approx 2^k \ln 2 + O(1)$

**First Moment method** on  $Z \equiv |\{\text{satisfying assignments of } \mathcal{G}\}|$ :

$$\mathbb{E}Z = 2^n (1 - 1/2^k)^m = \exp\{n \underbrace{[\ln 2 + \alpha \log(1 - 1/2^k)]}_{\text{exponent}}\}$$

exponent decreases in  $\alpha$ , crosses zero at  $\alpha_1 \approx 2^k \ln 2 + O(1)$

First moment threshold  $\alpha_1$  separates  $\mathbb{E}Z \rightarrow \infty$  |  $\mathbb{E}Z \rightarrow 0$ .

**First Moment method** on  $Z \equiv |\{\text{satisfying assignments of } \mathcal{G}\}|$ :

$$\mathbb{E}Z = 2^n (1 - 1/2^k)^m = \exp\{n \underbrace{[\ln 2 + \alpha \log(1 - 1/2^k)]}_{\text{exponent}}$$

exponent decreases in  $\alpha$ , crosses zero at  $\alpha_1 \approx 2^k \ln 2 + O(1)$

First moment threshold  $\alpha_1$  separates  $\mathbb{E}Z \rightarrow \infty$  |  $\mathbb{E}Z \rightarrow 0$ .

$\alpha_1 \neq \alpha_{\text{sat}}$ : At least  $\epsilon n$  unconstrained variables so  
 $Z > 0 \Rightarrow Z \geq 2^{\epsilon n}$ .

**First Moment method** on  $Z \equiv |\{\text{satisfying assignments of } \mathcal{G}\}|$ :

$$\mathbb{E}Z = 2^n (1 - 1/2^k)^m = \exp\{n \underbrace{[\ln 2 + \alpha \log(1 - 1/2^k)]}_{\text{exponent}}\}$$

exponent decreases in  $\alpha$ , crosses zero at  $\alpha_1 \approx 2^k \ln 2 + O(1)$

First moment threshold  $\alpha_1$  separates  $\mathbb{E}Z \rightarrow \infty$  |  $\mathbb{E}Z \rightarrow 0$ .

$\alpha_1 \neq \alpha_{\text{sat}}$ : At least  $\epsilon n$  unconstrained variables so  
 $Z > 0 \Rightarrow Z \geq 2^{\epsilon n}$ .

**Second Moment method:**

$$\mathbb{P}[Z > 0] \geq \frac{(\mathbb{E}Z)^2}{\mathbb{E}[Z^2]}$$

**First Moment method** on  $Z \equiv |\{\text{satisfying assignments of } \mathcal{G}\}|$ :

$$\mathbb{E}Z = 2^n(1 - 1/2^k)^m = \exp\{n[\ln 2 + \alpha \log(1 - 1/2^k)]\}$$

exponent decreases in  $\alpha$ , crosses zero at  $\alpha_1 \approx 2^k \ln 2 + O(1)$

First moment threshold  $\alpha_1$  separates  $\mathbb{E}Z \rightarrow \infty$  |  $\mathbb{E}Z \rightarrow 0$ .

$\alpha_1 \neq \alpha_{\text{sat}}$ : At least  $\epsilon n$  unconstrained variables so  
 $Z > 0 \Rightarrow Z \geq 2^{\epsilon n}$ .

**Second Moment method:**

$$\mathbb{P}[Z > 0] \geq \frac{(\mathbb{E}Z)^2}{\mathbb{E}[Z^2]}$$

To be useful, requires always  $\mathbb{E}[Z^2] \asymp (\mathbb{E}Z)^2$ . Fails, for **all**  $\alpha > 0$ .

**First Moment method** on  $Z \equiv |\{\text{satisfying assignments of } \mathcal{G}\}|$ :

$$\mathbb{E}Z = 2^n (1 - 1/2^k)^m = \exp\{n \underbrace{[\ln 2 + \alpha \log(1 - 1/2^k)]}_{\text{exponent decreases in } \alpha, \text{ crosses zero at } \alpha_1 \approx 2^k \ln 2 + O(1)}\}$$

exponent decreases in  $\alpha$ , crosses zero at  $\alpha_1 \approx 2^k \ln 2 + O(1)$

First moment threshold  $\alpha_1$  separates  $\mathbb{E}Z \rightarrow \infty$  |  $\mathbb{E}Z \rightarrow 0$ .

$\alpha_1 \neq \alpha_{\text{sat}}$ : At least  $\epsilon n$  unconstrained variables so  
 $Z > 0 \Rightarrow Z \geq 2^{\epsilon n}$ .

**Second Moment method:**

$$\mathbb{P}[Z > 0] \geq \frac{(\mathbb{E}Z)^2}{\mathbb{E}[Z^2]}$$

To be useful, requires always  $\mathbb{E}[Z^2] \asymp (\mathbb{E}Z)^2$ . Fails, for **all**  $\alpha > 0$ .

For random colourings and NAE-SAT, second moment method succeeds up to  $\alpha_2 = \alpha_{\text{sat}} - O(1)$ .

Some physics perspective:  
condensation and replica symmetry breaking



*Spin glasses* are marked by a prevalence of *frustrated interactions*  
— e.g. Sherrington Kirkpatrick spin-glass ('75): sample  $(g_{ij})_{i<j}$ ,  
standard  $N(0, 1)$  then use them to define

*Spin glasses* are marked by a prevalence of *frustrated interactions*  
— e.g. Sherrington Kirkpatrick spin-glass ('75): sample  $(g_{ij})_{i<j}$ ,  
standard  $N(0, 1)$  then use them to define

$$\mathbb{P}(\underline{x}) \cong \frac{1}{Z} \exp \left\{ \frac{\beta}{\sqrt{n}} \sum_{i<j} g_{ij} x_i x_j \right\}, \quad \underline{x} \in \{+1, -1\}^n$$

*Spin glasses* are marked by a prevalence of *frustrated interactions*  
— e.g. Sherrington Kirkpatrick spin-glass ('75): sample  $(g_{ij})_{i<j}$ ,  
standard  $N(0, 1)$  then use them to define

$$\mathbb{P}(\underline{x}) \cong \frac{1}{Z} \exp \left\{ \frac{\beta}{\sqrt{n}} \sum_{i<j} g_{ij} x_i x_j \right\}, \quad \underline{x} \in \{+1, -1\}^n$$

Some remarkable predictions proved for *dense* graphs

— e.g. for the SK spin-glass

Guerra '03, Talagrand '06: Parisi formula (conjecture: Parisi '79, '80)

Panchenko '11: Parisi ultrametricity (conjecture: Parisi '79, '80)

and for optimization on complete graphs with random edge weights:

Aldous '00: random assignment (conjecture: Mézard–Parisi '85, '86, '87)

Frieze '02, Wästlund '10: TSP (conjecture: Mézard–Parisi '86, Krauth–Mézard '89)

*Spin glasses* are marked by a prevalence of *frustrated interactions* — e.g. Sherrington Kirkpatrick spin-glass ('75): sample  $(g_{ij})_{i<j}$ , standard  $N(0, 1)$  then use them to define

$$\mathbb{P}(\underline{x}) \cong \frac{1}{Z} \exp \left\{ \frac{\beta}{\sqrt{n}} \sum_{i<j} g_{ij} x_i x_j \right\}, \quad \underline{x} \in \{+1, -1\}^n$$

Some remarkable predictions proved for *dense* graphs

— e.g. for the SK spin-glass

Guerra '03, Talagrand '06: Parisi formula (conjecture: Parisi '79, '80)

Panchenko '11: Parisi ultrametricity (conjecture: Parisi '79, '80)

and for optimization on complete graphs with random edge weights:

Aldous '00: random assignment (conjecture: Mézard–Parisi '85, '86, '87)

Frieze '02, Wästlund '10: TSP (conjecture: Mézard–Parisi '86, Krauth–Mézard '89)

More recently a set of predictions for *sparse* random systems

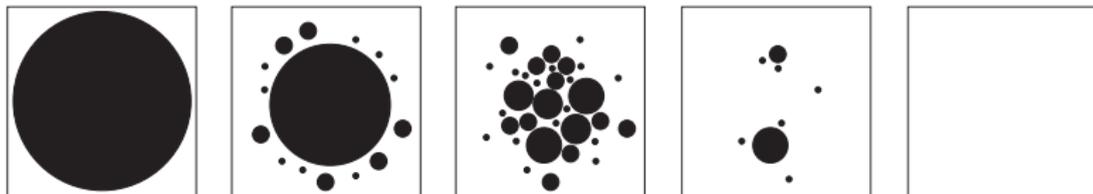
emerged:

Krzakała–Montanari–Ricci–Tersenghi–Semerjian–Zdeborová '07,

Montanari–Ricci–Tersenghi–Semerjian '08

# Phase Diagram

Two solutions are connected if they differ by one bit.

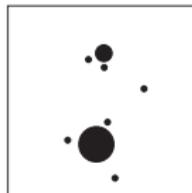
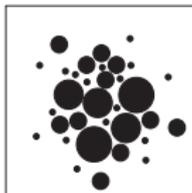
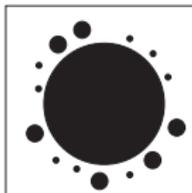
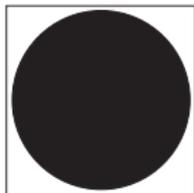


→  
increasing  $\alpha$

KMRSZ '07, MRS '08

# Phase Diagram

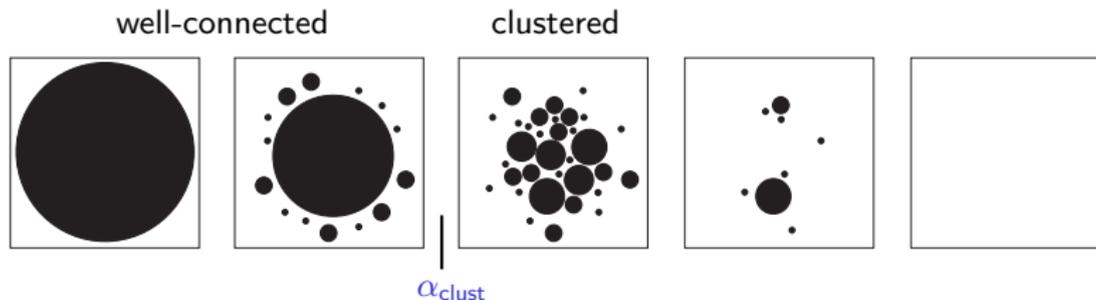
well-connected



KMRSZ '07, MRS '08

The solution space **SOL** starts out as a well-connected cluster.

# Phase Diagram



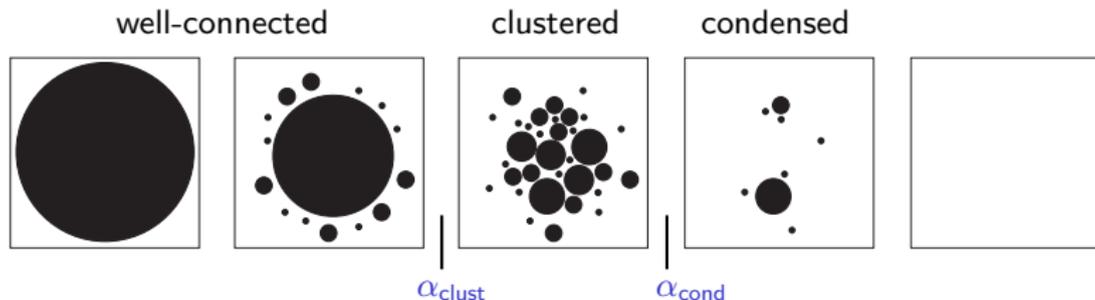
KMRSZ '07, MRS '08

The solution space **SOL** starts out as a well-connected cluster.

After  $\alpha_{\text{clust}}$ , **SOL** decomposes into exponentially clusters

–Clustering Achlioptas, Coja-Oghlan '10

# Phase Diagram



KMRSZ '07, MRS '08

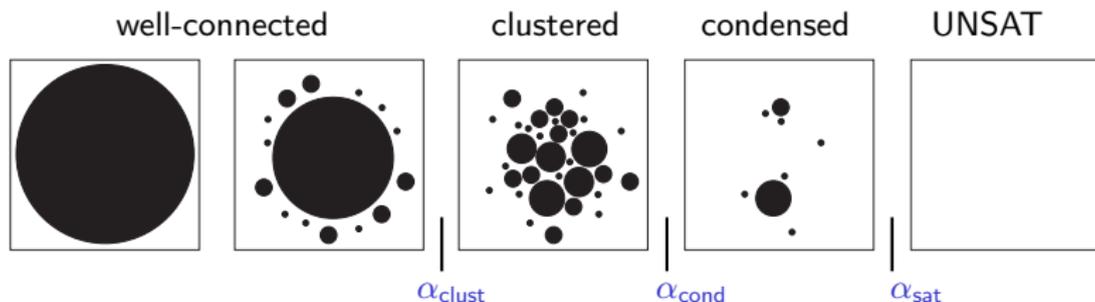
The solution space **SOL** starts out as a well-connected cluster.

After  $\alpha_{\text{clust}}$ , **SOL** decomposes into exponentially clusters

–Clustering Achlioptas, Coja-Oghlan '10

After  $\alpha_{\text{cond}}$ , **SOL** is dominated by a few large clusters

# Phase Diagram



KMRSZ '07, MRS '08

The solution space **SOL** starts out as a well-connected cluster.

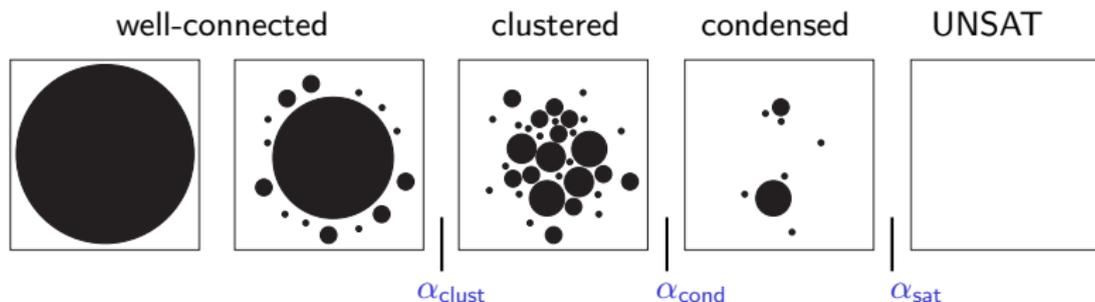
After  $\alpha_{\text{clust}}$ , **SOL** decomposes into exponentially clusters

–Clustering Achlioptas, Coja-Oghlan '10

After  $\alpha_{\text{cond}}$ , **SOL** is dominated by a few large clusters

After  $\alpha_{\text{sat}}$ , no solutions w.h.p.

# Phase Diagram



KMRSZ '07, MRS '08

The solution space **SOL** starts out as a well-connected cluster.

After  $\alpha_{\text{clust}}$ , **SOL** decomposes into exponentially clusters

–Clustering Achlioptas, Coja-Oghlan '10

After  $\alpha_{\text{cond}}$ , **SOL** is dominated by a few large clusters

After  $\alpha_{\text{sat}}$ , no solutions w.h.p.

**RSB:** The **one step replica symmetry breaking (1RSB)** heuristic roughly says there is no extra structure at the cluster level and decay of correlation.

**Cluster Model:** We represent clusters as a new spin system on  $V(\mathcal{G})$ .

**Cluster Model:** We represent clusters as a new spin system on  $V(\mathcal{G})$ .

- Start from  $\underline{x} \in \{+, -\}^{V(\mathcal{G})}$  and explore the cluster  $\mathcal{C}$ .

**Cluster Model:** We represent clusters as a new spin system on  $V(\mathcal{G})$ .

- Start from  $\underline{x} \in \{+, -\}^{V(\mathcal{G})}$  and explore the cluster  $\mathcal{C}$ .
- If a spin can be flipped between  $+$  and  $-$  without violating any clauses it is set to  $\mathbf{f}$ .
- Iterate until done.

**Cluster Model:** We represent clusters as a new spin system on  $V(\mathcal{G})$ .

- Start from  $\underline{x} \in \{+, -\}^{V(\mathcal{G})}$  and explore the cluster  $\mathcal{C}$ .
- If a spin can be flipped between  $+$  and  $-$  without violating any clauses it is set to  $\mathbf{f}$ .
- Iterate until done.
- Each variable is mapped to a value from  $\{+, -, \mathbf{f}\}$ .

**Cluster Model:** We represent clusters as a new spin system on  $V(\mathcal{G})$ .

- Start from  $\underline{x} \in \{+, -\}^{V(\mathcal{G})}$  and explore the cluster  $\mathcal{C}$ .
- If a spin can be flipped between  $+$  and  $-$  without violating any clauses it is set to  $\mathbf{f}$ .
- Iterate until done.
- Each variable is mapped to a value from  $\{+, -, \mathbf{f}\}$ .

This resulting configuration on  $\{+, -, \mathbf{f}\}^{V(\mathcal{G})}$  is our definition of a cluster. It is a spin system satisfying the following conditions:

- $\mathbf{f}$  are not forced by any clause.
- $+$  and  $-$  variables must be forced by at least one clause.
- No violated clause.

**Cluster Model:** We represent clusters as a new spin system on  $V(\mathcal{G})$ .

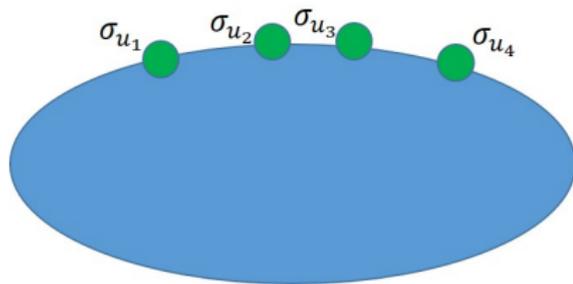
- Start from  $\underline{x} \in \{+, -\}^{V(\mathcal{G})}$  and explore the cluster  $\mathcal{C}$ .
- If a spin can be flipped between  $+$  and  $-$  without violating any clauses it is set to  $\mathbf{f}$ .
- Iterate until done.
- Each variable is mapped to a value from  $\{+, -, \mathbf{f}\}$ .

This resulting configuration on  $\{+, -, \mathbf{f}\}^{V(\mathcal{G})}$  is our definition of a cluster. It is a spin system satisfying the following conditions:

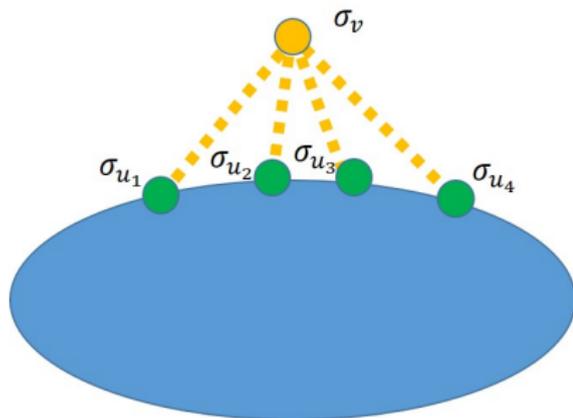
- $\mathbf{f}$  are not forced by any clause.
- $+$  and  $-$  variables must be forced by at least one clause.
- No violated clause.

We call this the cluster model. Let  $\Omega_n$  be the number of  $\{+, -, \mathbf{f}\}^{V(\mathcal{G})}$  configurations. Locally rigid resulting in no clustering.

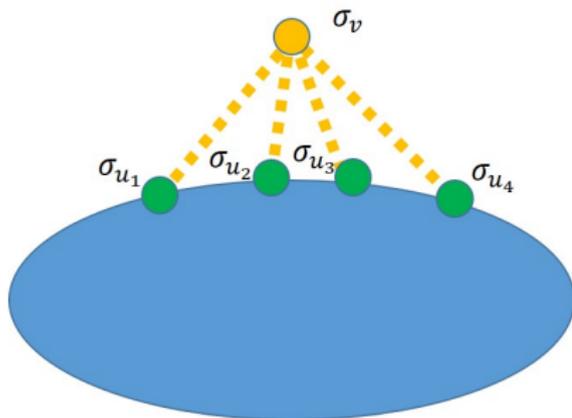
**Cavity Method:** Adding a new vertex  $v$  (or clause).



**Cavity Method:** Adding a new vertex  $v$  (or clause).



**Cavity Method:** Adding a new vertex  $v$  (or clause).

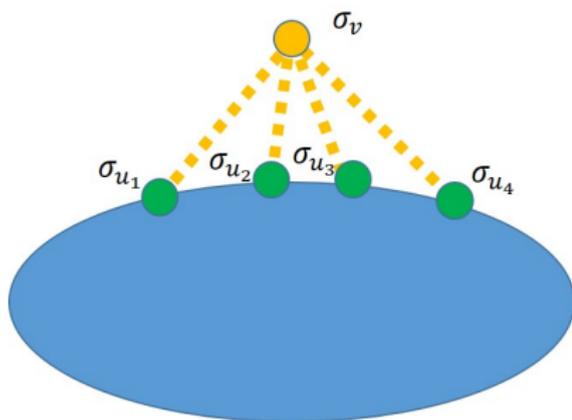


If we know the joint distribution of  $\sigma_{u_i}$  we can:

- 1 Calculate the law of  $\sigma_v$
- 2 Evaluate the change in the partition function from  $Z_{n+1}/Z_n$ .

Write  $\log Z_n = \sum_{i=1}^n \log Z_i/Z_{i-1}$ .

**Cavity Method:** Adding a new vertex  $v$  (or clause).



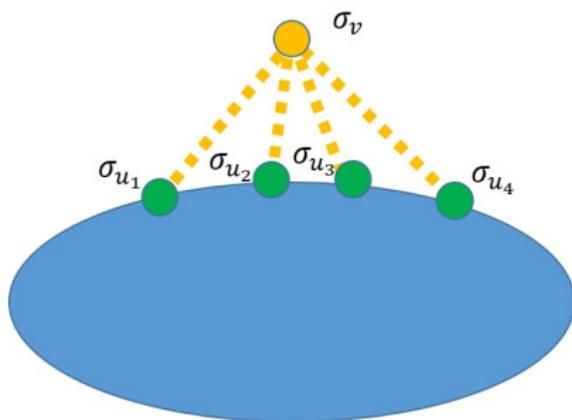
If we know the joint distribution of  $\sigma_{u_i}$  we can:

- 1 Calculate the law of  $\sigma_v$
- 2 Evaluate the change in the partition function from  $Z_{n+1}/Z_n$ .

Write  $\log Z_n = \sum_{i=1}^n \log Z_i/Z_{i-1}$ .

The **Replica Symmetric** heuristic assumes that  $\sigma_{u_i}$  are independent drawn from some law  $\mu$ .

**Cavity Method:** Adding a new vertex  $v$  (or clause).



If we know the joint distribution of  $\sigma_{u_i}$  we can:

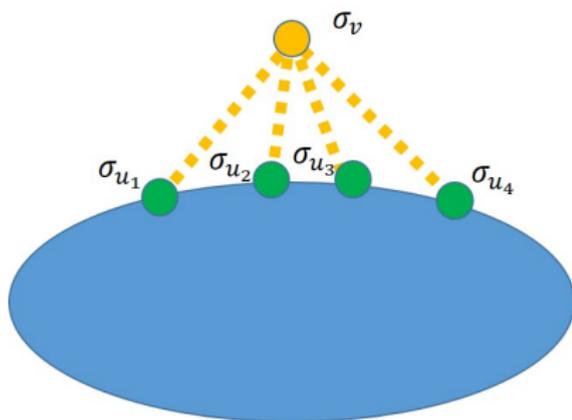
- 1 Calculate the law of  $\sigma_v$
- 2 Evaluate the change in the partition function from  $Z_{n+1}/Z_n$ .

Write  $\log Z_n = \sum_{i=1}^n \log Z_i/Z_{i-1}$ .

The **Replica Symmetric** heuristic assumes that  $\sigma_{u_i}$  are independent drawn from some law  $\mu$ .

The **1-RSB** heuristic assumes this for the cluster model.

**Cavity Method:** Adding a new vertex  $v$  (or clause).



If we know the joint distribution of  $\sigma_{u_i}$  we can:

- 1 Calculate the law of  $\sigma_v$
- 2 Evaluate the change in the partition function from  $Z_{n+1}/Z_n$ .

Write  $\log Z_n = \sum_{i=1}^n \log Z_i/Z_{i-1}$ .

The **Replica Symmetric** heuristic assumes that  $\sigma_{u_i}$  are independent drawn from some law  $\mu$ .

The **1-RSB** heuristic assumes this for the cluster model.

**Self-consistency:** The law of  $\sigma_v$  should also be drawn from  $\mu$  which means  $\mu$  must satisfy a fixed point equation.

## Explicit formula ( $k \geq 3$ )

**Explicit formula ( $k \geq 3$ )** Let  $\mathcal{P} \equiv$  space of probability measures on  $[0, 1]$ . Define the distributional recursion  $R_\alpha : \mathcal{P} \rightarrow \mathcal{P}$ ,

$$R_\alpha \mu(B) \equiv \sum_{\underline{d} \equiv (d^+, d^-)} \pi_\alpha(\underline{d}) \int \mathbf{1} \left\{ \frac{(1 - \pi^-) \pi^+}{\pi^+ + \pi^- - \pi^+ \pi^-} \in B \right\} \prod_{i,j} d\mu(\eta_{ij}^\pm)$$

$$\text{with } \pi_\alpha(\underline{d}) \equiv \frac{e^{-k\alpha} (k\alpha/2)^{d^+ + d^-}}{(d^+)! (d^-)!}, \quad \pi^\pm \equiv \pi^\pm(\underline{d}, \eta) \equiv \prod_{i=1}^{d^\pm} \left( 1 - \prod_{j=1}^{k-1} \eta_{ij}^\pm \right)$$

We show  $(R_\alpha)^\ell \mathbf{1}_{1/2} \xrightarrow{\ell \rightarrow \infty} \mu_\alpha$ .

*Distributional equation for the chance of being + in a random cluster.*

**Explicit formula ( $k \geq 3$ )** Let  $\mathcal{P} \equiv$  space of probability measures on  $[0, 1]$ . Define the distributional recursion  $R_\alpha : \mathcal{P} \rightarrow \mathcal{P}$ ,

$$R_\alpha \mu(B) \equiv \sum_{\underline{d} \equiv (d^+, d^-)} \pi_\alpha(\underline{d}) \int \mathbf{1} \left\{ \frac{(1 - \pi^-) \pi^+}{\pi^+ + \pi^- - \pi^+ \pi^-} \in B \right\} \prod_{i,j} d\mu(\eta_{ij}^\pm)$$

$$\text{with } \pi_\alpha(\underline{d}) \equiv \frac{e^{-k\alpha} (k\alpha/2)^{d^+ + d^-}}{(d^+)! (d^-)!}, \quad \pi^\pm \equiv \pi^\pm(\underline{d}, \eta) \equiv \prod_{i=1}^{d^\pm} \left( 1 - \prod_{j=1}^{k-1} \eta_{ij}^\pm \right)$$

We show  $(R_\alpha)^\ell \mathbf{1}_{1/2} \xrightarrow{\ell \rightarrow \infty} \mu_\alpha$ .

*Distributional equation for the chance of being + in a random cluster.*

Define

$$\begin{aligned} \Phi(\alpha) = & \sum_{\underline{d}} \pi_\alpha(\underline{d}) \int \ln \left( \pi^+ + \pi^- - \pi^+ \pi^- \right) \prod_j d\mu_\alpha(\eta_j) \prod_{i,j} d\mu_\alpha(\eta_{ij}^\pm) \\ & - \alpha(k-1) \int \ln \left( 1 - \prod_{j=1}^k \eta_j \right) \prod_j d\mu_\alpha(\eta_j) \prod_{i,j} d\mu_\alpha(\eta_{ij}^\pm) \end{aligned}$$

*Expected change in  $\log \Omega_n$  to  $\log \Omega_{n+1}$ .*

**Explicit formula ( $k \geq 3$ )** Let  $\mathcal{P} \equiv$  space of probability measures on  $[0, 1]$ . Define the distributional recursion  $R_\alpha : \mathcal{P} \rightarrow \mathcal{P}$ ,

$$R_\alpha \mu(B) \equiv \sum_{\underline{d} \equiv (d^+, d^-)} \pi_\alpha(\underline{d}) \int \mathbf{1} \left\{ \frac{(1 - \pi^-) \pi^+}{\pi^+ + \pi^- - \pi^+ \pi^-} \in B \right\} \prod_{i,j} d\mu(\eta_{ij}^\pm)$$

with  $\pi_\alpha(\underline{d}) \equiv \frac{e^{-k\alpha} (k\alpha/2)^{d^+ + d^-}}{(d^+)!(d^-)!}$ ,  $\pi^\pm \equiv \pi^\pm(\underline{d}, \eta) \equiv \prod_{i=1}^{d^\pm} \left( 1 - \prod_{j=1}^{k-1} \eta_{ij}^\pm \right)$

We show  $(R_\alpha)^\ell \mathbf{1}_{1/2} \xrightarrow{\ell \rightarrow \infty} \mu_\alpha$ .

*Distributional equation for the chance of being + in a random cluster.*

Define

$$\begin{aligned} \Phi(\alpha) = & \sum_{\underline{d}} \pi_\alpha(\underline{d}) \int \ln \left( \pi^+ + \pi^- - \pi^+ \pi^- \right) \prod_j d\mu_\alpha(\eta_j) \prod_{i,j} d\mu_\alpha(\eta_{ij}^\pm) \\ & - \alpha(k-1) \int \ln \left( 1 - \prod_{j=1}^k \eta_j \right) \prod_j d\mu_\alpha(\eta_j) \prod_{i,j} d\mu_\alpha(\eta_{ij}^\pm) \end{aligned}$$

*Expected change in  $\log \Omega_n$  to  $\log \Omega_{n+1}$ .*

Then the 1RSB prediction  $\alpha_{\text{sat}} \approx 2^k \ln 2 - (1 + \ln 2)/2$  is the root of  $\Phi(\alpha) = 0$ .

**Previous Bounds:** Satisfiability conjecture is known in special case  $k = 2$ , with  $\alpha_{\text{sat}} = 1$

Goerdt '92, '96, Chvátal–Reed '92, de la Vega '92

**Previous Bounds:** Satisfiability conjecture is known in special case  $k = 2$ , with  $\alpha_{\text{sat}} = 1$

Goerdts '92, '96, Chvátal–Reed '92, de la Vega '92

Bounds for  $k \geq 3$ :

$(\epsilon_k \rightarrow 0 \text{ as } k \rightarrow \infty)$

**Previous Bounds:** Satisfiability conjecture is known in special case  $k = 2$ , with  $\alpha_{\text{sat}} = 1$

Goerdt '92, '96, Chvátal–Reed '92, de la Vega '92

Bounds for  $k \geq 3$ :

( $\epsilon_k \rightarrow 0$  as  $k \rightarrow \infty$ )

	bound on threshold	gap	
$\alpha_{\text{sat}} \leq$	$2^k \ln 2 - (\ln 2)/2 + \epsilon_k$	$O(1)$	trivial

**Previous Bounds:** Satisfiability conjecture is known in special case  $k = 2$ , with  $\alpha_{\text{sat}} = 1$

Goerdt '92, '96, Chvátal–Reed '92, de la Vega '92

Bounds for  $k \geq 3$ :

( $\epsilon_k \rightarrow 0$  as  $k \rightarrow \infty$ )

	bound on threshold	gap	
$\alpha_{\text{sat}} \leq$	$2^k \ln 2 - (\ln 2)/2 + \epsilon_k$	$O(1)$	trivial
	$2^k \ln 2 - (1 + \ln 2)/2 + \epsilon_k$	$\epsilon_k$	Kirousis et al. '98

**Previous Bounds:** Satisfiability conjecture is known in special case  $k = 2$ , with  $\alpha_{\text{sat}} = 1$

Goerdt '92, '96, Chvátal–Reed '92, de la Vega '92

Bounds for  $k \geq 3$ :

( $\epsilon_k \rightarrow 0$  as  $k \rightarrow \infty$ )

	bound on threshold	gap	
$\alpha_{\text{sat}} \leq$	$2^k \ln 2 - (\ln 2)/2 + \epsilon_k$	$O(1)$	trivial
	$2^k \ln 2 - (1 + \ln 2)/2 + \epsilon_k$	$\epsilon_k$	Kirousis et al. '98
$\alpha_{\text{sat}} \geq$	( <i>algorithmic</i> ) $1.817 \cdot 2^k/k$	$2^k \ln 2$	Frieze–Suen '96
	( <i>algorithmic</i> ) $2^k (\ln k)/k$	$2^k \ln 2$	Coja-Oghlan '10

**Previous Bounds:** Satisfiability conjecture is known in special case  $k = 2$ , with  $\alpha_{\text{sat}} = 1$

Goerdt '92, '96, Chvátal–Reed '92, de la Vega '92

Bounds for  $k \geq 3$ :

( $\epsilon_k \rightarrow 0$  as  $k \rightarrow \infty$ )

	bound on threshold	gap	
$\alpha_{\text{sat}} \leq$	$2^k \ln 2 - (\ln 2)/2 + \epsilon_k$	$O(1)$	trivial
	$2^k \ln 2 - (1 + \ln 2)/2 + \epsilon_k$	$\epsilon_k$	Kirousis et al. '98
$\alpha_{\text{sat}} \geq$	<i>(algorithmic)</i> $1.817 \cdot 2^k/k$	$2^k \ln 2$	Frieze–Suen '96
	<i>(algorithmic)</i> $2^k (\ln k)/k$	$2^k \ln 2$	Coja-Oghlan '10
	$2^{k-1} \ln 2 - O(1)$	$2^{k-1} \ln 2$	Achlioptas–Moore '02
	$2^k \ln 2 - O(k)$	$O(k)$	Achlioptas–Peres '03
	$2^k \ln 2 - 3(\ln 2)/2 - \epsilon_k$	$O(1)$	Coja-Oghlan–
	$2^k \ln 2 - (1 + \ln 2)/2 - \epsilon_k$	$\epsilon_k$	–Panagiotou '13, '14

**Previous Bounds:** Satisfiability conjecture is known in special case  $k = 2$ , with  $\alpha_{\text{sat}} = 1$

Goerdt '92, '96, Chvátal–Reed '92, de la Vega '92

Bounds for  $k \geq 3$ :

( $\epsilon_k \rightarrow 0$  as  $k \rightarrow \infty$ )

	bound on threshold	gap	
$\alpha_{\text{sat}} \leq$	$2^k \ln 2 - (\ln 2)/2 + \epsilon_k$	$O(1)$	trivial
	$2^k \ln 2 - (1 + \ln 2)/2 + \epsilon_k$	$\epsilon_k$	Kirousis et al. '98
$\alpha_{\text{sat}} \geq$	<i>(algorithmic)</i> $1.817 \cdot 2^k/k$	$2^k \ln 2$	Frieze–Suen '96
	<i>(algorithmic)</i> $2^k (\ln k)/k$	$2^k \ln 2$	Coja-Oghlan '10
	$2^{k-1} \ln 2 - O(1)$	$2^{k-1} \ln 2$	Achlioptas–Moore '02
	$2^k \ln 2 - O(k)$	$O(k)$	Achlioptas–Peres '03
	$2^k \ln 2 - 3(\ln 2)/2 - \epsilon_k$	$O(1)$	Coja-Oghlan–
	$2^k \ln 2 - (1 + \ln 2)/2 - \epsilon_k$	$\epsilon_k$	–Panagiotou '13, '14
$\alpha_{\text{sat}} =$	$\alpha_* (k \geq k_0)$	$0 (k \geq k_0)$	exact threshold

---

**Theorem.** (Ding, S., Sun) *For  $k \geq k_0$  (absolute constant), random  $k$ -SAT has a sharp satisfiability threshold, with explicit value  $\alpha_{\text{sat}} = \alpha_*$  matching the one-step replica symmetry breaking prediction of Mertens–Mézard–Zecchina '06.*

---

Beyond the Satisfiability Threshold

## Condensation

Complexity function  $\Sigma \equiv \Sigma_\alpha(s)$  such that:

$$\mathbb{E}Z = \sum \underbrace{(\text{cluster size})}_{\exp\{ns\}} \times \underbrace{\mathbb{E}[\text{number of clusters of that size}]}_{\exp\{n\Sigma(s)\}}$$

## Condensation

Complexity function  $\Sigma \equiv \Sigma_\alpha(s)$  such that:

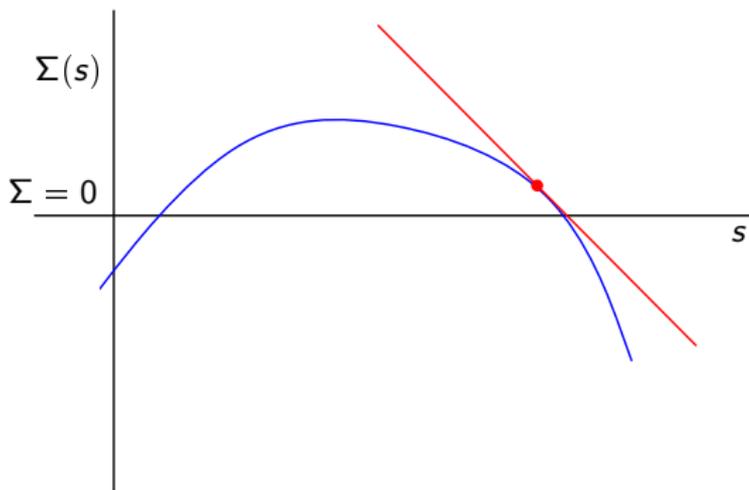
$$\mathbb{E}Z = \sum \underbrace{(\text{cluster size})}_{\exp\{ns\}} \times \underbrace{\mathbb{E}[\text{number of clusters of that size}]}_{\exp\{n\Sigma(s)\}}$$

## Condensation

Complexity function  $\Sigma \equiv \Sigma_\alpha(s)$  such that:

$$\mathbb{E}Z = \sum \underbrace{(\text{cluster size})}_{\exp\{ns\}} \times \underbrace{\mathbb{E}[\text{number of clusters of that size}]}_{\exp\{n\Sigma(s)\}}$$

$\mathbb{E}Z$  is dominated by  $s$  where  $\Sigma'(s) \equiv -1$  (depending on  $\alpha$ ).

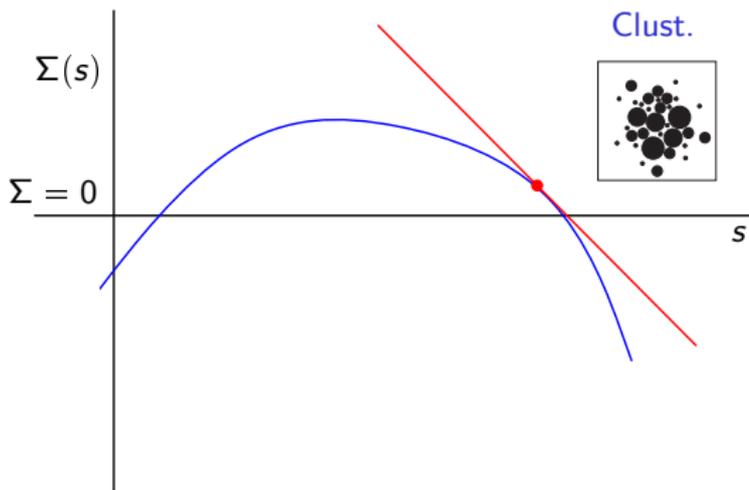


## Condensation

Complexity function  $\Sigma \equiv \Sigma_\alpha(s)$  such that:

$$\mathbb{E}Z = \sum \underbrace{(\text{cluster size})}_{\exp\{ns\}} \times \underbrace{\mathbb{E}[\text{number of clusters of that size}]}_{\exp\{n\Sigma(s)\}}$$

$\mathbb{E}Z$  is dominated by  $s$  where  $\Sigma'(s) \equiv -1$  (depending on  $\alpha$ ).

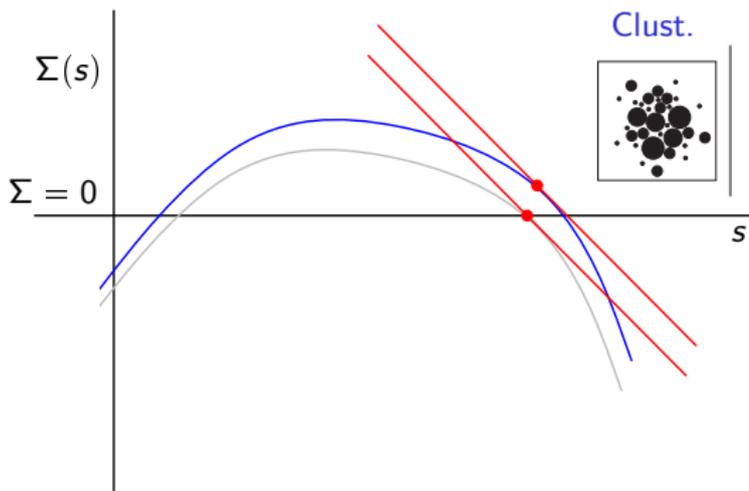


## Condensation

Complexity function  $\Sigma \equiv \Sigma_\alpha(s)$  such that:

$$\mathbb{E}Z = \sum \underbrace{(\text{cluster size})}_{\exp\{ns\}} \times \underbrace{\mathbb{E}[\text{number of clusters of that size}]}_{\exp\{n\Sigma(s)\}}$$

$\mathbb{E}Z$  is dominated by  $s$  where  $\Sigma'(s) \equiv -1$  (depending on  $\alpha$ ).

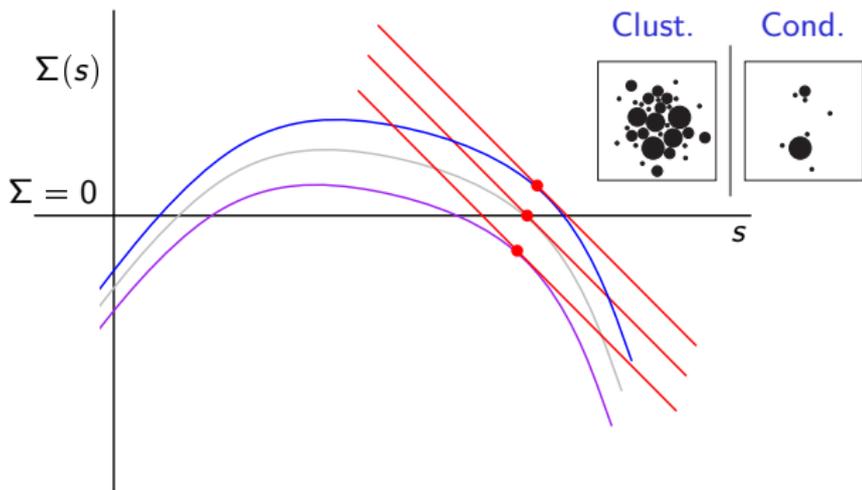


## Condensation

Complexity function  $\Sigma \equiv \Sigma_\alpha(s)$  such that:

$$\mathbb{E}Z = \sum \underbrace{(\text{cluster size})}_{\exp\{ns\}} \times \underbrace{\mathbb{E}[\text{number of clusters of that size}]}_{\exp\{n\Sigma(s)\}}$$

$\mathbb{E}Z$  is dominated by  $s$  where  $\Sigma'(s) \equiv -1$  (depending on  $\alpha$ ).

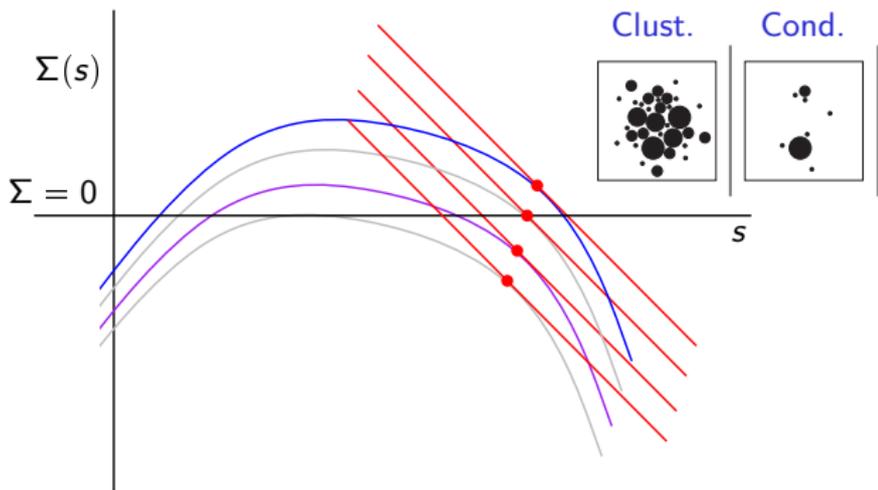


## Condensation

Complexity function  $\Sigma \equiv \Sigma_\alpha(s)$  such that:

$$\mathbb{E}Z = \sum \underbrace{(\text{cluster size})}_{\exp\{ns\}} \times \underbrace{\mathbb{E}[\text{number of clusters of that size}]}_{\exp\{n\Sigma(s)\}}$$

$\mathbb{E}Z$  is dominated by  $s$  where  $\Sigma'(s) \equiv -1$  (depending on  $\alpha$ ).

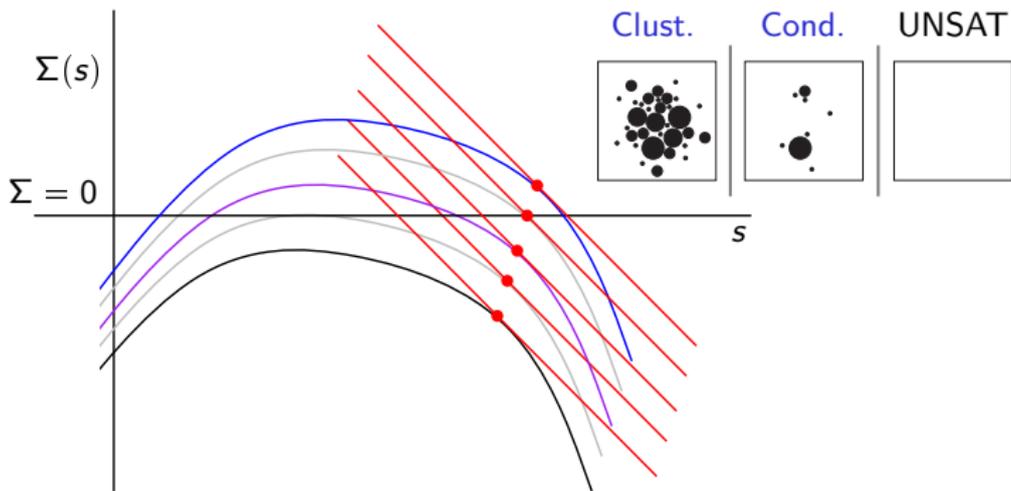


## Condensation

Complexity function  $\Sigma \equiv \Sigma_\alpha(s)$  such that:

$$\mathbb{E}Z = \sum \underbrace{(\text{cluster size})}_{\exp\{ns\}} \times \underbrace{\mathbb{E}[\text{number of clusters of that size}]}_{\exp\{n\Sigma(s)\}}$$

$\mathbb{E}Z$  is dominated by  $s$  where  $\Sigma'(s) \equiv -1$  (depending on  $\alpha$ ).

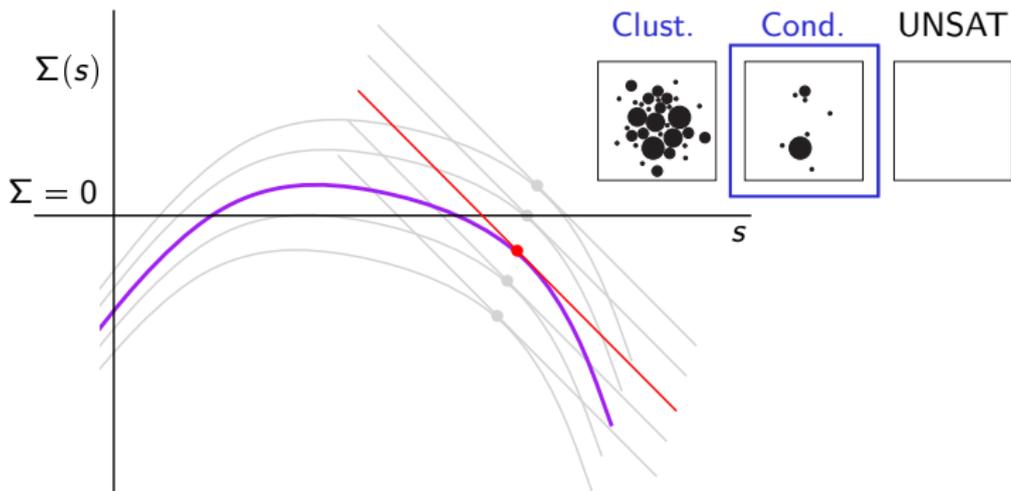


## Condensation

Complexity function  $\Sigma \equiv \Sigma_\alpha(s)$  such that:

$$\mathbb{E}Z = \sum \underbrace{(\text{cluster size})}_{\exp\{ns\}} \times \underbrace{\mathbb{E}[\text{number of clusters of that size}]}_{\exp\{n\Sigma(s)\}}$$

$\mathbb{E}Z$  is dominated by  $s$  where  $\Sigma'(s) \equiv -1$  (depending on  $\alpha$ ).

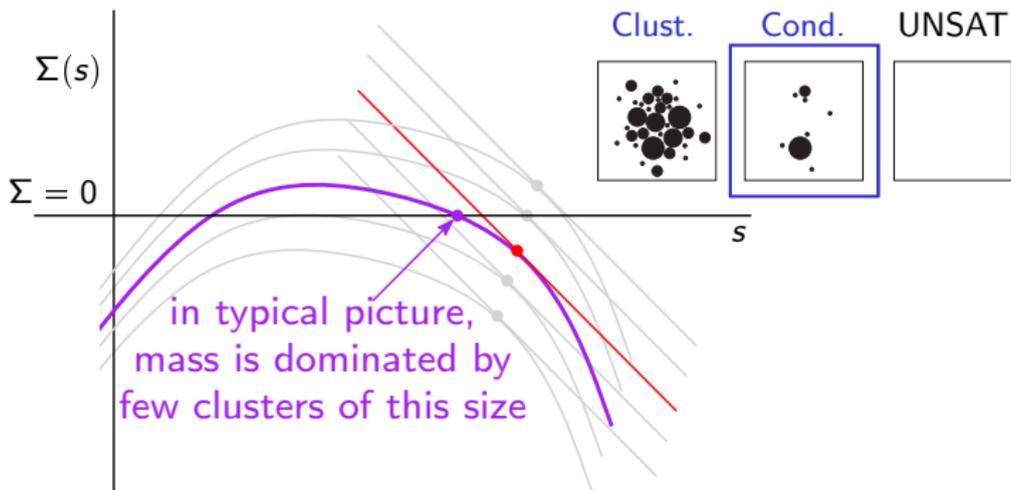


## Condensation

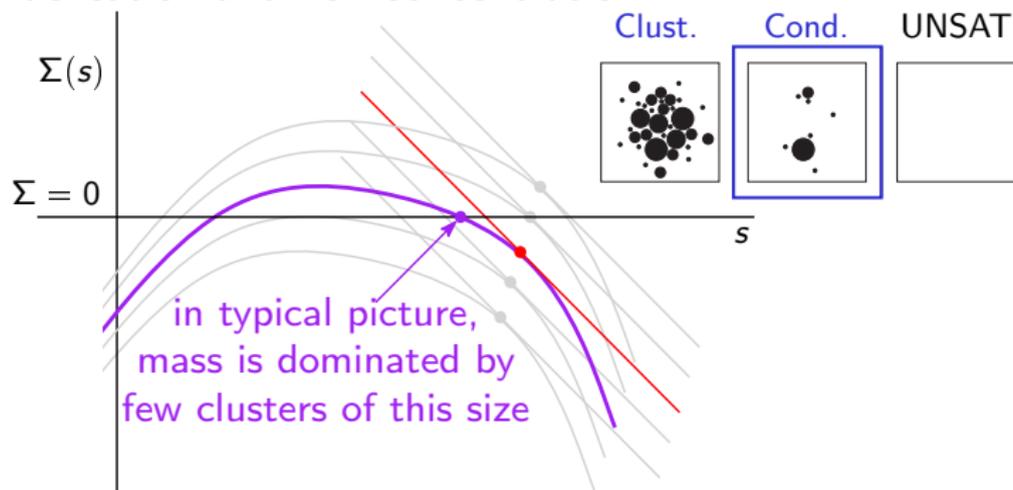
Complexity function  $\Sigma \equiv \Sigma_\alpha(s)$  such that:

$$\mathbb{E}Z = \sum \underbrace{(\text{cluster size})}_{\exp\{ns\}} \times \underbrace{\mathbb{E}[\text{number of clusters of that size}]}_{\exp\{n\Sigma(s)\}}$$

$\mathbb{E}Z$  is dominated by  $s$  where  $\Sigma'(s) \equiv -1$  (depending on  $\alpha$ ).



## Condensation and non-concentration



### The 1-RSB prediction:

- Satisfiability Threshold

$$\alpha_{\text{sat}} = \sup \left\{ \alpha : \sup_s \Sigma(s) \geq 0 \right\}$$

- Condensation Threshold and free energy

$$\alpha_{\text{cond}} = \sup \left\{ \alpha : \sup_s s + \Sigma(s) = \sup_{s: \Sigma(s) \geq 0} s + \Sigma(s) \right\}$$

$$\Phi = \lim_{n \rightarrow \infty} \frac{1}{n} \log Z = \sup \{ s + \Sigma(s) : \Sigma(s) > 0 \} = \sup \{ s : \Sigma(s) > 0 \}$$

## Results beyond the condensation threshold:

## Results beyond the condensation threshold:

### Condensation Threshold:

Random  $k$ -Colourings  $G(n,p)$  large  $k$

[Bapst, Coja-Oghlan, Hetterich, Rassmann, Vilenchik]

Regular  $k$ -NAESAT large  $k$

[S', Sun, Zhang]

### Condensation Regime Free Energy:

Regular  $k$ -NAESAT large  $k$

[S', Sun, Zhang]

### Satisfiability Threshold:

Regular NAESAT large  $k$

[Ding, S', Sun]

Maximum Independent Set  $d$ -Regular, large  $d$

[Ding, S', Sun]

Regular SAT, large  $k$

[Coja-Oghlan, Panagiotou]

Random  $k$ -SAT, large  $k$

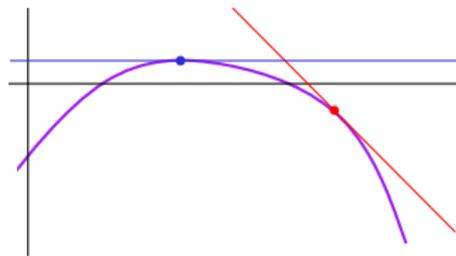
[Ding, S', Sun]

## Free Energy



$$\mathbb{E}Z = \sum_s \exp\{n[\mathbf{1} \cdot s + \Sigma(s)]\}, \quad \text{maximized at } \Sigma'(s) = -\mathbf{1}.$$

## Free Energy



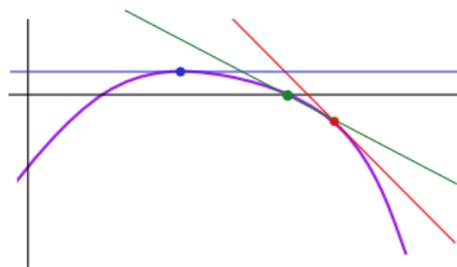
$$\mathbb{E}Z = \sum_s \exp\{n[1 \cdot s + \Sigma(s)]\},$$

maximized at  $\Sigma'(s) = -1$ .

$$\mathbb{E}|\Omega| = \sum_s \exp\{n[0 \cdot s + \Sigma(s)]\},$$

maximized at  $\Sigma'(s) = 0$ .

## Free Energy



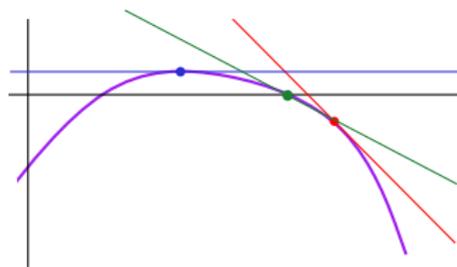
$$\mathbb{E}Z = \sum_s \exp\{n[\mathbf{1} \cdot s + \Sigma(s)]\},$$

maximized at  $\Sigma'(s) = -\mathbf{1}$ .

$$\mathbb{E}|\Omega| = \sum_s \exp\{n[\mathbf{0} \cdot s + \Sigma(s)]\},$$

maximized at  $\Sigma'(s) = \mathbf{0}$ .

## Free Energy Weight clusters by (their size) <sup>$\lambda$</sup>



$$\mathbb{E}Z = \sum_s \exp\{n[1 \cdot s + \Sigma(s)]\},$$

maximized at  $\Sigma'(s) = -1$ .

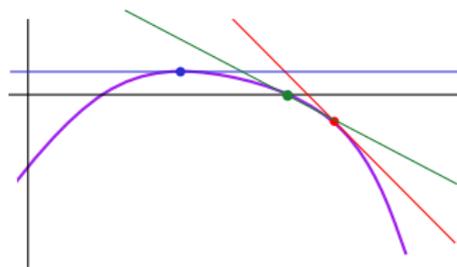
$$\mathbb{E}|\Omega| = \sum_s \exp\{n[0 \cdot s + \Sigma(s)]\},$$

maximized at  $\Sigma'(s) = 0$ .

$$\mathbb{E}Z_\lambda \equiv \sum_s \exp\{n[\lambda \cdot s + \Sigma(s)]\},$$

maximized at  $\Sigma'(s) = -\lambda$

## Free Energy Weight clusters by (their size) <sup>$\lambda$</sup>



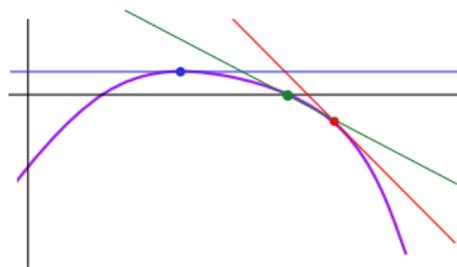
$$\mathbb{E}Z = \sum_s \exp\{n[1 \cdot s + \Sigma(s)]\}, \quad \text{maximized at } \Sigma'(s) = -1.$$

$$\mathbb{E}|\Omega| = \sum_s \exp\{n[0 \cdot s + \Sigma(s)]\}, \quad \text{maximized at } \Sigma'(s) = 0.$$

$$\mathbb{E}Z_\lambda \equiv \sum_s \exp\{n[\lambda \cdot s + \Sigma(s)]\}, \quad \text{maximized at } \Sigma'(s) = -\lambda$$

In fact,  $\frac{1}{n} \log \mathbb{E}Z_\lambda$  is the Legendre transform of  $\Sigma(s)$ .

## Free Energy Weight clusters by (their size) <sup>$\lambda$</sup>



$$\mathbb{E}Z = \sum_s \exp\{n[1 \cdot s + \Sigma(s)]\}, \quad \text{maximized at } \Sigma'(s) = -1.$$

$$\mathbb{E}|\Omega| = \sum_s \exp\{n[0 \cdot s + \Sigma(s)]\}, \quad \text{maximized at } \Sigma'(s) = 0.$$

$$\mathbb{E}Z_\lambda \equiv \sum_s \exp\{n[\lambda \cdot s + \Sigma(s)]\}, \quad \text{maximized at } \Sigma'(s) = -\lambda$$

In fact,  $\frac{1}{n} \log \mathbb{E}Z_\lambda$  is the Legendre transformation of  $\Sigma(s)$ .

The moments of  $Z_\lambda$  may be computed by adding local weights to the free variables in the  $\{+, -, \mathbf{f}\}$  configurations.

## Counting solutions within a cluster

We divide the subgraph of  $f$ 's into a forest of  $O(1)$ -size trees such that assigning values to one tree does not affect the others.

## Counting solutions within a cluster

We divide the subgraph of  $f$ 's into a forest of  $O(1)$ -size trees such that assigning values to one tree does not affect the others.

Every edge encodes the 'f-tree' it resides in.

$$\Rightarrow \underline{\tau} \in \{+, -, f\}^{V(\mathcal{G})} \leftrightarrow \underline{\sigma} \in \{\text{f-trees}\}^{E(\mathcal{G})}$$

## Counting solutions within a cluster

We divide the subgraph of  $f$ 's into a forest of  $O(1)$ -size trees such that assigning values to one tree does not affect the others.

Every edge encodes the 'f-tree' it resides in.

$$\Rightarrow \underline{\tau} \in \{+, -, f\}^{V(\mathcal{G})} \leftrightarrow \underline{\sigma} \in \{\text{f-trees}\}^{E(\mathcal{G})}$$

We can use BP algorithm write the number of solutions on trees as a product of weights.

## Counting solutions within a cluster

We divide the subgraph of  $f$ 's into a forest of  $O(1)$ -size trees such that assigning values to one tree does not affect the others.

Every edge encodes the 'f-tree' it resides in.

$$\Rightarrow \underline{\tau} \in \{+, -, f\}^{V(\mathcal{G})} \leftrightarrow \underline{\sigma} \in \{\mathbf{f}\text{-trees}\}^{E(\mathcal{G})}$$

We can use BP algorithm write the number of solutions on trees as a product of weights.

Define weight functions  $\Psi_v, \Psi_a, \Psi_e$  accordingly s.t. for each  $\underline{\sigma} \in \{\mathbf{f}\text{-trees}\}^{E(\mathcal{G})}$

$$\begin{aligned} w(\underline{\sigma}) &\equiv \prod_v \Psi_v(\underline{\sigma}_{\delta v}) \prod_a \Psi_a(\underline{\sigma}_{\delta a}) \prod_{e=(av)} \Psi_e(\underline{\sigma}_{(av)}) \\ &= \prod_T (\# \text{ of ways of assigning } \mathbf{f}'\text{s. in tree } T) \\ &= (\text{size of cluster}) \end{aligned}$$

## Counting solutions within a cluster

We divide the subgraph of  $f$ 's into a forest of  $O(1)$ -size trees such that assigning values to one tree does not affect the others.

Every edge encodes the 'f-tree' it resides in.

$$\Rightarrow \underline{\tau} \in \{+, -, f\}^{V(\mathcal{G})} \leftrightarrow \underline{\sigma} \in \{\text{f-trees}\}^{E(\mathcal{G})}$$

We can use BP algorithm write the number of solutions on trees as a product of weights.

Define weight functions  $\Psi_v, \Psi_a, \Psi_e$  accordingly s.t. for each  $\underline{\sigma} \in \{\text{f-trees}\}^{E(\mathcal{G})}$

$$\begin{aligned} w(\underline{\sigma}) &\equiv \prod_v \Psi_v(\underline{\sigma}_{\delta v}) \prod_a \Psi_a(\underline{\sigma}_{\delta a}) \prod_{e=(av)} \Psi_e(\underline{\sigma}_{(av)}) \\ &= \prod_T (\# \text{ of ways of assigning } f\text{'s. in tree } T) \\ &= (\text{size of cluster}) \end{aligned}$$

Then we can define

$$Z_\lambda \equiv \sum_{\underline{\sigma}} w^\lambda(\underline{\sigma}).$$

## Optimization

We can write

$$\mathbb{E}Z_\lambda = \frac{\sum_{(\mathcal{G}, \sigma)} w^\lambda(\sigma)}{\#\mathcal{G}}$$

## Optimization

We can write

$$\mathbb{E}Z_\lambda = \frac{\sum_{(\mathcal{G}, \underline{\sigma})} w^\lambda(\underline{\sigma})}{\#\mathcal{G}}$$

Then partitioning  $\underline{\sigma}$  according to its empirical distribution  $\nu$ ,

$$\begin{aligned}\mathbb{E}Z_\lambda[\nu] &= \frac{\binom{n}{n\nu} \binom{\alpha n}{\alpha n\hat{\nu}}}{\binom{dn}{dn\bar{\nu}}} \Psi_\nu^{\lambda n\hat{\nu}} \Psi_a^{\lambda \alpha n\hat{\nu}} \Psi_e^{\lambda dn\bar{\nu}} \\ &\equiv \exp\{n[\Sigma(\nu) + \lambda s(\nu)] + o(n)\} \\ &\equiv \exp\{n\Phi_\lambda(\nu) + o(n)\}\end{aligned}$$

## Optimization

We can write

$$\mathbb{E}Z_\lambda = \frac{\sum_{(\mathcal{G}, \underline{\sigma})} w^\lambda(\underline{\sigma})}{\#\mathcal{G}}$$

Then partitioning  $\underline{\sigma}$  according to its empirical distribution  $\nu$ ,

$$\begin{aligned}\mathbb{E}Z_\lambda[\nu] &= \frac{\binom{n}{n\nu} \binom{\alpha n}{\alpha n\hat{\nu}}}{\binom{dn}{dn\bar{\nu}}} \Psi_\nu^{\lambda n\hat{\nu}} \Psi_a^{\lambda \alpha n\hat{\nu}} \Psi_e^{\lambda dn\bar{\nu}} \\ &\equiv \exp\{n[\Sigma(\nu) + \lambda s(\nu)] + o(n)\} \\ &\equiv \exp\{n\Phi_\lambda(\nu) + o(n)\}\end{aligned}$$

Can find optimal  $\nu^*$  by finding fixed points of the Belief Propagation equations (e.g. Dembo–Montanari–Sun '13.)

## Optimization

We can write

$$\mathbb{E}Z_\lambda = \frac{\sum_{(\mathcal{G}, \sigma)} w^\lambda(\sigma)}{\#\mathcal{G}}$$

Then partitioning  $\sigma$  according to its empirical distribution  $\nu$ ,

$$\begin{aligned}\mathbb{E}Z_\lambda[\nu] &= \frac{\binom{n}{n\nu} \binom{\alpha n}{\alpha n\hat{\nu}}}{\binom{dn}{dn\bar{\nu}}} \Psi_\nu^{\lambda n\hat{\nu}} \Psi_a^{\lambda \alpha n\hat{\nu}} \Psi_e^{\lambda dn\bar{\nu}} \\ &\equiv \exp\{n[\Sigma(\nu) + \lambda s(\nu)] + o(n)\} \\ &\equiv \exp\{n\Phi_\lambda(\nu) + o(n)\}\end{aligned}$$

Can find optimal  $\nu^*$  by finding fixed points of the Belief Propagation equations (e.g. Dembo–Montanari–Sun '13.)

For regular NAE-SAT and  $k \geq k_0$ , the limit  $\Phi(\alpha)$  exists for  $\alpha_{\text{cond}} < \alpha < \alpha_{\text{sat}}$ , given by an explicit formula matching the 1-RSB prediction from statistical physics. S., Sun, Zhang '16

## New Results

---

**Theorem** (Nam, S., Sohn 19+) *For  $k \geq k_0$  (absolute constant), random regular  $k$ -NAESAT, WHP the largest and second largest clusters both have a constant fraction of the set total solutions. Two uniformly chosen solutions have normalized hamming distance concentrated on **two** points.*

---

- Requires estimating the partition function up to multiplicative  $O(1)$  factor.
- States space of free trees is unbounded.

## **Future Directions and open problems:**

## **Future Directions and open problems:**

Small  $k$ ?

## **Future Directions and open problems:**

Small  $k$ ?

Extension to random graph coloring?

## Future Directions and open problems:

Small  $k$ ?

Extension to random graph coloring?

Other aspects of the 1RSB phase diagram?



## Future Directions and open problems:

Small  $k$ ?

Extension to random graph coloring?

Other aspects of the 1RSB phase diagram?



Models at finite temperature?

Thanks!