

## MAT211 Lecture 10

### Coordinates

- Definition
- Linearity of coordinates
- The matrix of a linear transformation
- Standard matrix - B-matrix
- Similar matrices

## Review

- Linear combination
- Subspace of  $\mathbb{R}^n$
- Span
- Basis

- Consider a basis  $\mathbf{B}=(v_1, v_2, \dots, v_m)$  of a subspace  $V$  of  $\mathbb{R}^n$  and a vector  $x$  of  $V$ .
- We know that  $x$  can be written as  
$$x = c_1 v_1 + c_2 v_2 + \dots + c_n v_n$$
- Moreover, the coefficients  $c_1, c_2, \dots, c_n$  are unique.
- The scalars  $c_1, c_2, \dots, c_n$  are the coordinates of  $x$ .
- The vector  $(c_1, c_2, \dots, c_n)$  is the B-coordinate of  $x$ .
- The B-coordinate of  $x$  is denoted by  $[x]_{\mathbf{B}}$

## Example 3.4-10

If  $\mathbf{B} = (-1, 0, 1), (-2, 1, 0)$  and  $V$  is the span of  $\mathbf{B}$ , find the B-coordinates of  $(1, -2, -2)$ .

## Remark

Since

$$x = c_1 v_1 + c_2 v_2 + \dots + c_n v_n,$$

$x = S [x]_{\mathbf{B}}$ , where  $S$  is the  $n \times m$  matrix with columns  $v_1, v_2, \dots, v_m$ .

## Theorem

If  $\mathbf{B}$  is a basis of a subspace  $V$  or  $\mathbb{R}^n$ ,  $x$  and  $y$  are vectors in  $V$  and  $k$  is a scalar then

- $[x+y]_{\mathbf{B}} = [x]_{\mathbf{B}} + [y]_{\mathbf{B}}$
- $[k \cdot x]_{\mathbf{B}} = k \cdot [x]_{\mathbf{B}}$

## Definition

Consider a linear transformation  $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$  and a basis  $\mathbf{B} = (v_1, v_2, \dots, v_n)$  of  $\mathbb{R}^n$ .

The  $n \times n$  matrix with columns

$[T(v_1)]_{\mathbf{B}}, [T(v_2)]_{\mathbf{B}}, \dots, [T(v_n)]_{\mathbf{B}}$

is called the  $\mathbf{B}$ -matrix of  $T$ .

- Observe that the  $\mathbf{B}$ -matrix of  $T$  transforms  $[x]_{\mathbf{B}}$  in  $[T(x)]_{\mathbf{B}}$  for every  $x$  in  $\mathbb{R}^n$

## Example 3.4-22

Find the matrix  $\mathbf{B}$  of the linear transformation  $T(x) = Ax$  with respect to the basis  $\mathbf{B} = (1, 2), (-2, 1)$ , where  $A$  is

$$\begin{vmatrix} -3 & 4 \\ 4 & 3 \end{vmatrix}$$

## Theorem

Consider a linear transformation  $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$  and a basis  $\mathbf{B} = (v_1, v_2, \dots, v_n)$  of  $\mathbb{R}^n$ .

Denote by  $\mathbf{B}$  the  $\mathbf{B}$ -matrix of  $T$ .

Denote  $A$  the standard matrix of  $T$ .

Denote by  $S$  the matrix with columns  $v_1, v_2, \dots, v_n$ .

Then  $AS = SB$ ,  $B = S^{-1}AS$  and  $A = SBS^{-1}$ .

## Example 3.4-22

Find the matrix  $\mathbf{B}$  of the linear transformation  $T(x) = Ax$  with respect to the basis  $\mathbf{B} = (1, 2), (-2, 1)$ , where  $A$  is

$$\begin{vmatrix} -3 & 4 \\ 4 & 3 \end{vmatrix}$$

Solve it in three different ways

1. Use the formula  $B = S^{-1}AS$
2. Use a commutative diagram
3. Construct  $\mathbf{B}$  column by column

## Definition

Consider two  $n \times n$  matrices  $A$  and  $B$ .

We say that  $A$  is similar to  $B$  if there exists an invertible matrix  $S$  such that  $AS = SB$ .

## Example 3.4-61

Find a basis  $\mathbf{B}$  of  $\mathbb{R}^2$  such that the  $\mathbf{B}$ -matrix of the linear transformation given by the first matrix is the second matrix.

$$\begin{vmatrix} -5 & 9 \\ 4 & 7 \end{vmatrix} \quad \begin{vmatrix} 1 & 1 \\ 0 & 1 \end{vmatrix}$$