

*Mass, Scalar Curvature,
Kähler Geometry, and All That*

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Mathematics Colloquium
University of Florida
Gainesville, FL, April 15, 2019

Core results joint with

Core results joint with

Hans-Joachim Hein
Fordham University

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Mass in Kähler Geometry

Comm. Math. Phys. 347 (2016) 621–653.

Recent technical improvements:

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Mass, Kähler Manifolds,
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arXiv: 1810.11417 [math.DG]

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Ann. Glob. An. Geom. to appear

doi: 10.1007/s10455-019-09658-9

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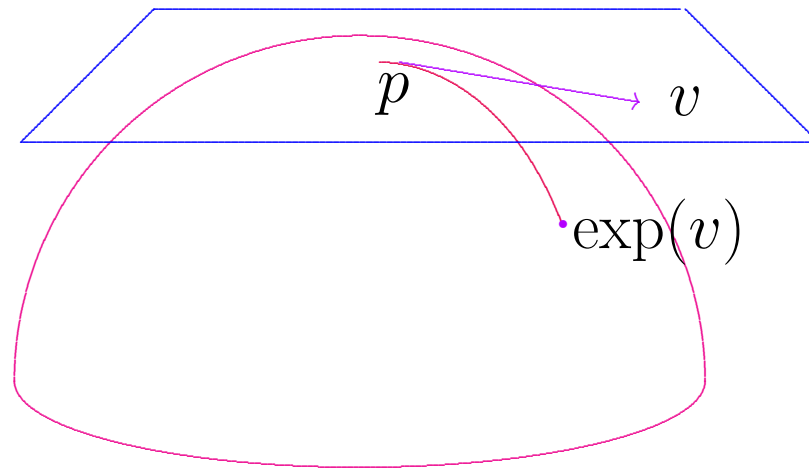
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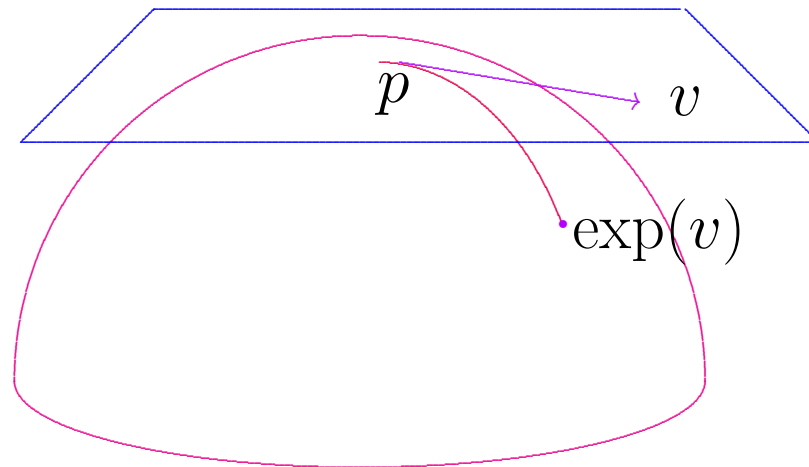
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Now choosing $T_p M \xrightarrow{\cong} \mathbb{R}^n$ via some orthonormal
basis gives us special coordinates on M .

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Components like \mathcal{R}_{1212} are “**sectional curvatures**” ...

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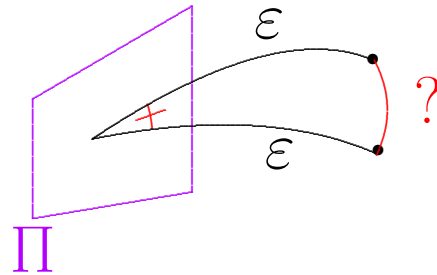
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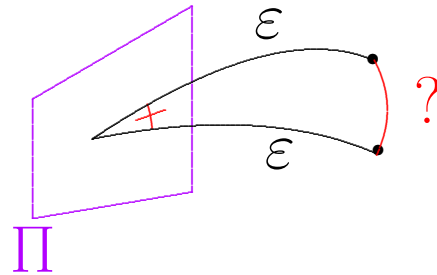


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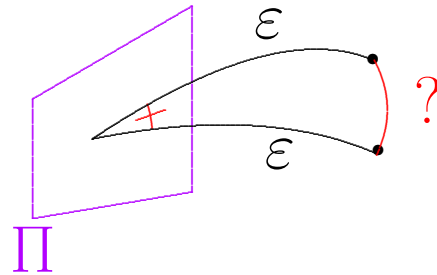
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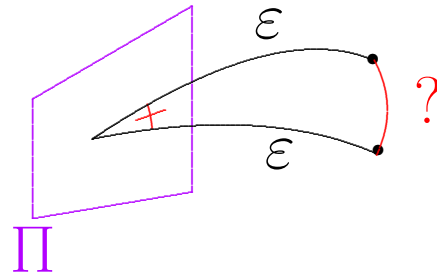
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$$d\mu_g = \sqrt{\det[g_{jk}]} dx^1 \wedge \cdots \wedge dx^n$$

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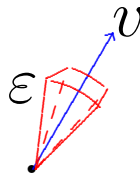
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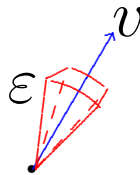


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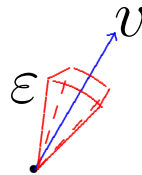


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The metric g is called *Ricci-flat* if it satisfies $r \equiv 0$.

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But this has a simple geometric interpretation...

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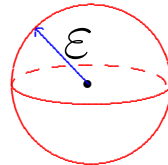
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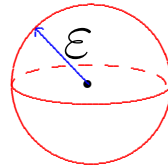


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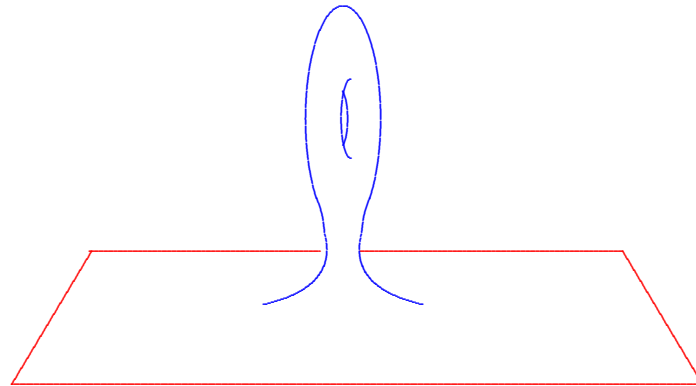


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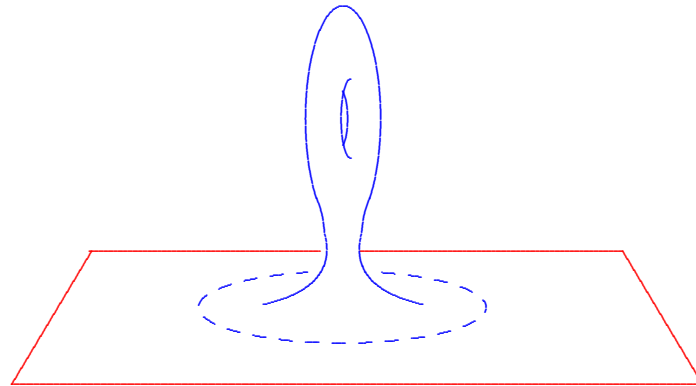
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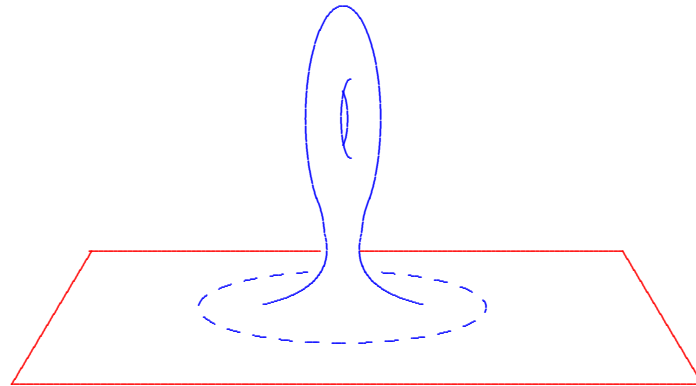
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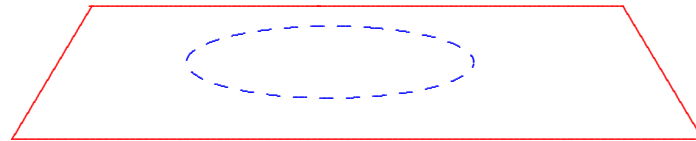


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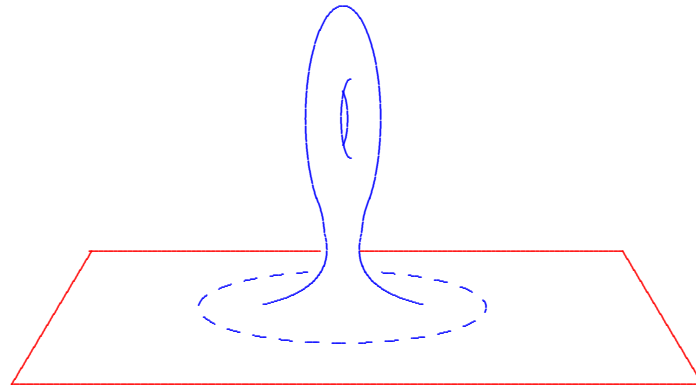


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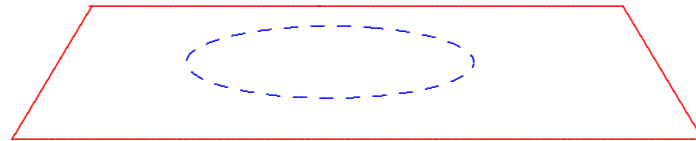


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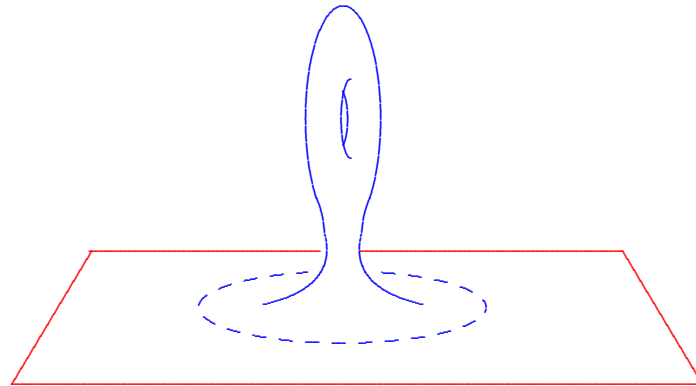


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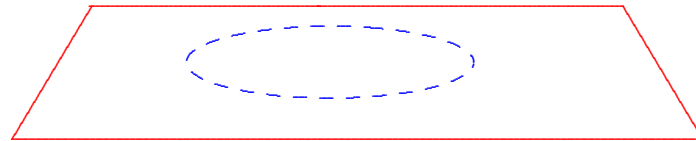


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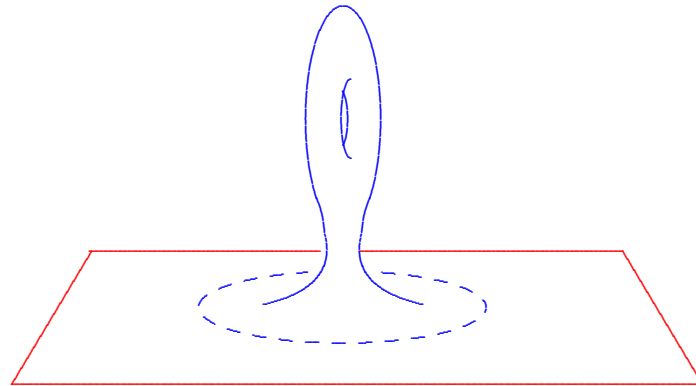


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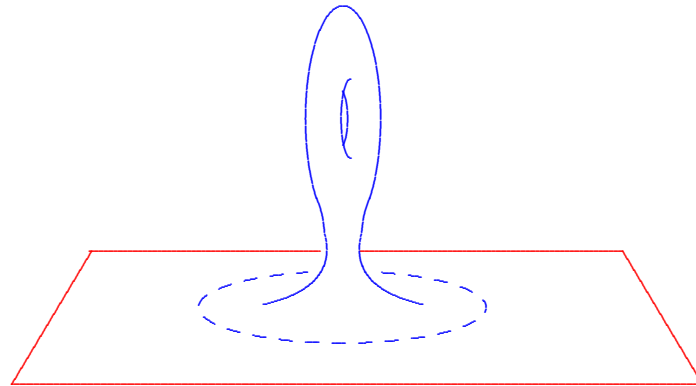


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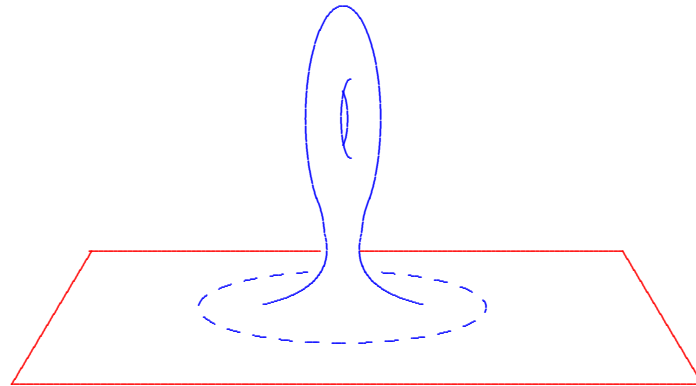
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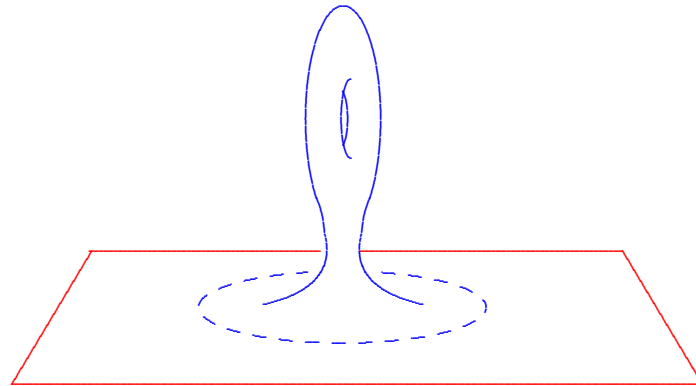
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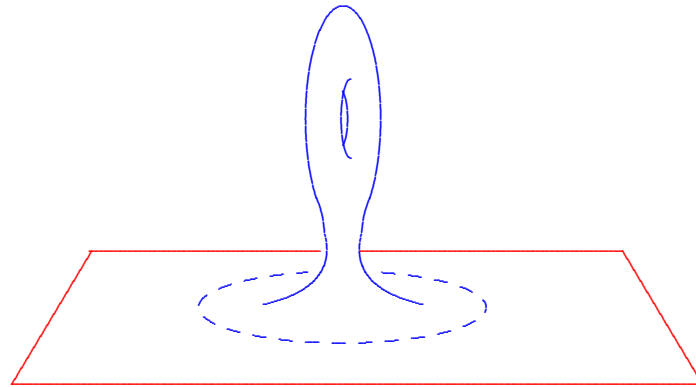
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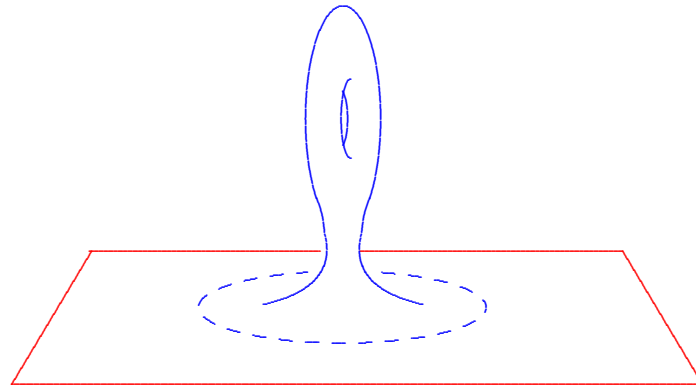
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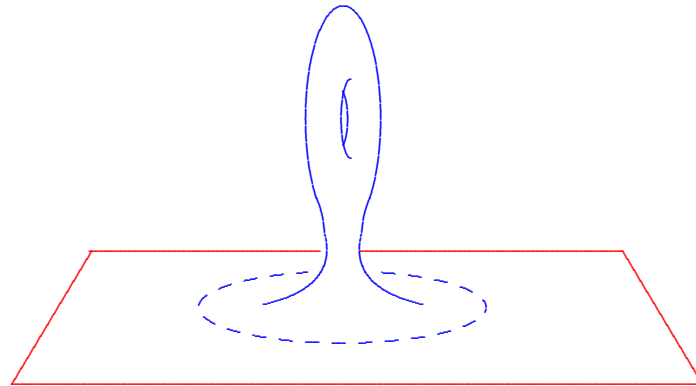
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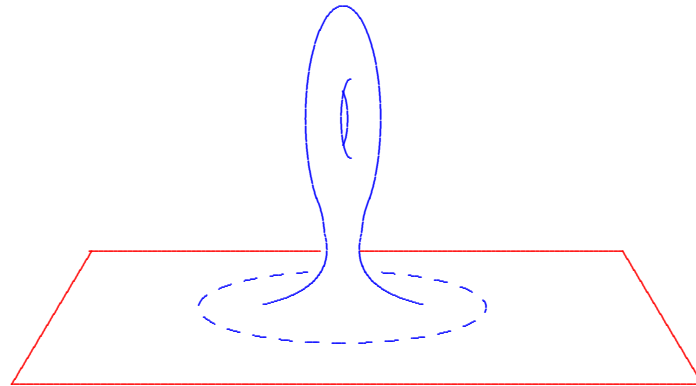
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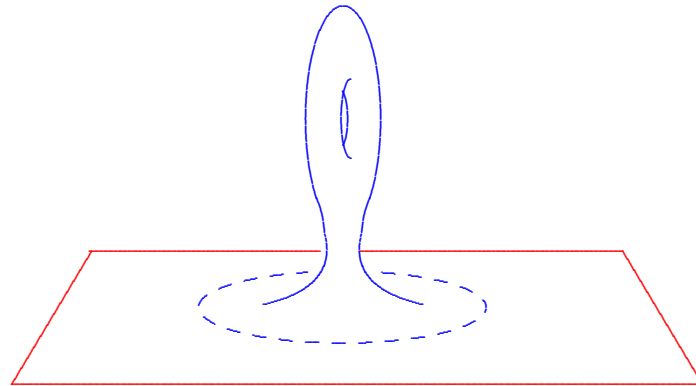
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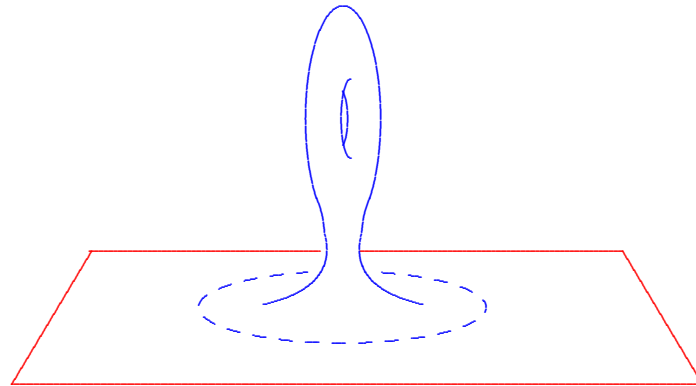
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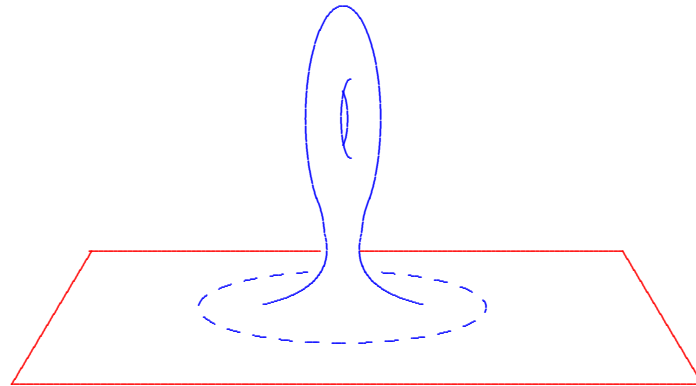
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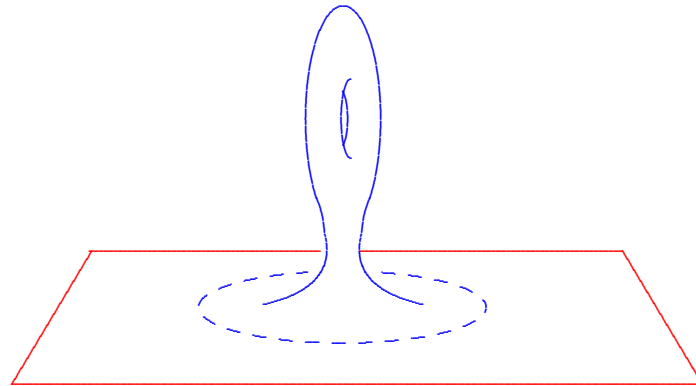
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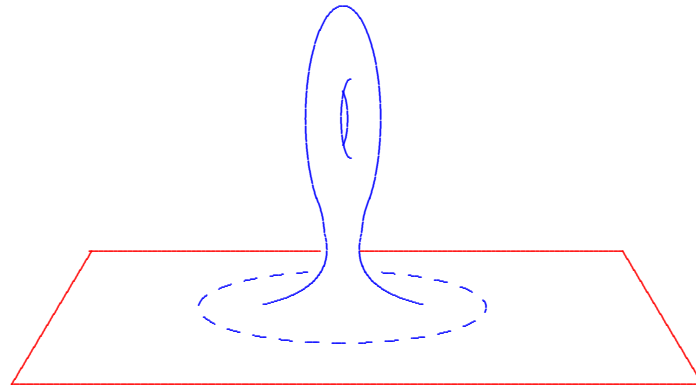
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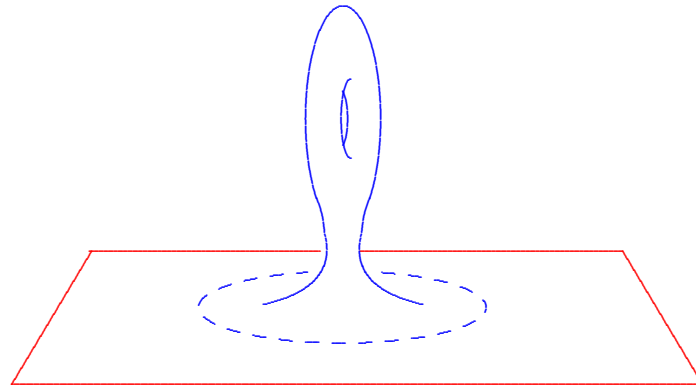
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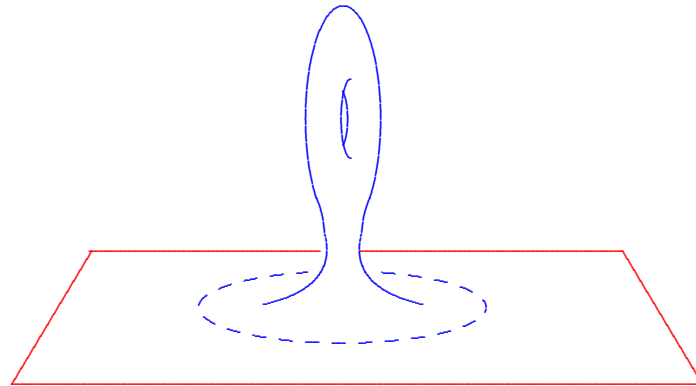
If M has scalar curvature ≥ 0 , is it flat? Yes!

This time, the inspiration comes from physics!

Simple, natural problem:

(M^n, g) complete non-compact Riemannian n -manifold.

Suppose $\exists K \subset M$ compact



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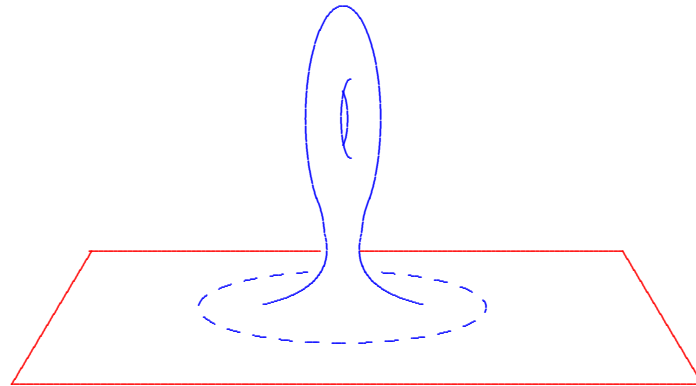
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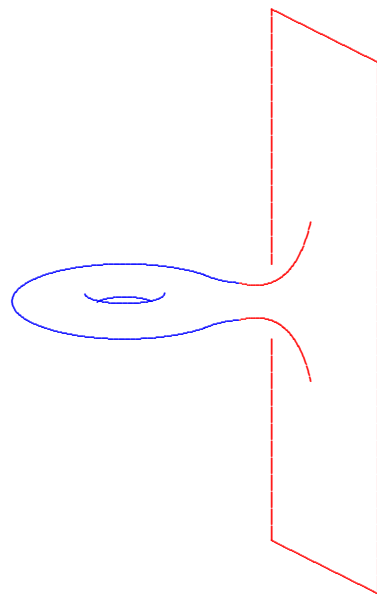
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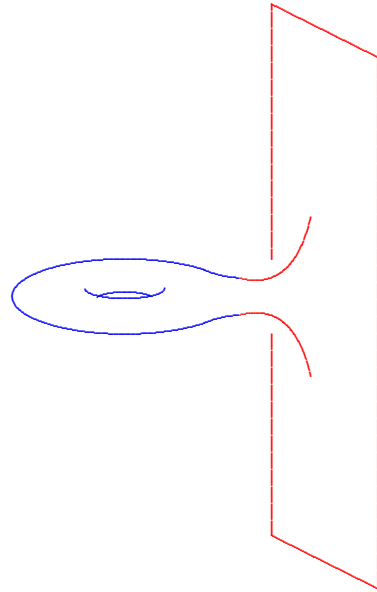
“Positive Mass Theorem”

Get result even with appropriate fall-off to Euclidean...

Definition. A complete, non-compact Riemannian n -manifold (M^n, g)

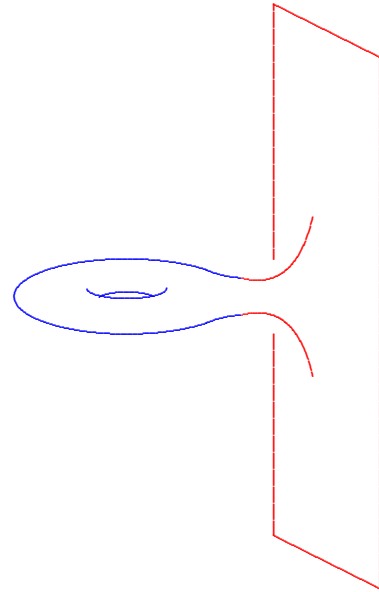


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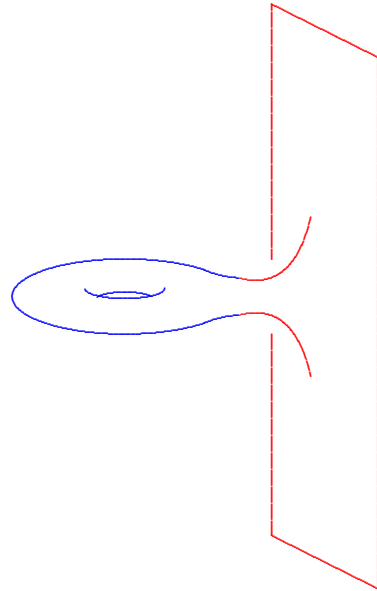
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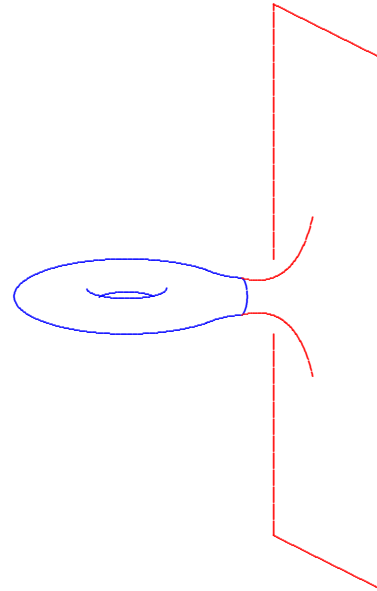
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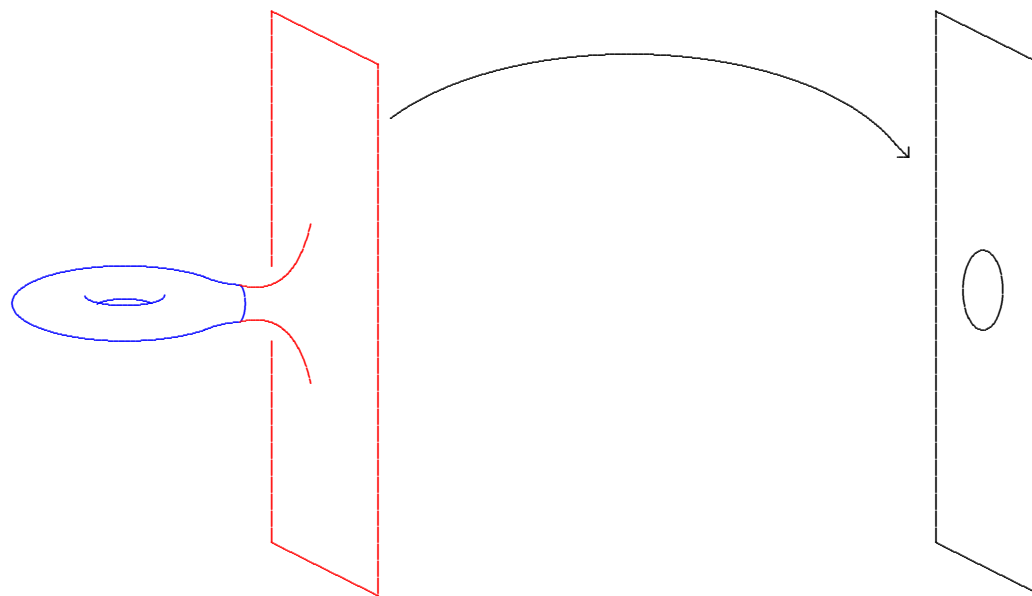


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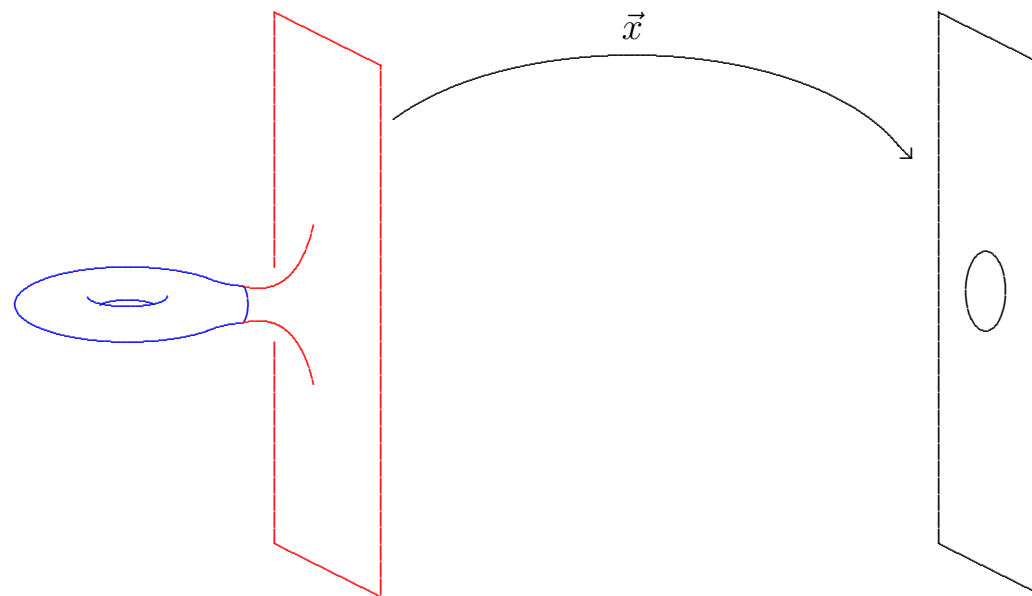
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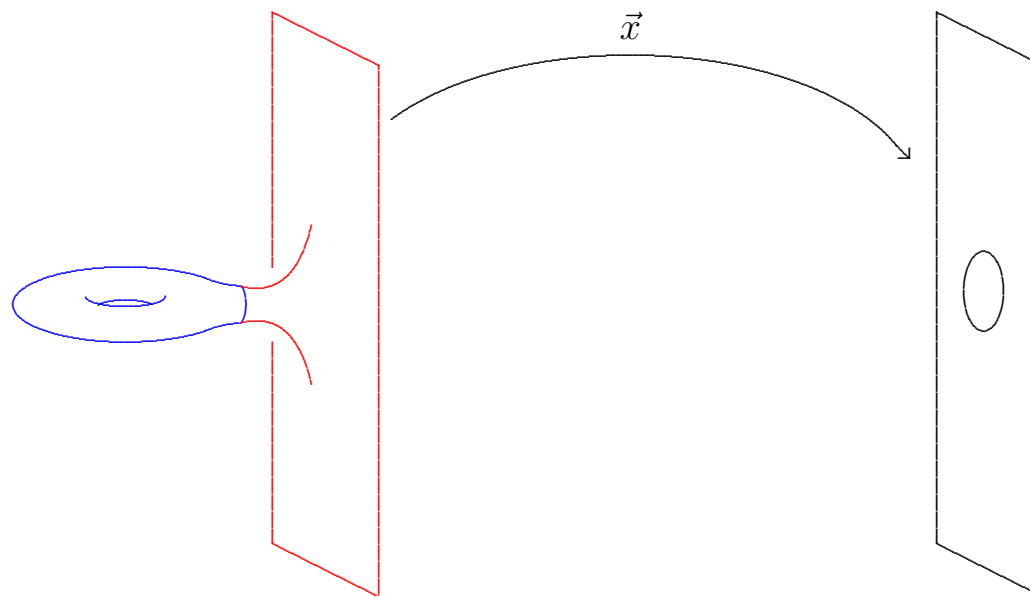


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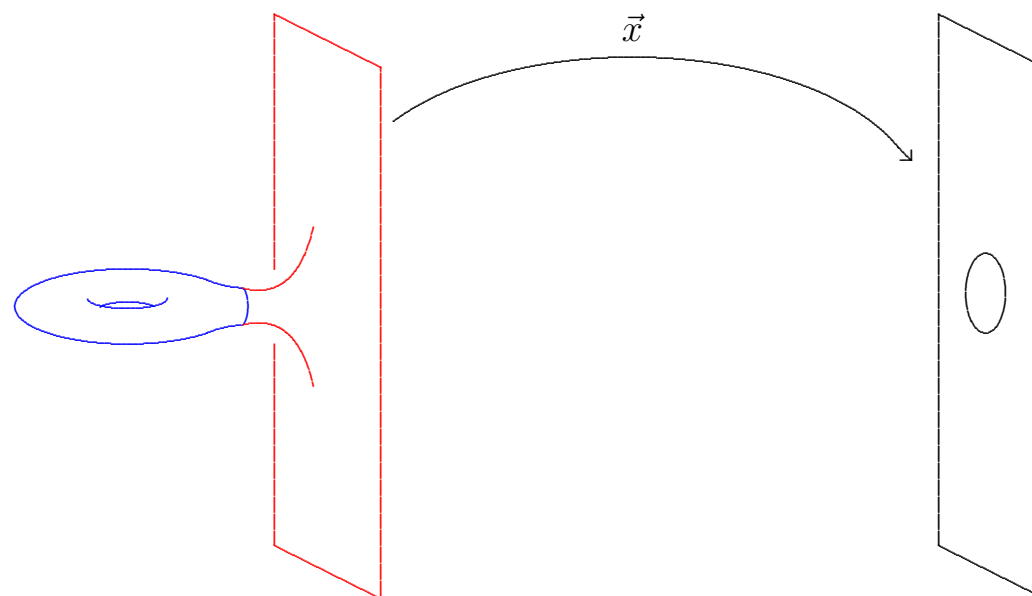
$$g_{jk} = \delta_{jk} + \text{terms that fall-off at infinity}$$

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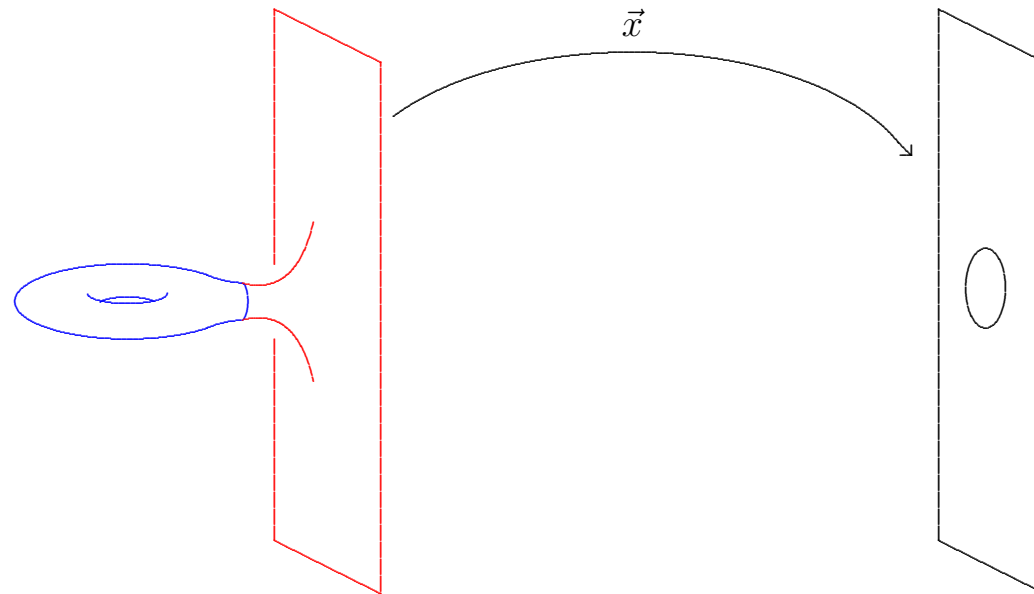
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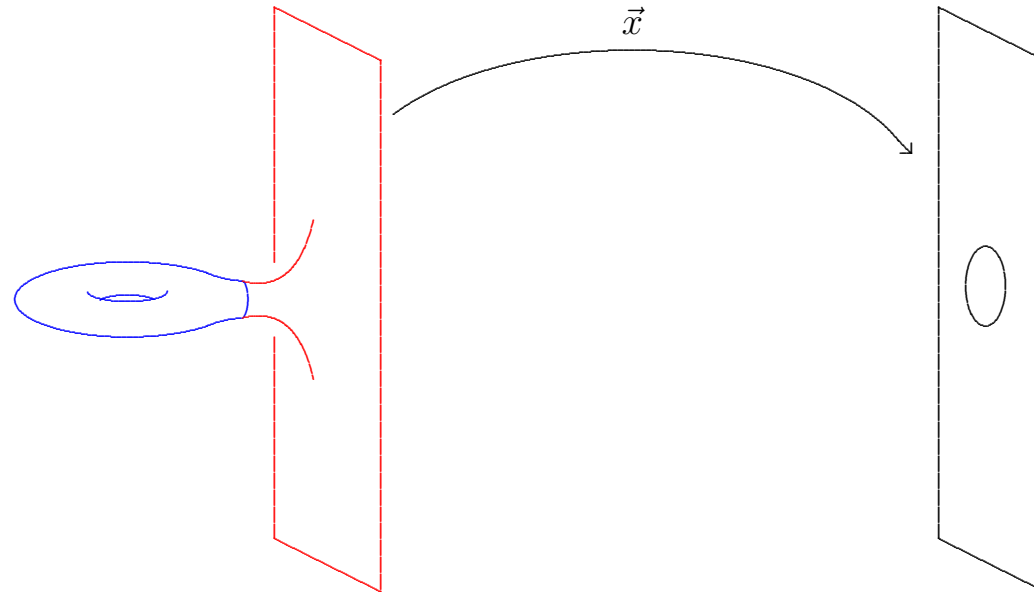
Chruściel-type fall-off:

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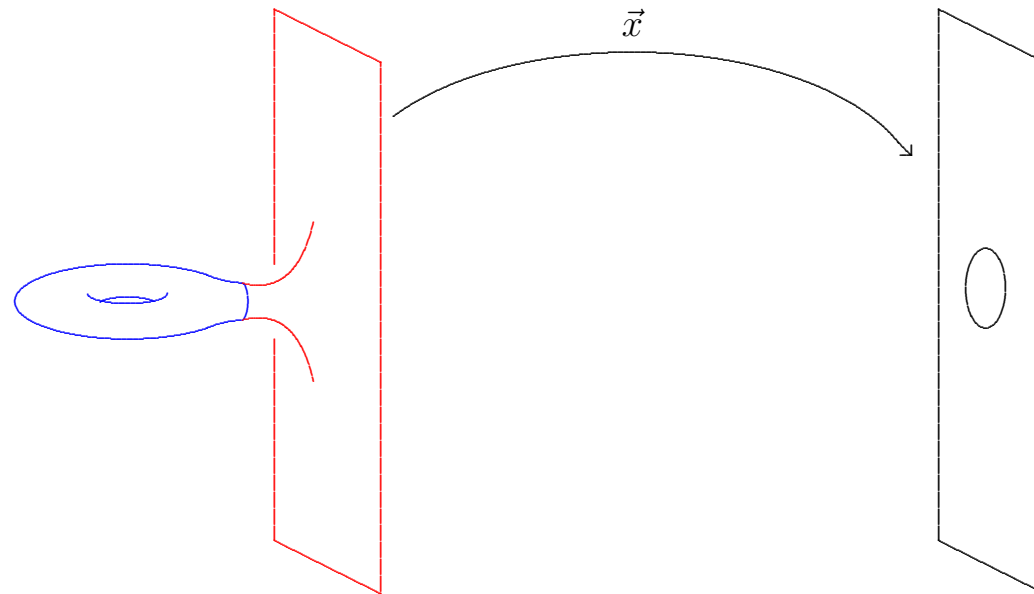
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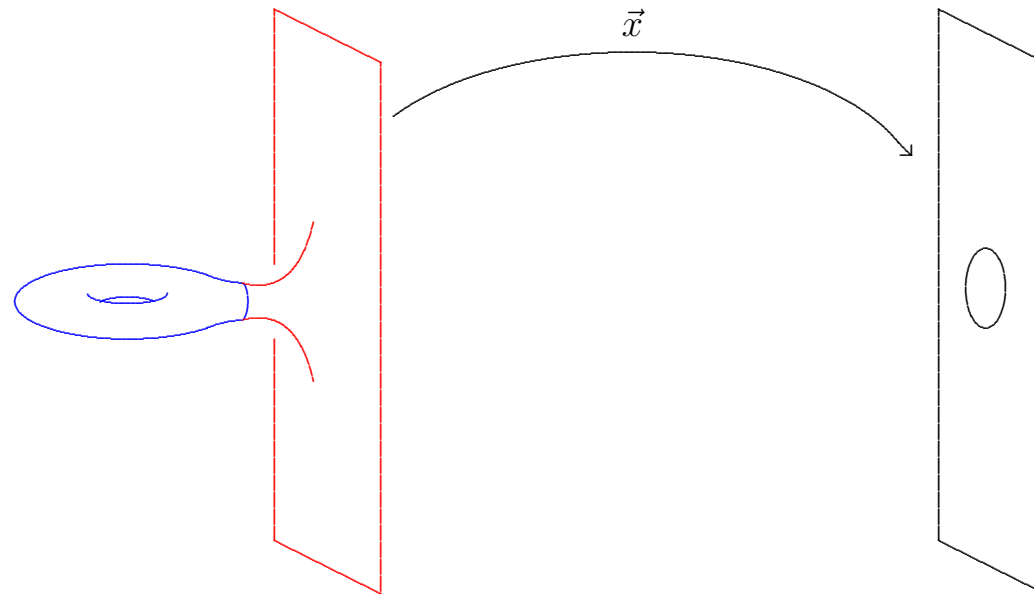
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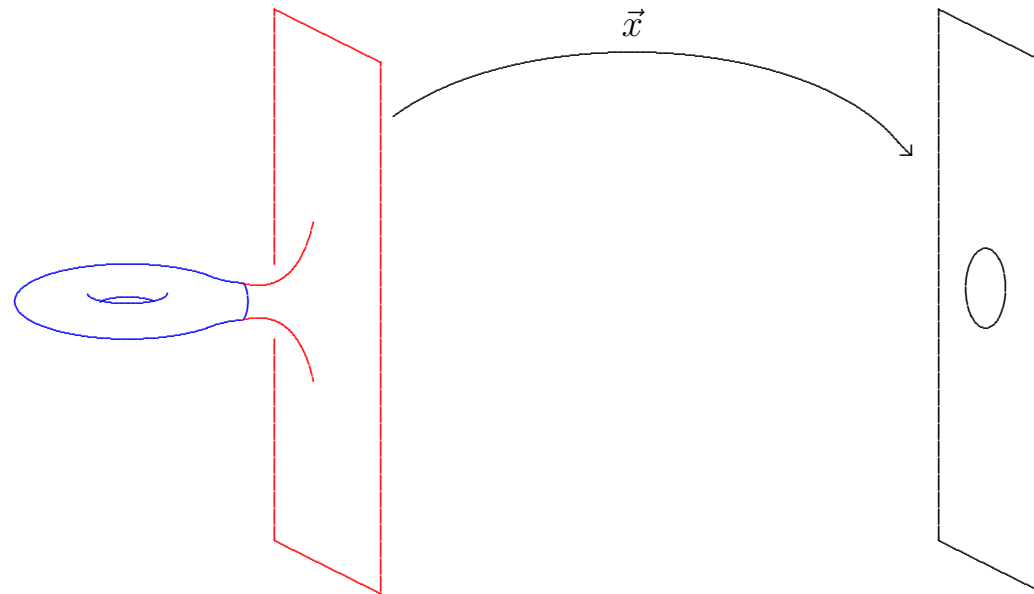
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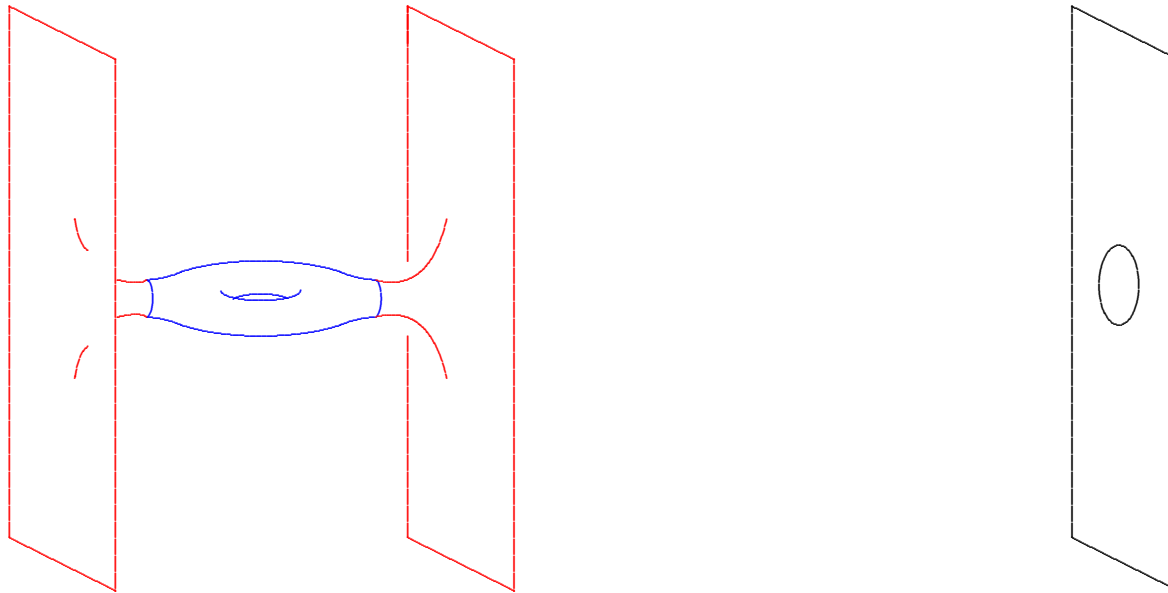
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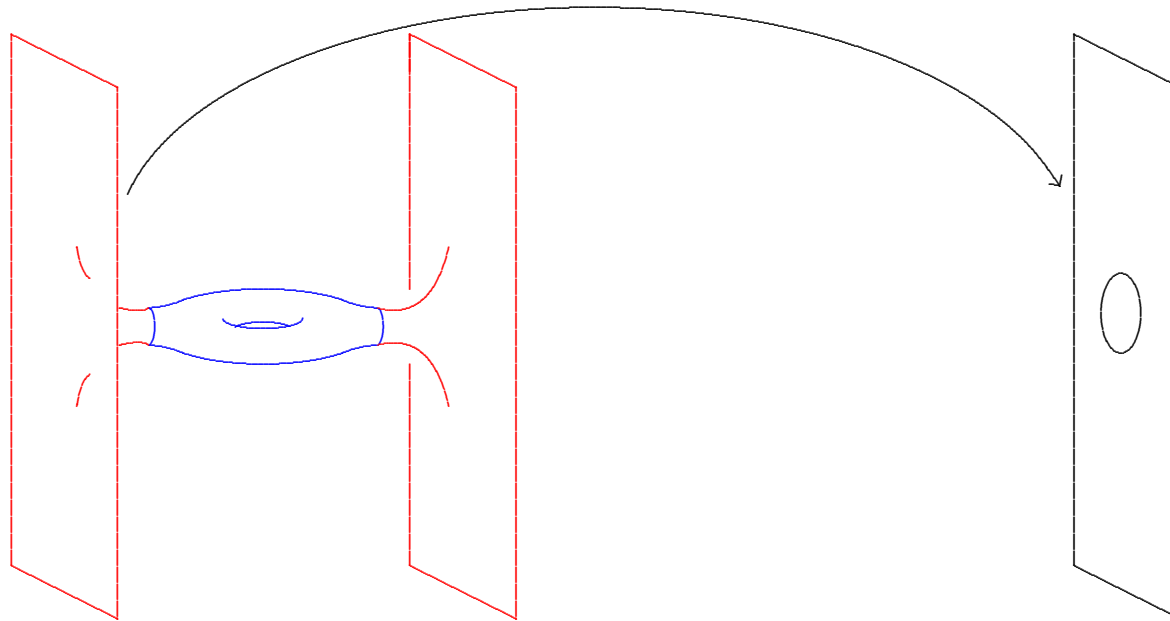
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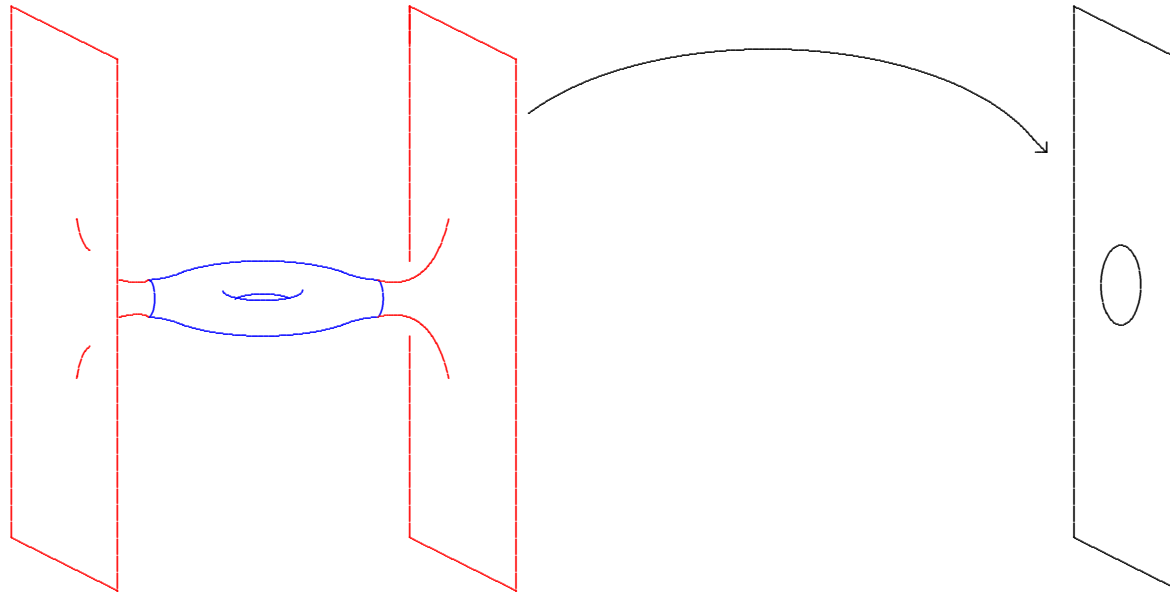
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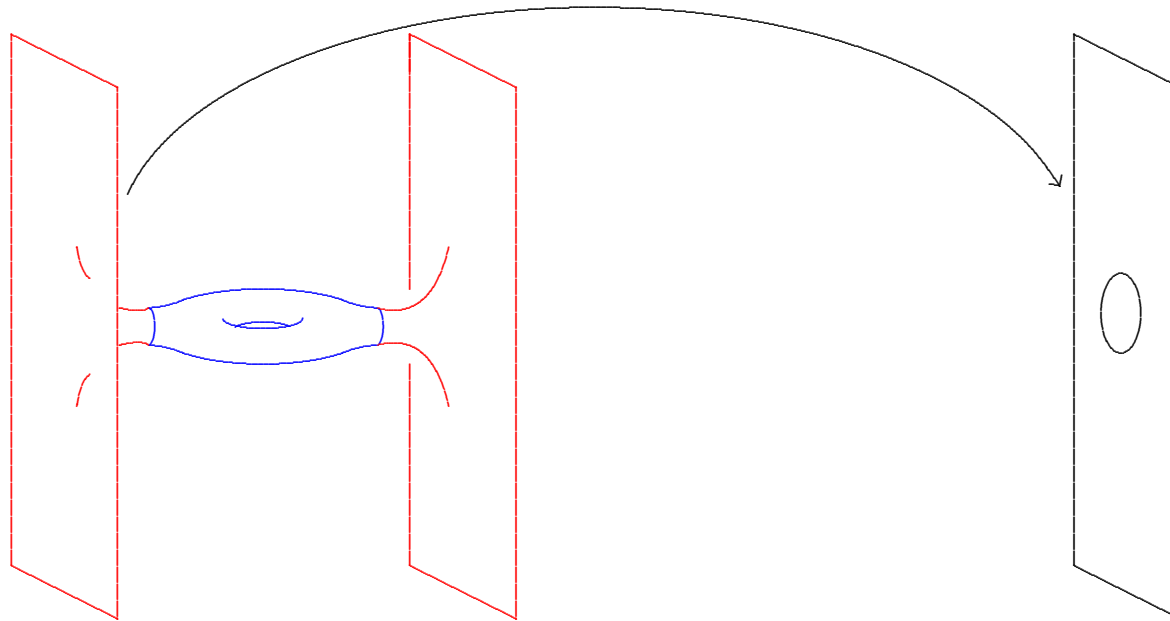
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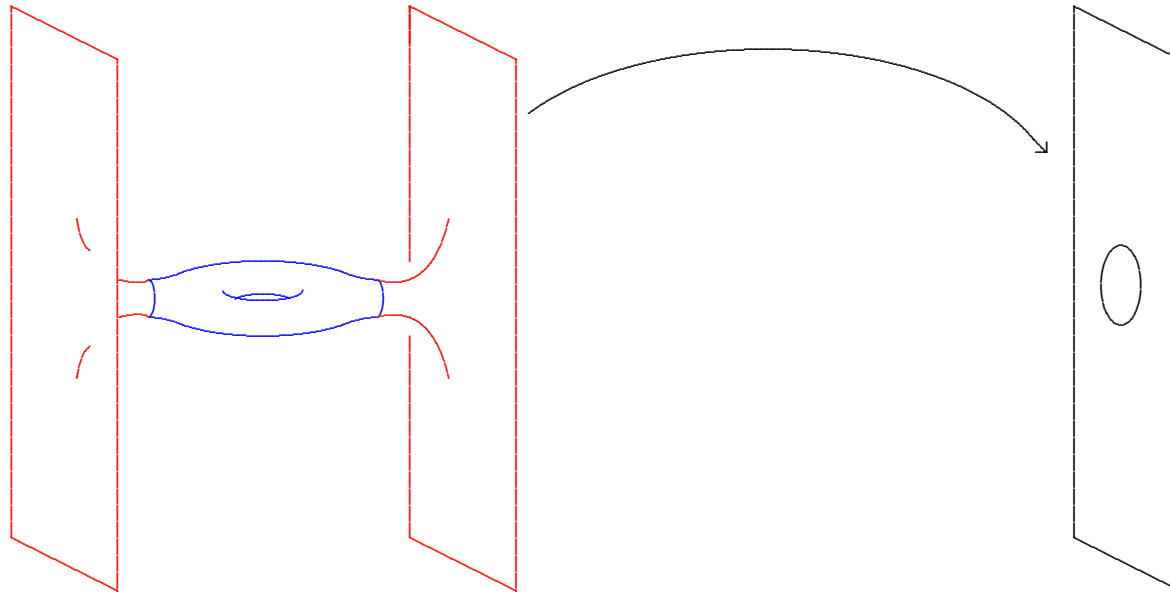
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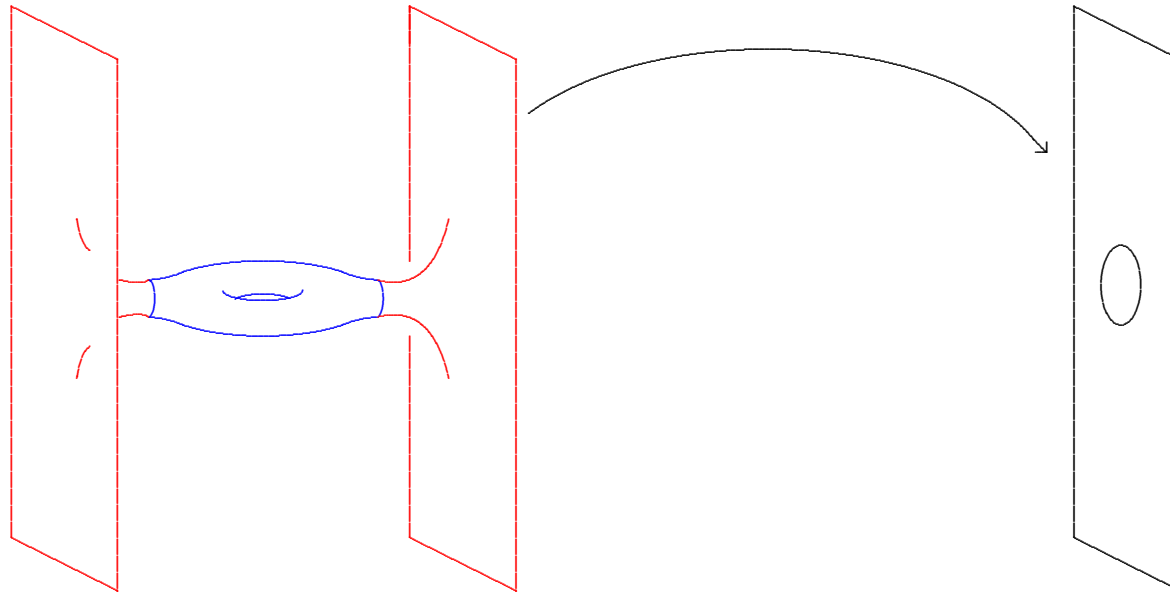
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Seems to depend on choice of coordinates!

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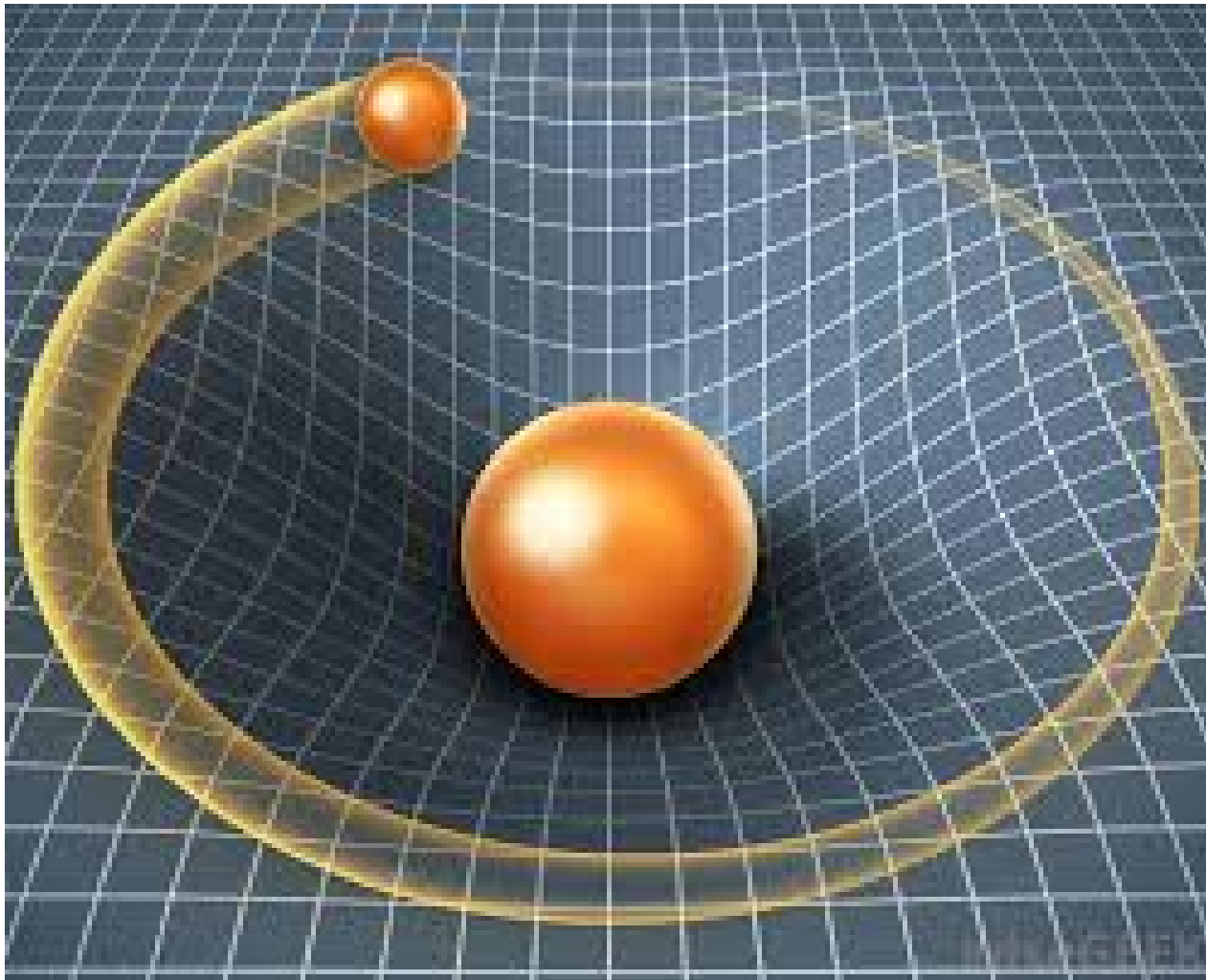
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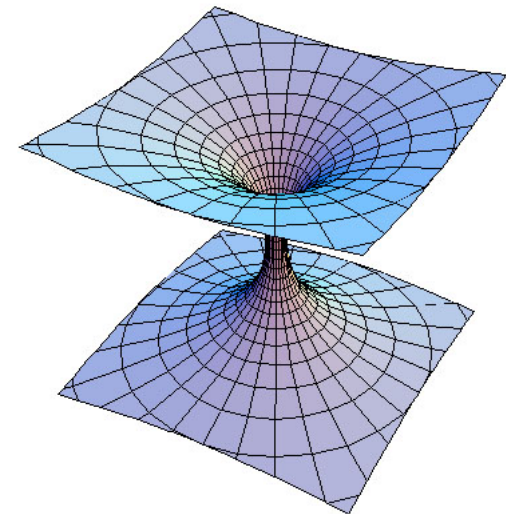
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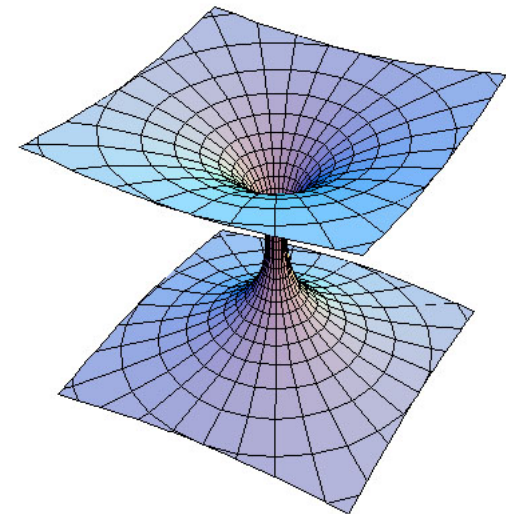
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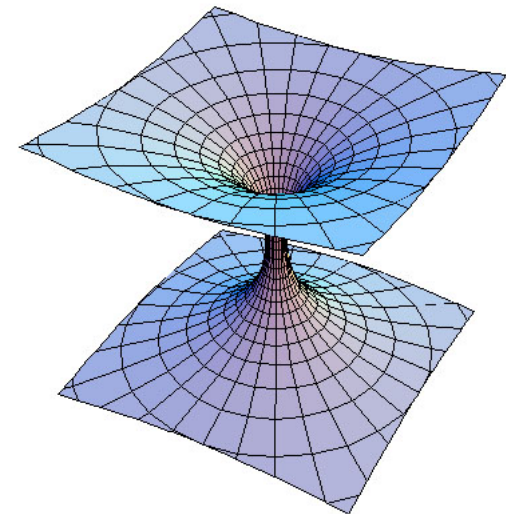
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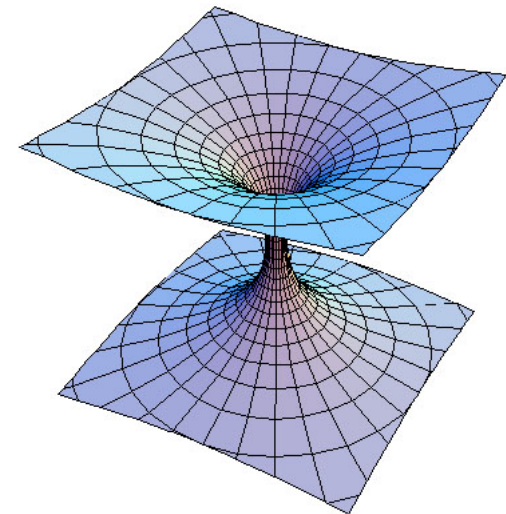
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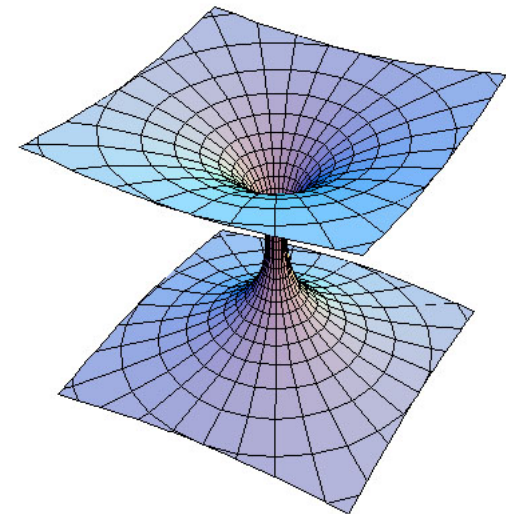
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Motivation:

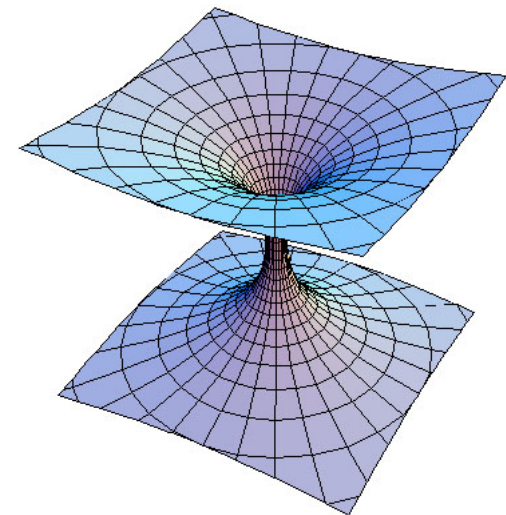
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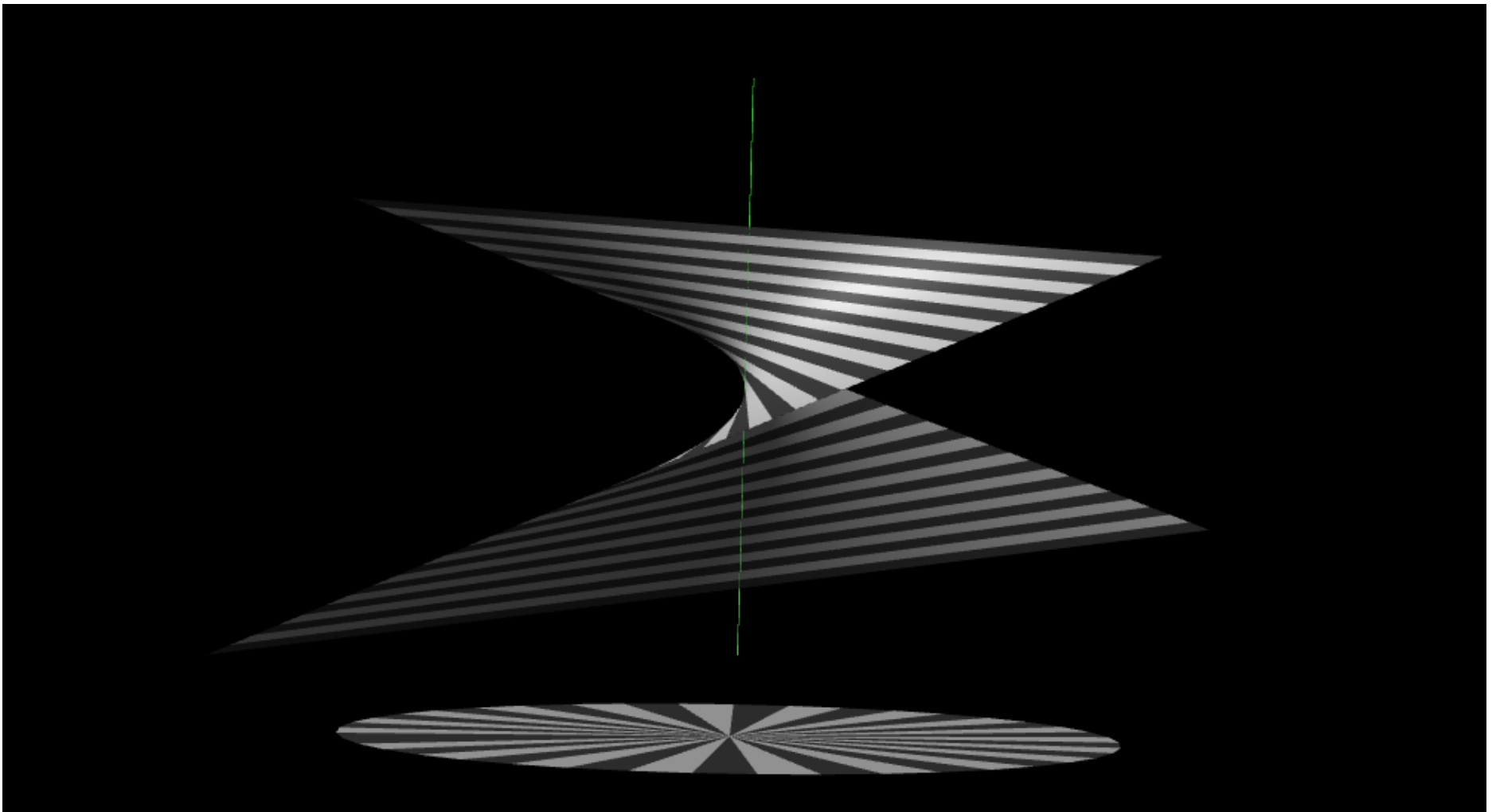
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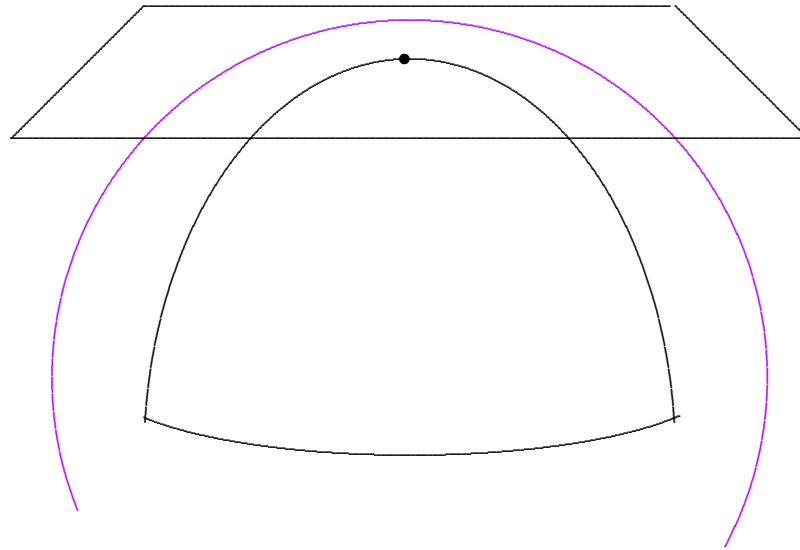
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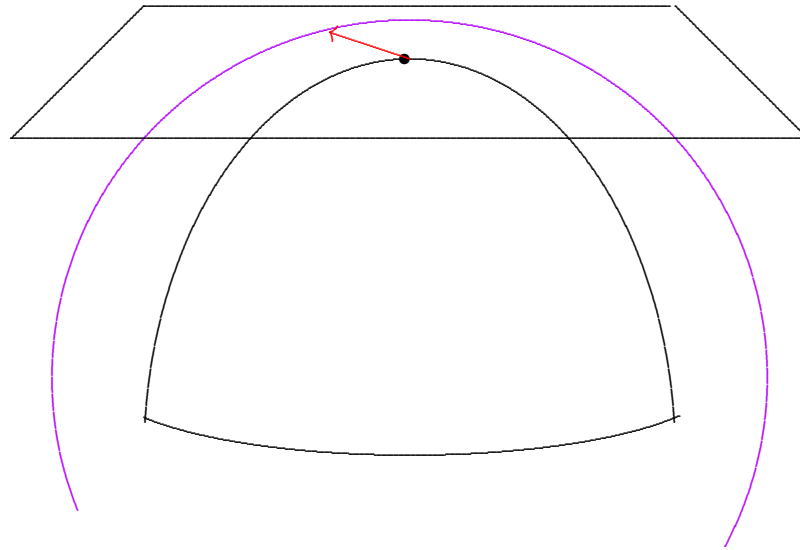
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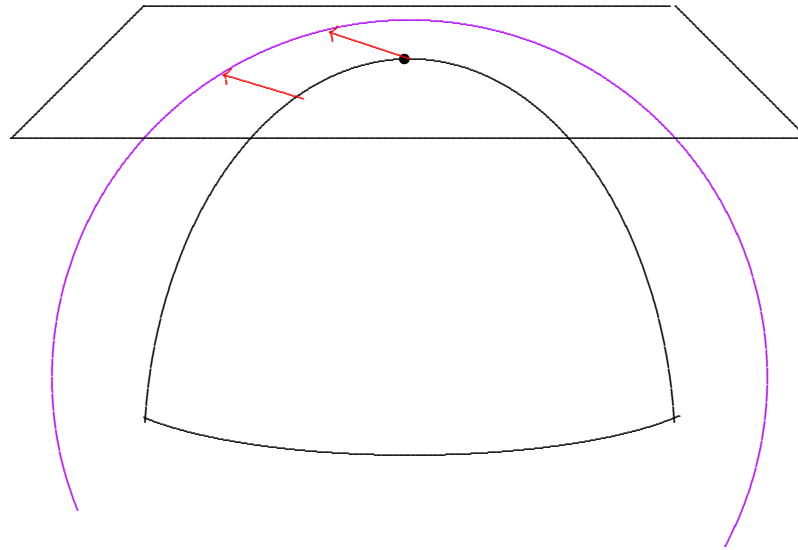
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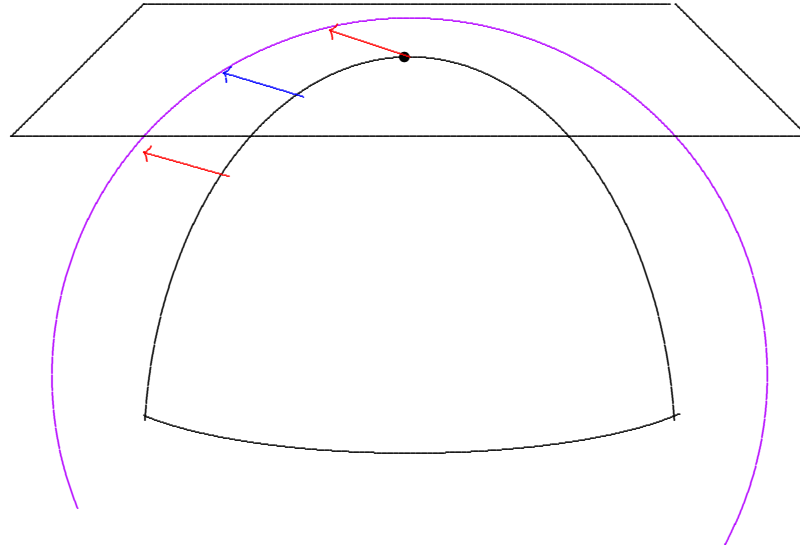
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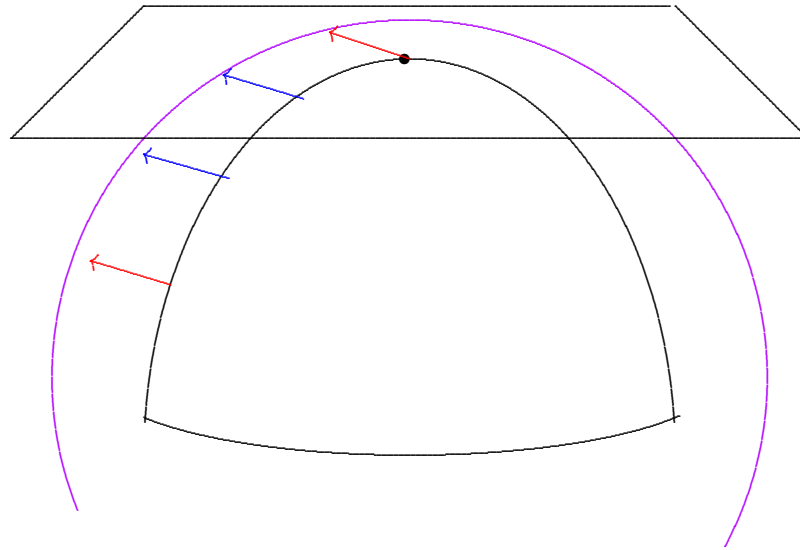
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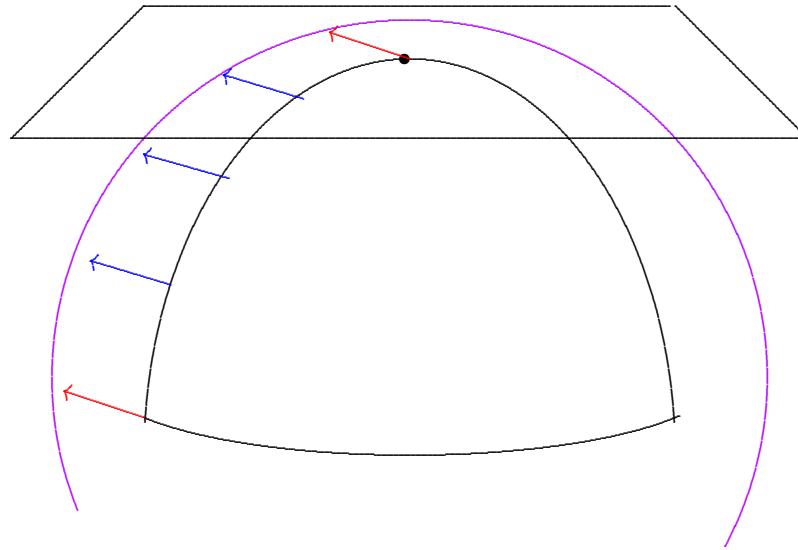
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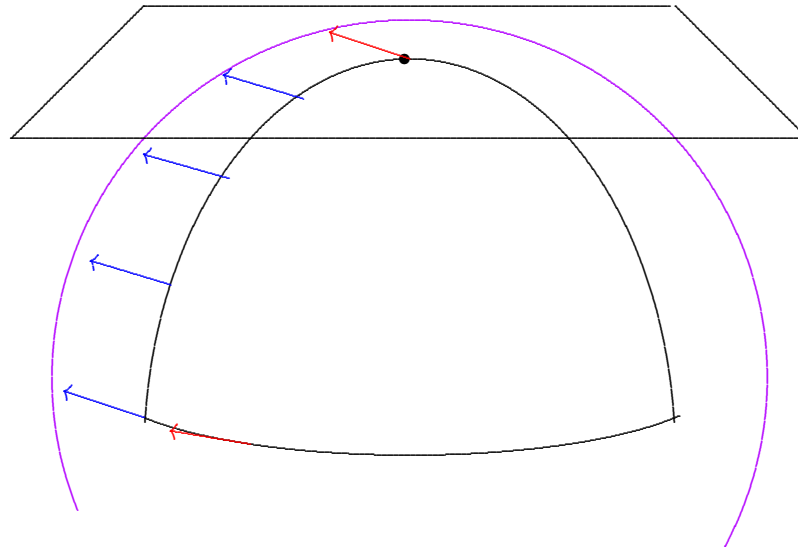
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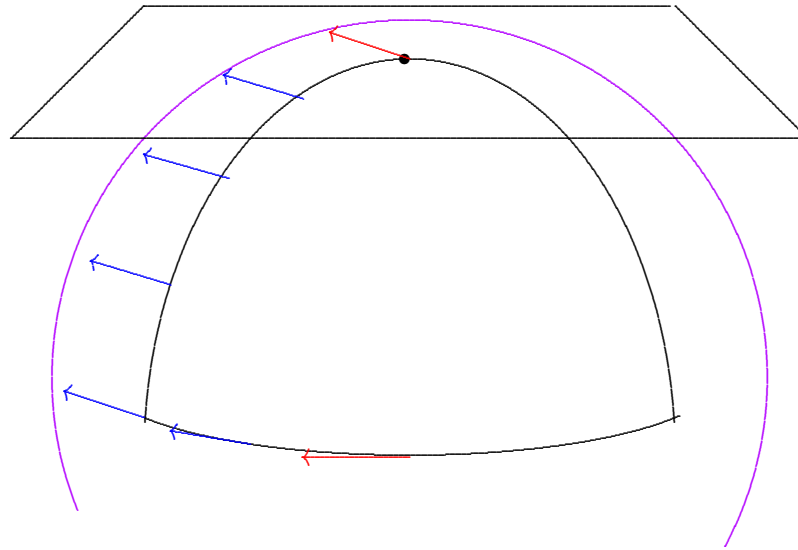
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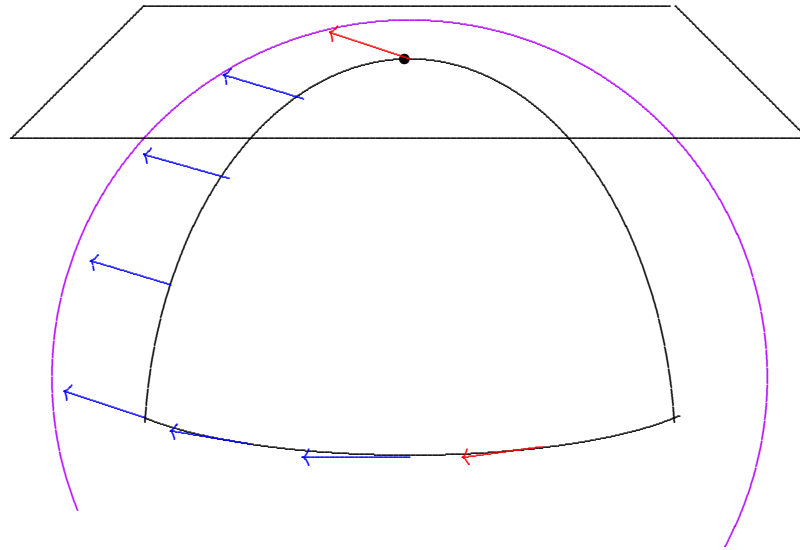
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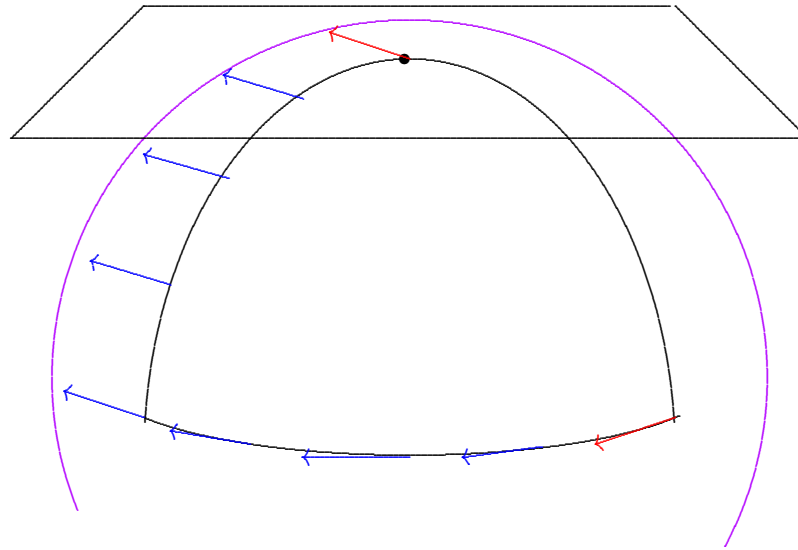
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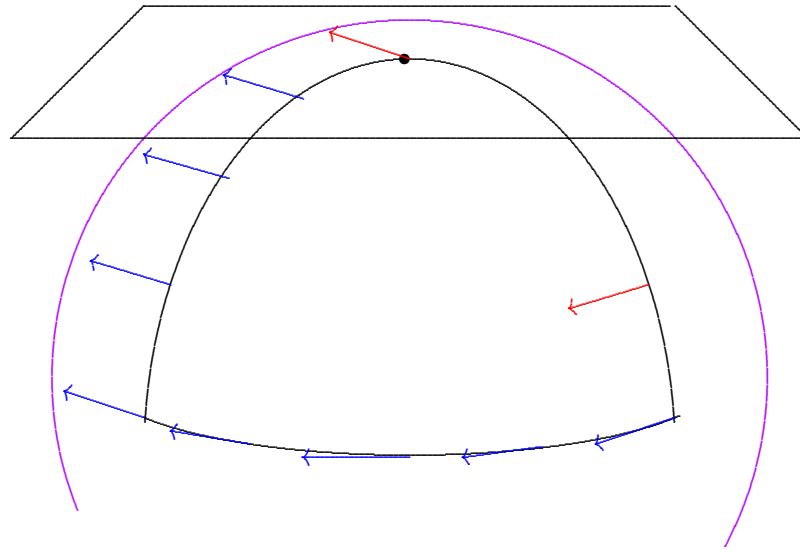
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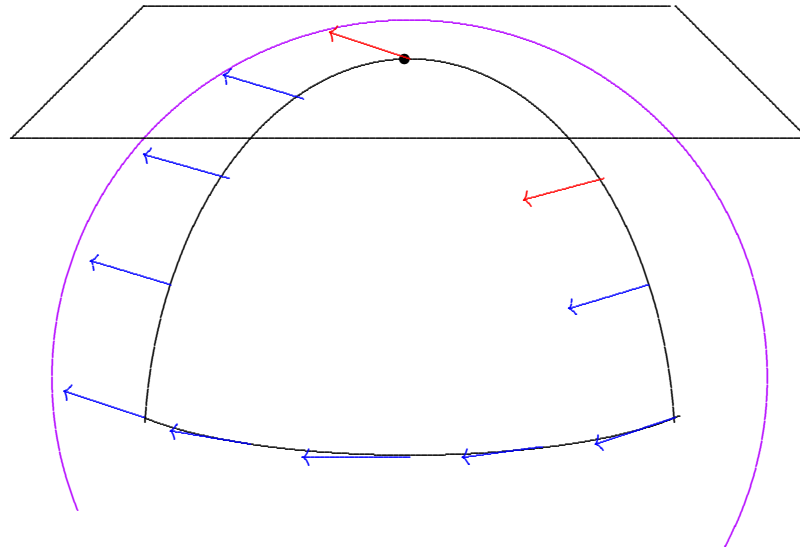
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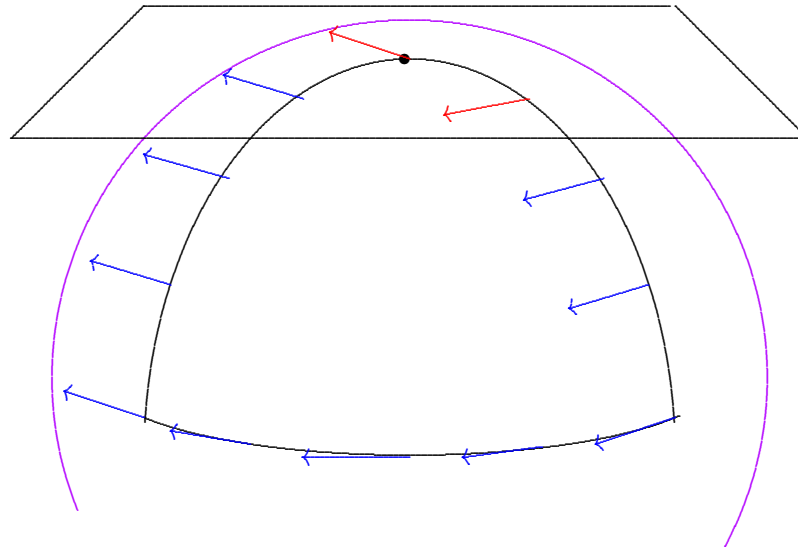
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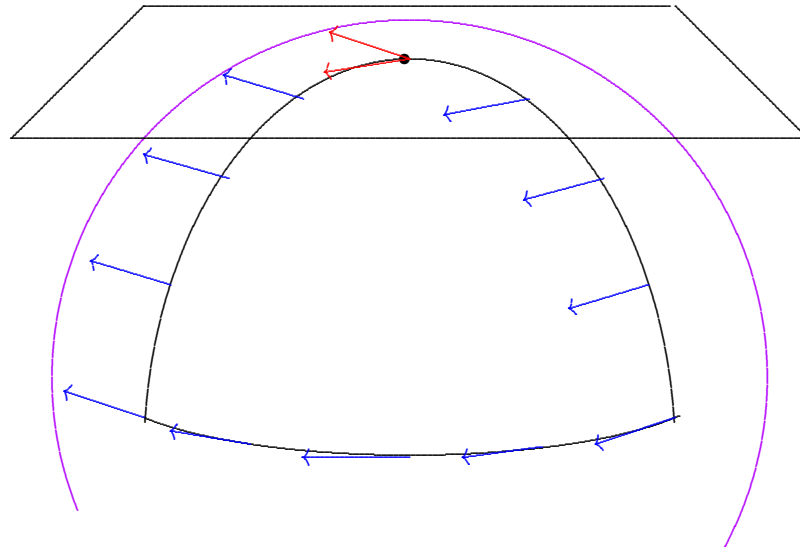
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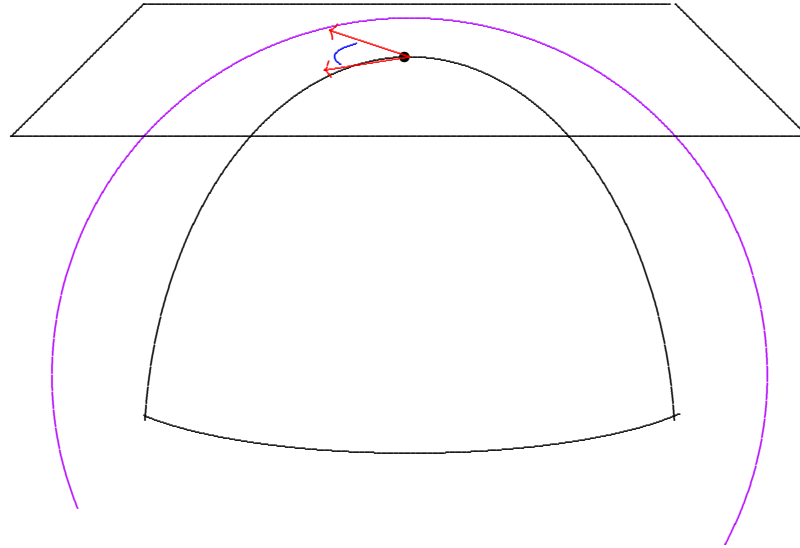
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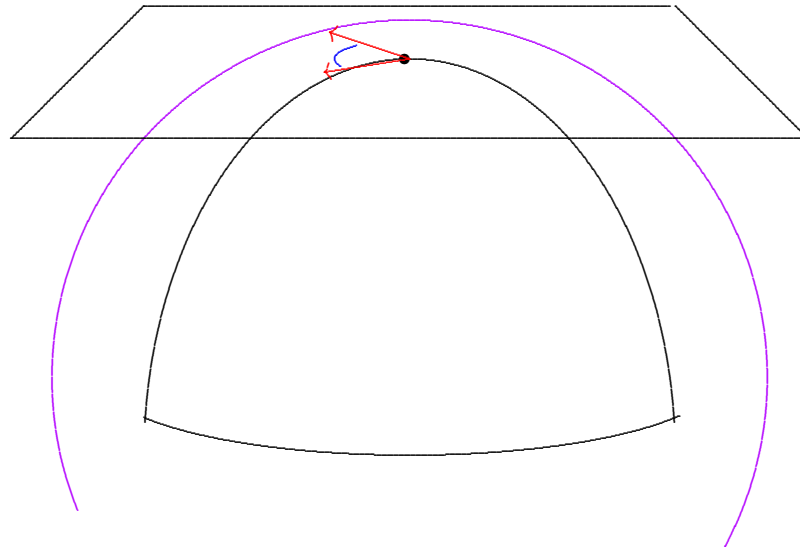
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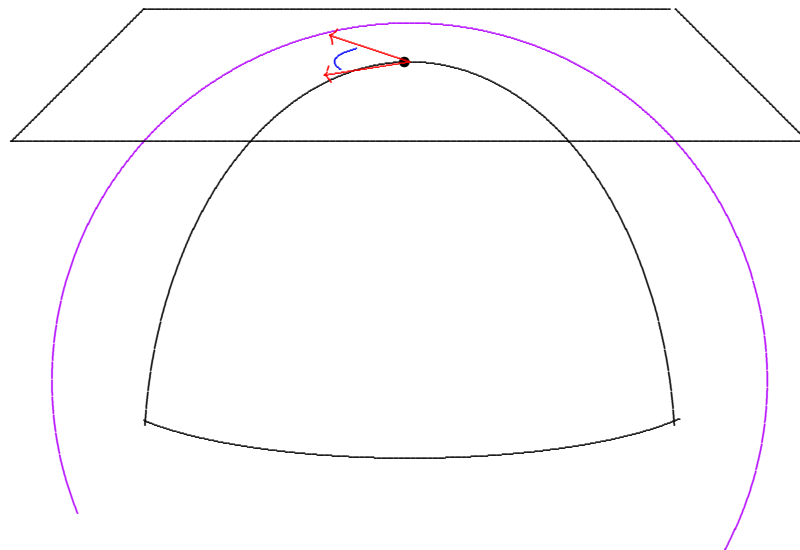
holonomy $\subset \mathbf{O}(n)$



Kähler metrics:

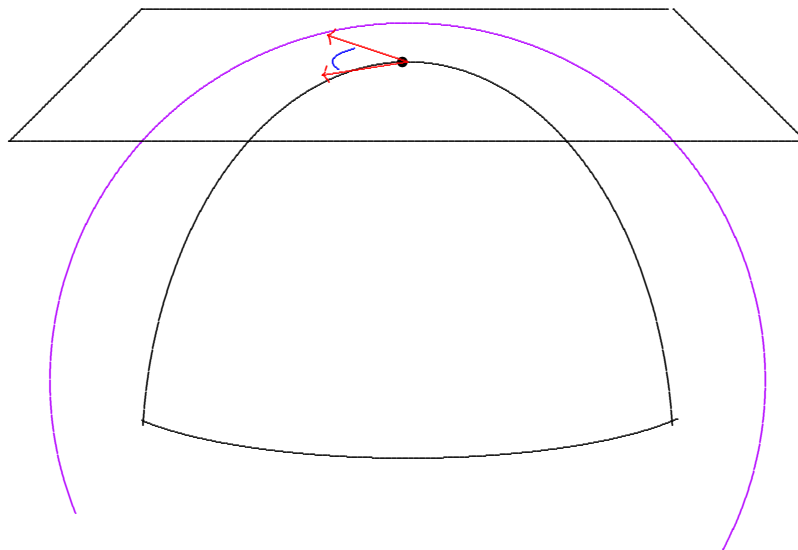
(M^{2m}, g) :

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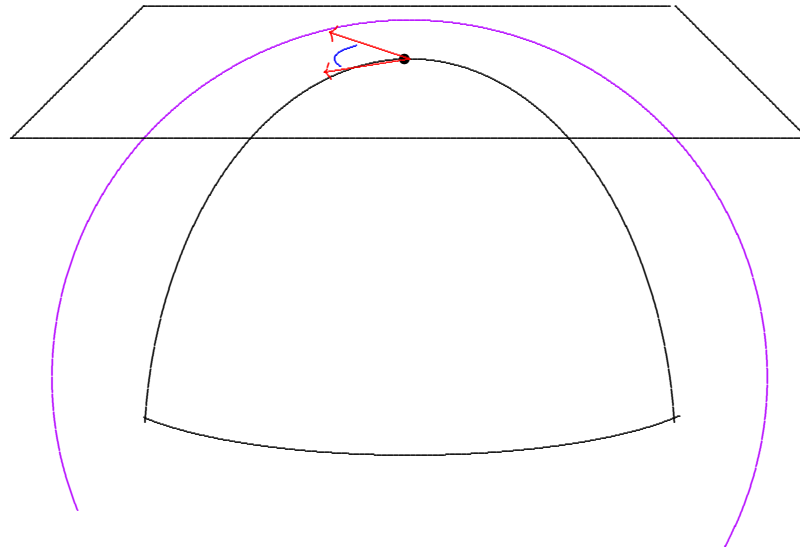
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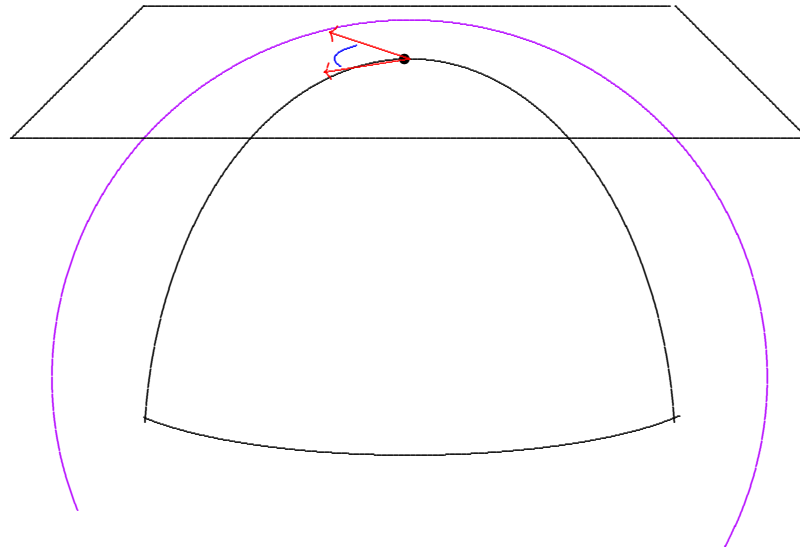
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$$\mathbf{U}(m) := \mathbf{O}(2m) \cap \mathbf{GL}(m, \mathbb{C})$$

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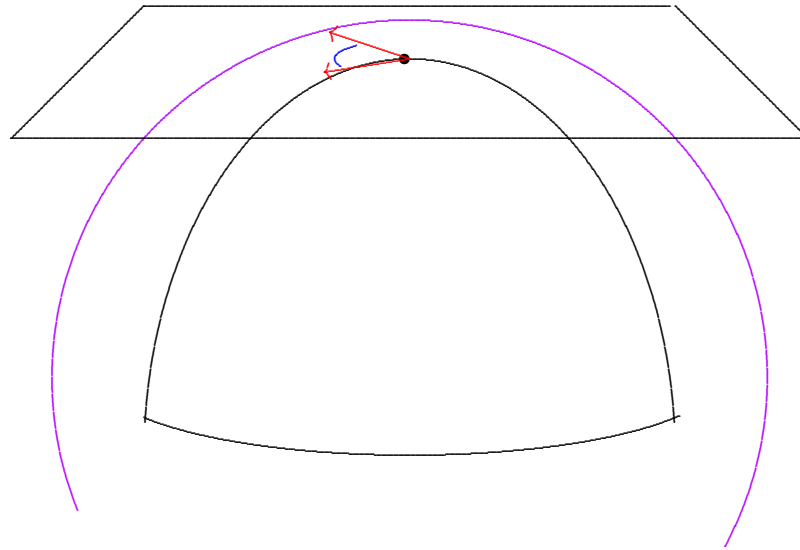
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Makes tangent space a complex vector space!

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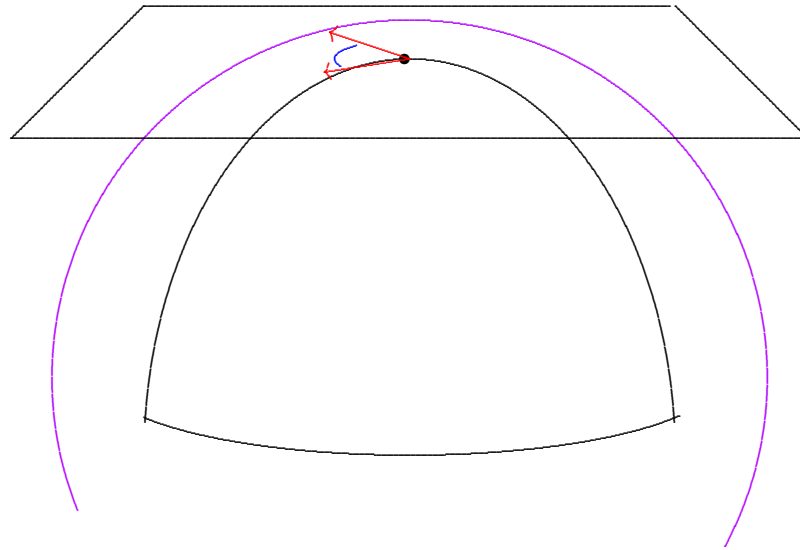
Makes tangent space a complex vector space!

$$J : TM \rightarrow TM, \quad J^2 = -\text{identity}$$

“almost-complex structure”

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Makes tangent space a complex vector space!

Invariant under parallel transport!

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Kähler magic:

$$r = - \sum_{j,k=1}^m \frac{\partial^2}{\partial z^j \partial \bar{z}^k} \log \det[g_{p\bar{q}}] \left[dz^j \otimes d\bar{z}^k + d\bar{z}^k \otimes dz^j \right]$$

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Kähler magic:

If we define the Ricci form by

$$\rho = r(J\cdot, \cdot)$$

then $i\rho$ is curvature of canonical line bundle $\Lambda^{m,0}$.

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$$[\omega] \in H^2(M)$$

“Kähler class”

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ω non-degenerate closed 2-form: symplectic form

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Restrict Euclidean \times round metric to $\begin{vmatrix} z_1 & z_2 \\ \zeta_1 & \zeta_2 \end{vmatrix} = 0$.

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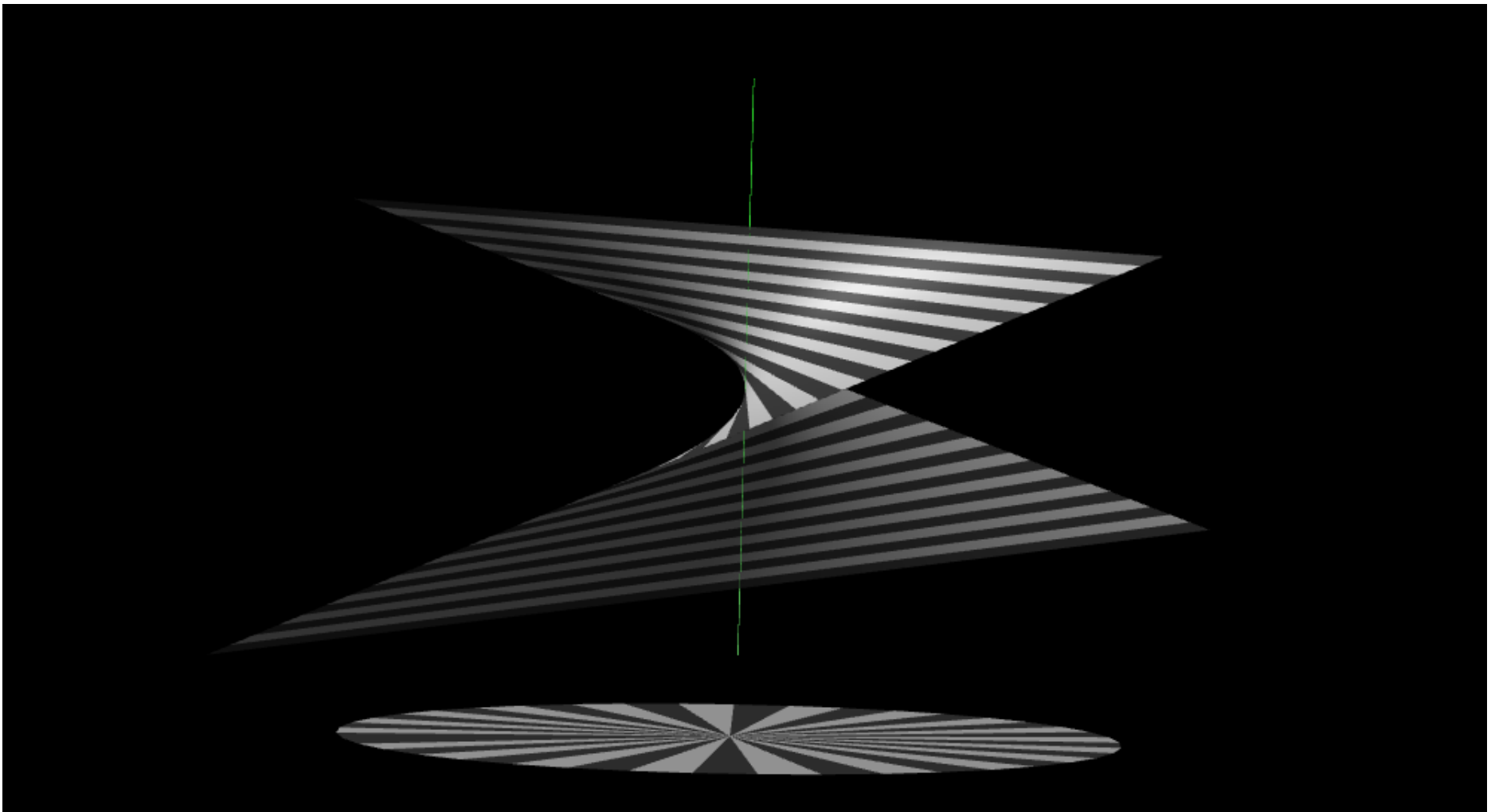
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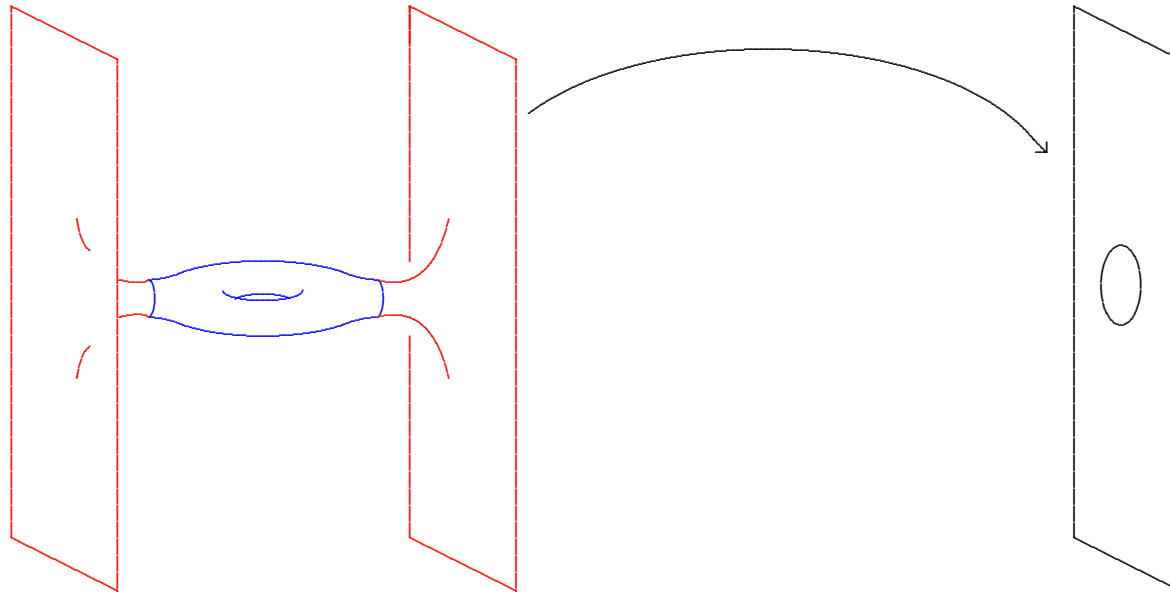
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also has mass m . Again measures “size of throat.”

Definition. A complete, non-compact Riemannian n -manifold (M^n, g) is called **asymptotically Euclidean (AE)** if there is a compact set $K \subset M$ such that each “end” is diffeomorphic to $\mathbb{R}^n - D^n$ in such a manner that

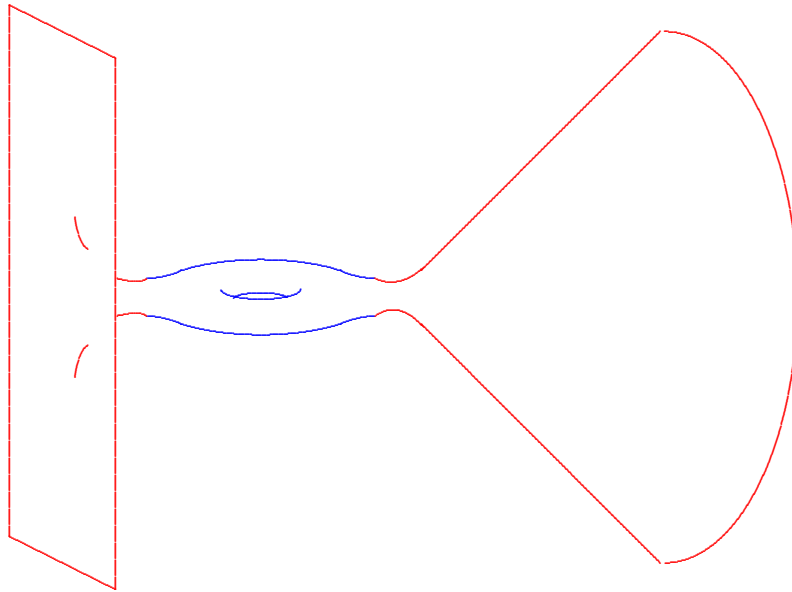


$$g_{jk} = \delta_{jk} + O(|x|^{1-\frac{n}{2}-\varepsilon})$$

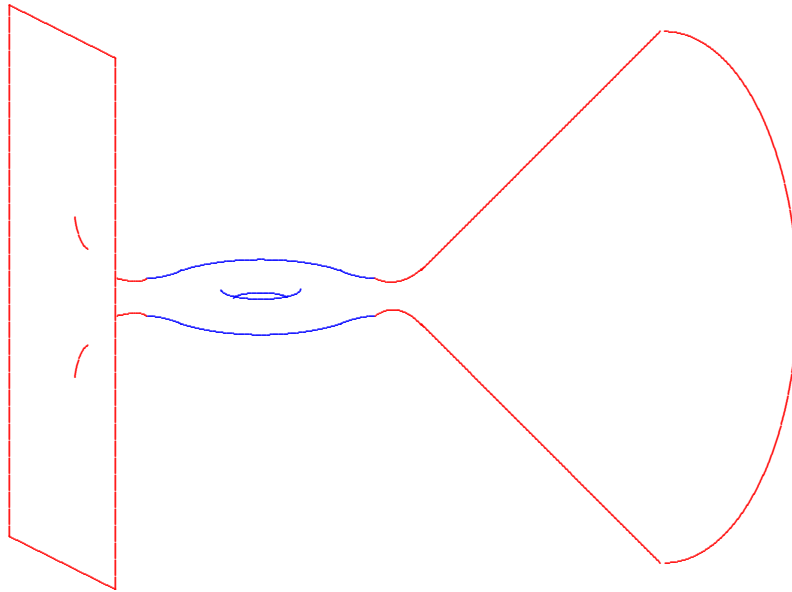
$$g_{jk,\ell} = O(|x|^{-\frac{n}{2}-\varepsilon}), \quad s \in L^1$$

Interesting generalization...

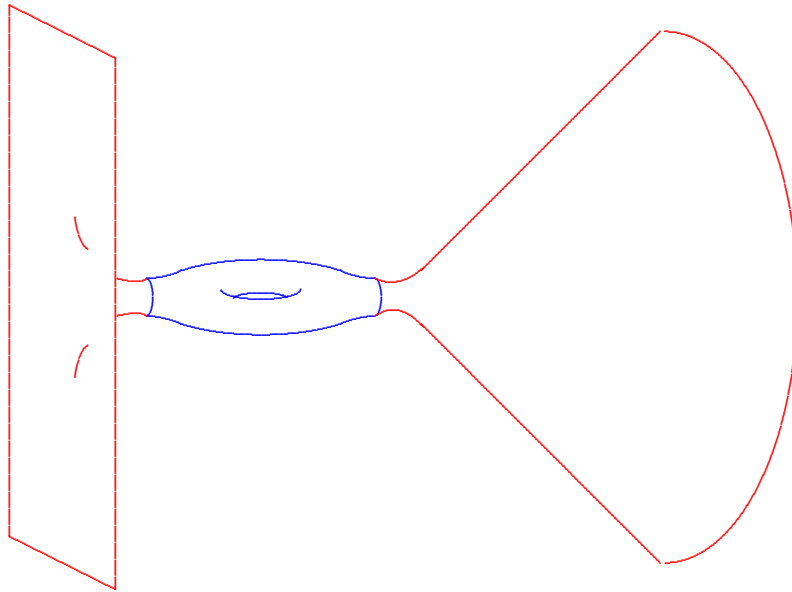
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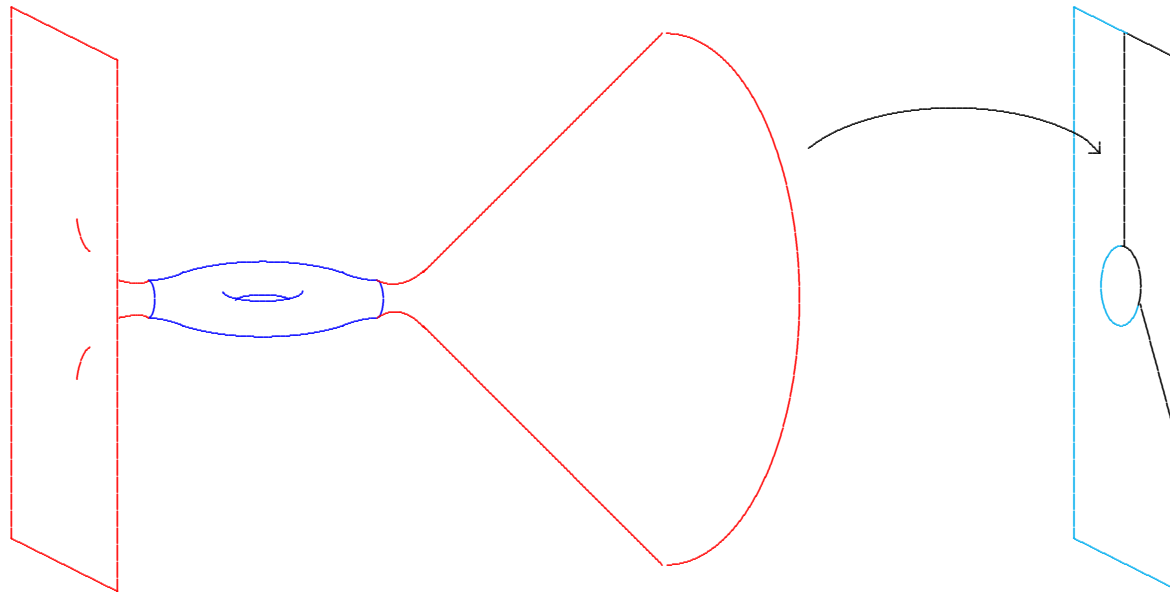
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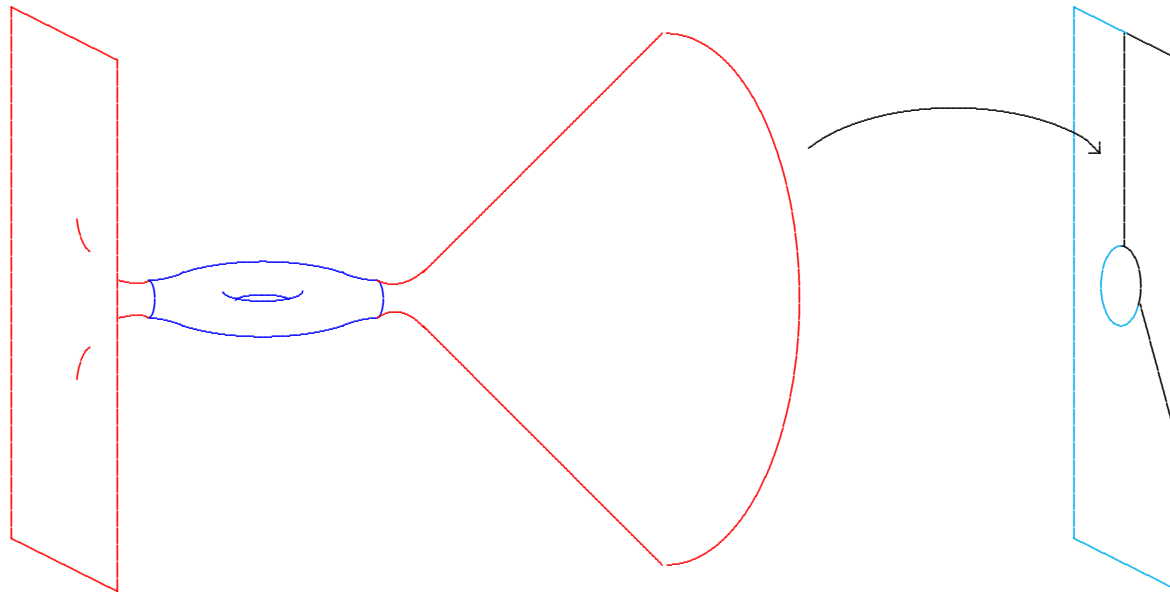
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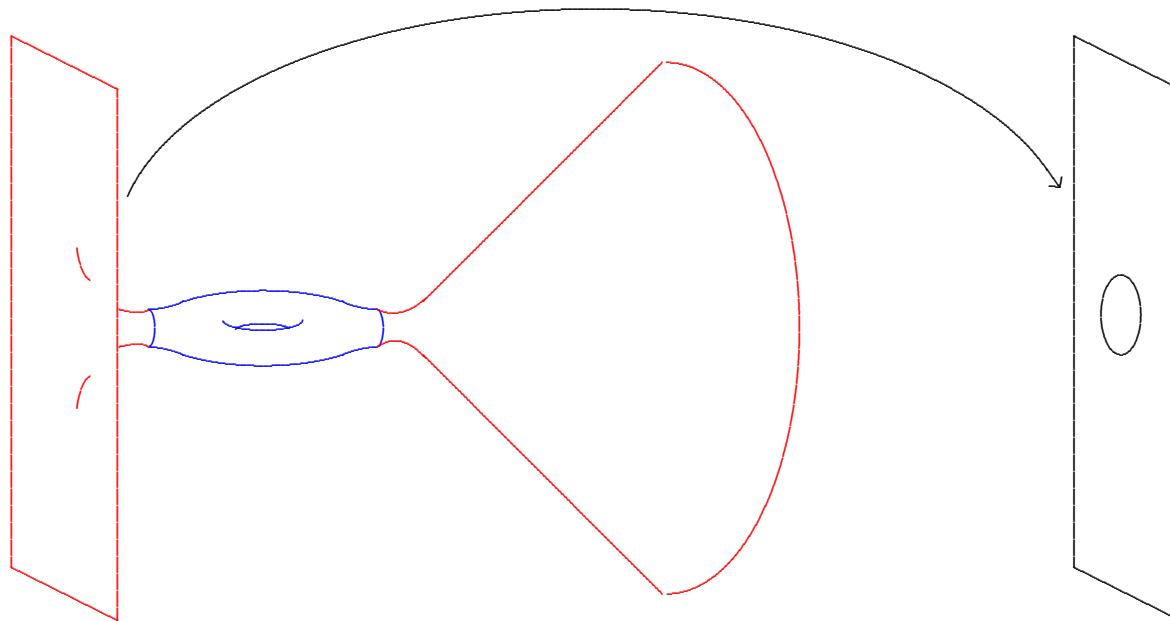
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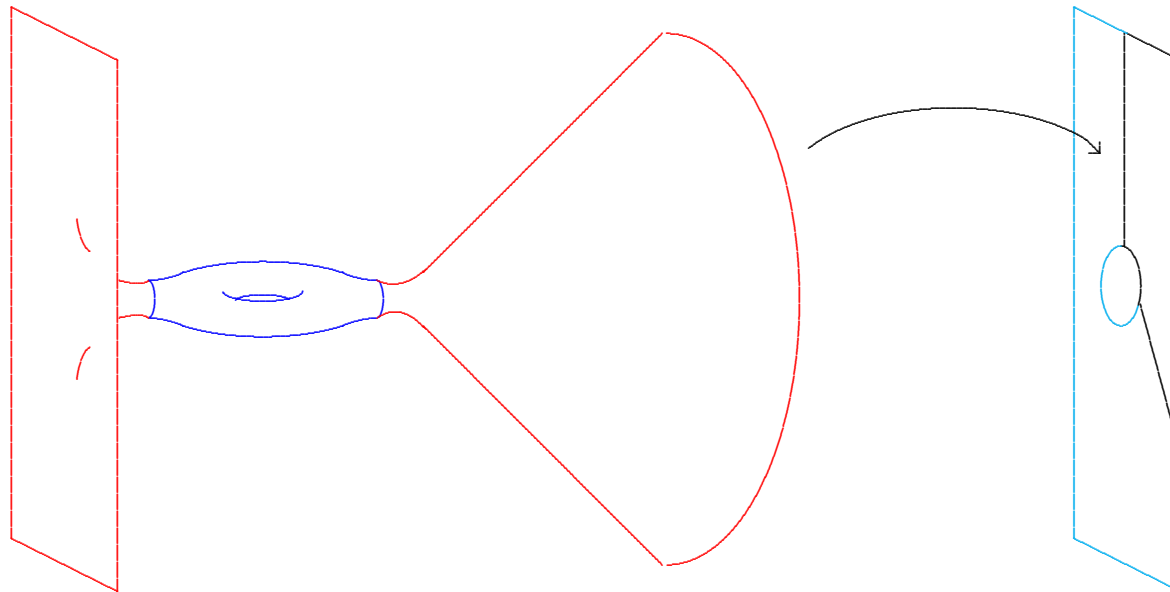
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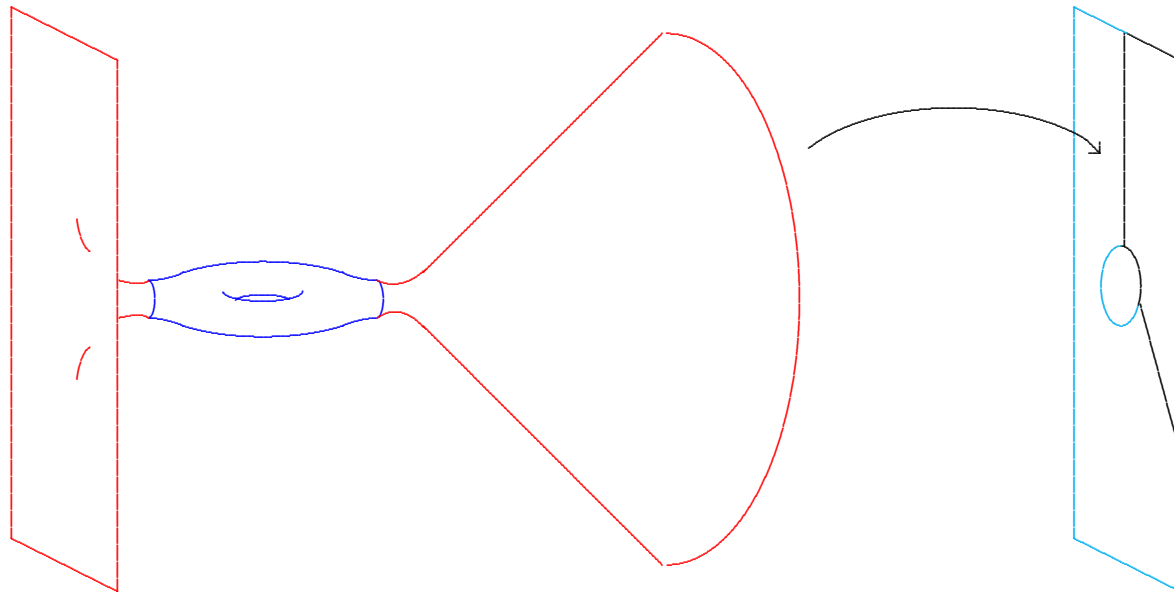
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$$g_{jk} = \delta_{jk} + O(|x|^{1-\frac{n}{2}-\varepsilon})$$

$$g_{jk,\ell} = O(|x|^{-\frac{n}{2}-\varepsilon}), \quad s \in L^1$$

Why consider *ALE* spaces?

Key examples:

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Gravitational Instantons:

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ALE Ricci-flat Kähler manifolds.

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Bubbling modes for sequences of Einstein metrics.

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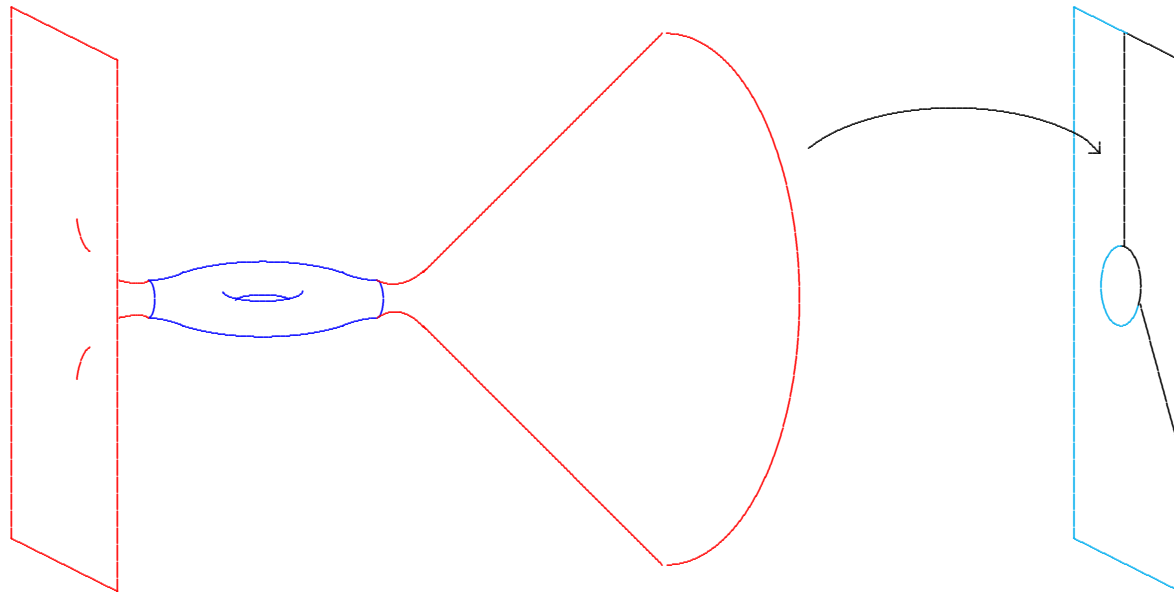
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Chen-L-Weber '08.

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Mass still meaningful in this context...

Definition. *The mass (at a given end) of an ALE n -manifold is defined to be*

$$m(M, g) := [g_{ij,i} - g_{ii,j}]$$

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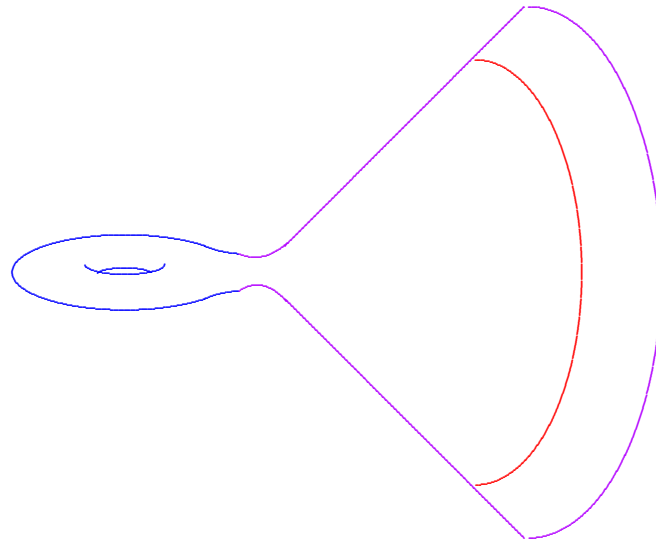
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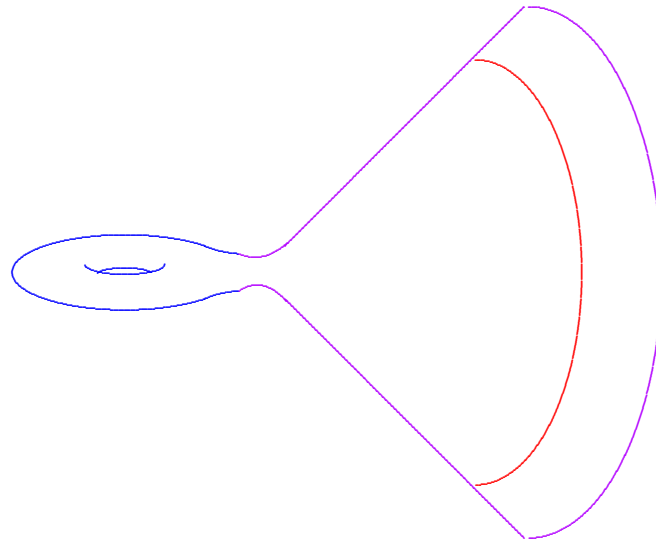


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Bartnik/Chruściel (1986): With weak fall-off conditions, the mass is well-defined & coordinate independent.

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General case in arbitrary dimension n .

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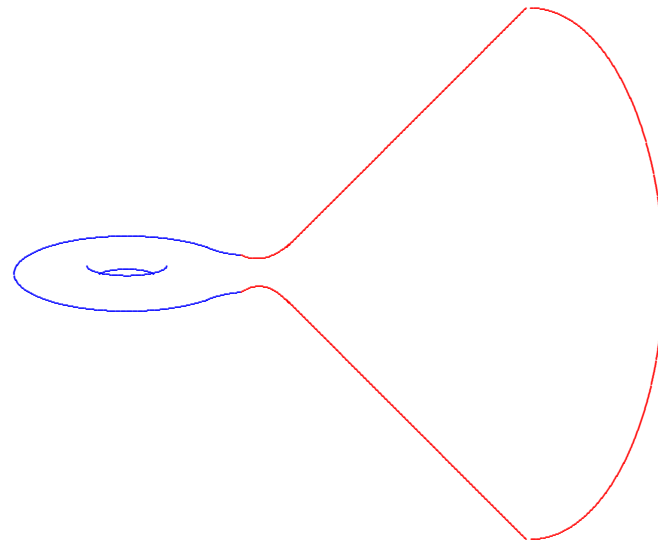
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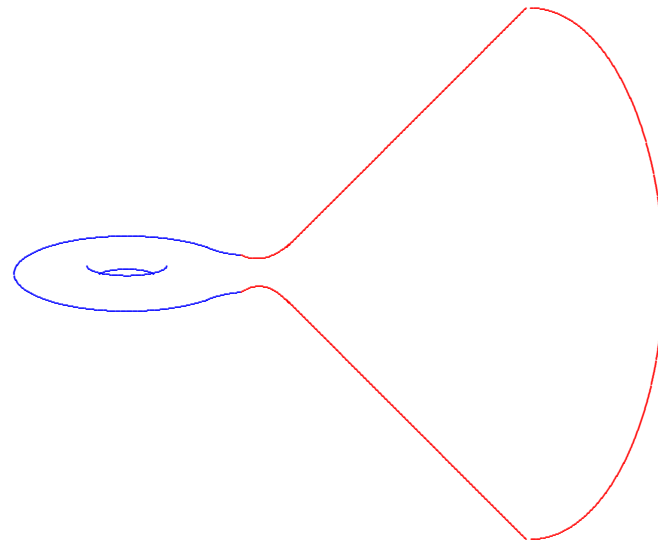
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Theorem A.

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In fact, we will see that there is an explicit formula for the mass in terms of these data!

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Non-minimal resolutions typically admit families of such metrics for which the mass can be continuously deformed from negative to positive.

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$$H_c^2(M) \rightarrow H_{dR}^2(M)$$

is an isomorphism.

Definition. *If (M, g, J) is any ALE Kähler manifold, we will use*

$$\clubsuit : H_{dR}^2(M) \rightarrow H_c^2(M)$$

to denote the inverse of the natural map

$$H_c^2(M) \rightarrow H_{dR}^2(M)$$

induced by the inclusion of compactly supported smooth forms into all forms.

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- $\langle \cdot, \cdot \rangle$ is pairing between $H_c^2(M)$ and $H^{2m-2}(M)$.

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$$\frac{4\pi^m(2m-1)}{(m-1)!} \mathfrak{m}(M, g) = -\frac{4\pi}{(m-1)!} \langle \clubsuit(c_1), [\omega]^{m-1} \rangle + \int_M s_g d\mu_g$$

For a compact Kähler manifold (M^{2m}, g, J) ,

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So the mass is a “boundary correction” to the topological formula for the total scalar curvature.

Theorem C. Any *ALE Kähler manifold* (M, g, J) of complex dimension m has mass given by

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So **Theorem A** is an immediate consequence!

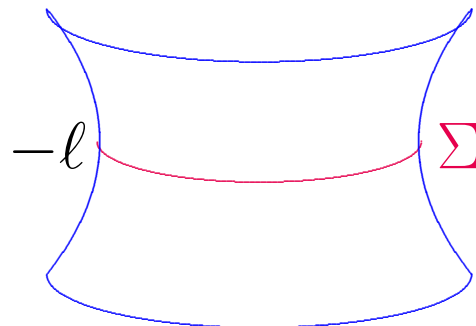
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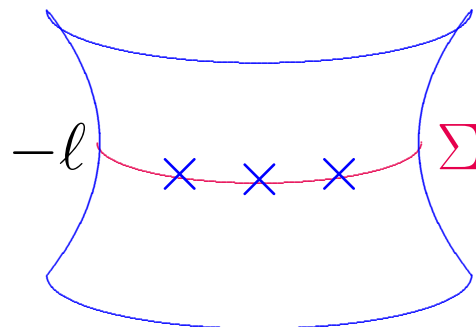
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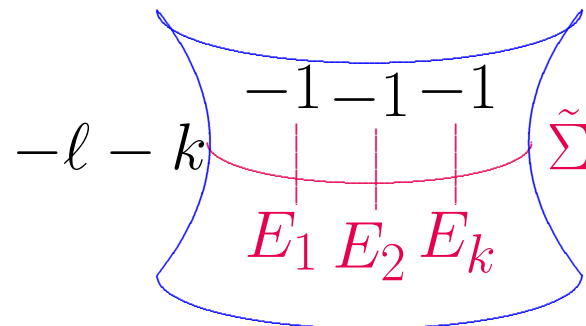
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Proof actually shows something stronger!

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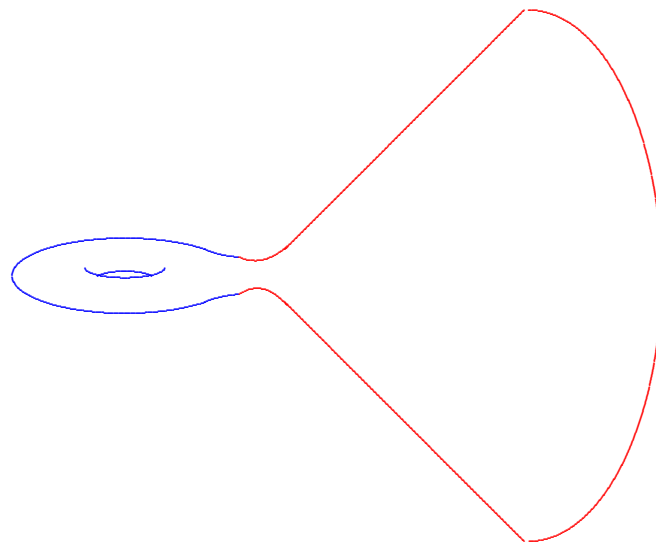
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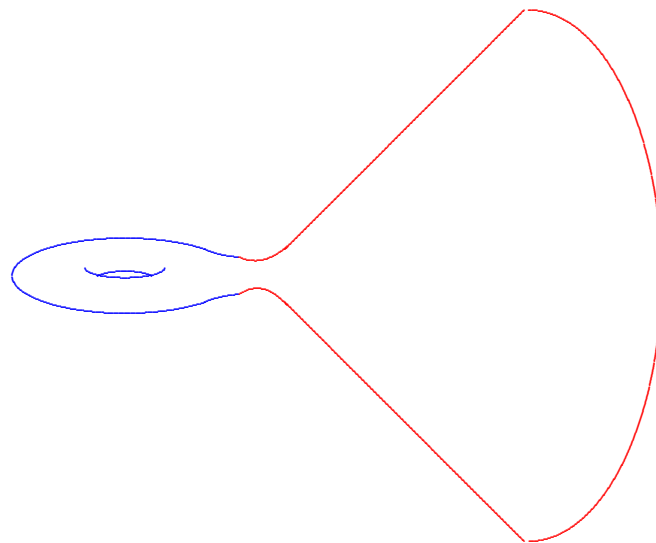
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